

CM4650 Polymer Rheology*Just-in-time*

 **Michigan Tech**


What exactly do we observe when we subject non-Newtonian fluids to deformation?



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Part II-A. Continuum versus molecular modeling

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What exactly do we observe when we subject non-Newtonian fluids to deformation?

Rheology uses a sort of an ASTM or ISO-like technical standards approach to organize observations:

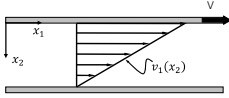
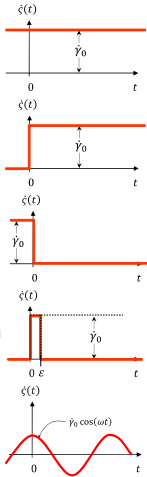
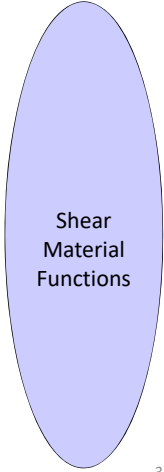
1. Choose a standard flow (shear or elongation)
2. Choose a set of flow kinematics (the speed and time-profile of the specific test)
3. Measure specified quantities (related to stress or deformation)
4. Report a standardized function (material function)

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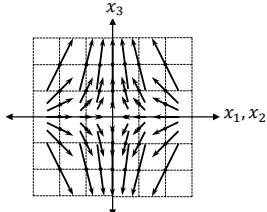
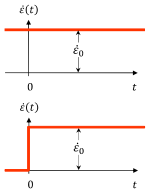
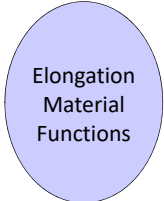
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Standard flow	$\zeta(t) =$	Standard kinematics	What do we observe?
<div style="background-color: yellow; padding: 5px; margin-bottom: 10px;">Shear</div> $\underline{v} \equiv \begin{pmatrix} \dot{\zeta}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$ 	<p>a) Steady</p> <p>b) Start-up</p> <p>c) Cessation</p> <p>d) Step-strain</p> <p>e) SAOS*</p>		
2/3/2020	(*SAOS=small-amplitude oscillatory shear)	© Faith A. Morrison, Michigan Tech U.	3


What exactly do we observe when we subject non-Newtonian fluids to deformation?



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Standard flow	$\dot{\epsilon}(t) =$	Standard kinematics	What do we observe?
<div style="background-color: yellow; padding: 5px; margin-bottom: 10px;">Elongation</div> $\underline{v} \equiv \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{123}$ 	<p>a) Steady</p> <p>b) Start-up</p> <p>(etc.)</p>		
2/3/2020	Note: the Society of Rheology convention has flow in the 1-direction rather than the 3-direction.	© Faith A. Morrison, Michigan Tech U.	4

What exactly do we observe when we subject non-Newtonian fluids to deformation?



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Material Functions

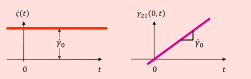
Summarized on "recipe cards" →

Steady Shear Flow Material Functions Michigan Tech

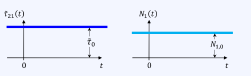
Imposed Kinematics:

$$\Sigma \equiv \begin{pmatrix} \dot{\gamma}(t)x_2 \\ 0 \\ 0 \end{pmatrix} /_{123}$$

$\dot{\gamma}(t) = \dot{\gamma}_0 = \text{constant}$



Material Stress Response:



Material Functions:

Viscosity $\eta(\dot{\gamma}_0) \equiv \frac{\tau_{21}}{\dot{\gamma}_0} = \frac{-\tau_{21}}{\dot{\gamma}_0}$

First normal stress coefficient $\Psi_1(\dot{\gamma}_0) \equiv \frac{\tau_{11} - \tau_{22}}{\dot{\gamma}_0^2} = \frac{-(\tau_{11} - \tau_{22})}{\dot{\gamma}_0^2}$

Second normal stress coefficient $\Psi_2(\dot{\gamma}_0) \equiv \frac{\tau_{22} - \tau_{33}}{\dot{\gamma}_0^2} = \frac{-(\tau_{22} - \tau_{33})}{\dot{\gamma}_0^2}$

- Vocabulary (framework) of material comparison
- Used to characterize a material as Newtonian vs. non-Newtonian

Newtonian

$\eta = \mu = \text{constant}$

$\Psi_1 = \Psi_2 = 0$

$G' = 0$

etc.

Non-Newtonian

$\eta = \eta(\dot{\gamma})$

$\Psi_1 \neq 0; \Psi_2 \neq 0$


$G', G'' \neq 0$

etc.

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What exactly do we observe when we subject non-Newtonian fluids to deformation?



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Material Functions

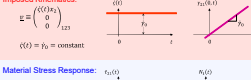
Summarized on "recipe cards" →

Steady Shear Flow Material Functions Michigan Tech

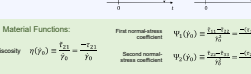
Imposed Kinematics:

$$\Sigma \equiv \begin{pmatrix} \dot{\gamma}(t)x_2 \\ 0 \\ 0 \end{pmatrix} /_{123}$$

$\dot{\gamma}(t) = \dot{\gamma}_0 = \text{constant}$



Material Stress Response:



Material Functions:

Viscosity $\eta(\dot{\gamma}_0) \equiv \frac{\tau_{21}}{\dot{\gamma}_0} = \frac{-\tau_{21}}{\dot{\gamma}_0}$

First normal stress coefficient $\Psi_1(\dot{\gamma}_0) \equiv \frac{\tau_{11} - \tau_{22}}{\dot{\gamma}_0^2} = \frac{-(\tau_{11} - \tau_{22})}{\dot{\gamma}_0^2}$

Second normal stress coefficient $\Psi_2(\dot{\gamma}_0) \equiv \frac{\tau_{22} - \tau_{33}}{\dot{\gamma}_0^2} = \frac{-(\tau_{22} - \tau_{33})}{\dot{\gamma}_0^2}$

- Vocabulary (framework) of material comparison
- Used to characterize a material as Newtonian vs. non-Newtonian
- Within non-Newtonian fluids, used to further categorize materials

Newtonian

$\eta = \mu = \text{constant}$

$\Psi_1 = \Psi_2 = 0$

$G' = 0$

etc.

Non-Newtonian

$\eta = \eta(\dot{\gamma})$

$\Psi_1 \neq 0; \Psi_2 \neq 0$

$G', G'' \neq 0$

etc.

Cross-linked rubber: $G' = G_0 = \text{constant}$

Entangled melt: characteristic $G'(\omega), G''(\omega)$ shapes


Shear thinning, shear thickening melt: characteristic $\eta(\dot{\gamma})$

Branched polymer: characteristic $G'(\omega), G''(\omega)$ shapes

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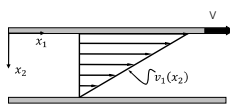
Part II-A. Continuum versus molecular modeling



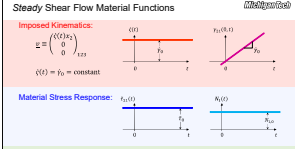
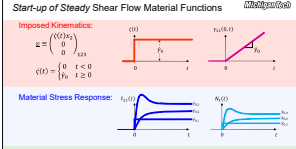
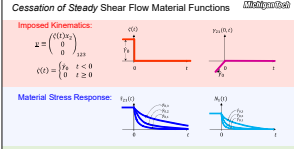
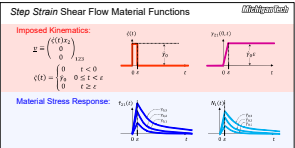
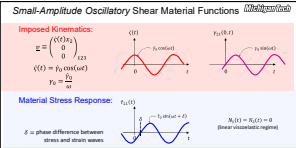
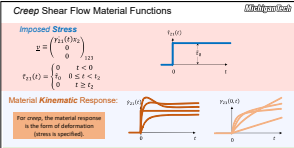
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Shear Material Functions

$$\underline{v} \equiv \begin{pmatrix} \dot{\gamma}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$$




"Recipe cards"

<p>a) Steady</p> <p>Steady Shear Flow Material Functions</p> <p>Imposed Kinematics:</p> $\underline{\Sigma} = \begin{pmatrix} \dot{\gamma}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$ $\dot{\gamma}(t) = \dot{\gamma}_0 = \text{constant}$ <p>Material Stress Response:</p>  <p>Material Functions:</p> <p>Viscosity $\eta(\dot{\gamma}_0) = \frac{\tau_{12}}{\dot{\gamma}_0} = \frac{\tau_{21}}{\dot{\gamma}_0}$</p> <p>First normal stress coefficient $\Psi_1^*(\dot{\gamma}_0) = \frac{\tau_{11} - \tau_{22}}{\dot{\gamma}_0} = \frac{\tau_{11} - \tau_{22}}{\dot{\gamma}_0}$</p> <p>Second normal stress coefficient $\Psi_2^*(\dot{\gamma}_0) = \frac{\tau_{33} - \tau_{11}}{\dot{\gamma}_0} = \frac{\tau_{33} - \tau_{11}}{\dot{\gamma}_0}$</p>	<p>b) Start-up</p> <p>Start-up of Steady Shear Flow Material Functions</p> <p>Imposed Kinematics:</p> $\underline{\Sigma} = \begin{pmatrix} \dot{\gamma}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$ $\dot{\gamma}(t) = \begin{cases} 0 & t < 0 \\ \dot{\gamma}_0 & t \geq 0 \end{cases}$ <p>Material Stress Response:</p>  <p>Material Functions:</p> <p>Shear stress growth function $\Psi_1^*(t, \dot{\gamma}_0) = \frac{\tau_{12}(t)}{\dot{\gamma}_0}$</p> <p>First normal stress growth coefficient $\Psi_1^*(t, \dot{\gamma}_0) = \frac{\tau_{11}(t) - \tau_{22}(t)}{\dot{\gamma}_0}$</p> <p>Second normal stress growth coefficient $\Psi_2^*(t, \dot{\gamma}_0) = \frac{\tau_{33}(t) - \tau_{11}(t)}{\dot{\gamma}_0}$</p>	<p>c) Cessation</p> <p>Cessation of Steady Shear Flow Material Functions</p> <p>Imposed Kinematics:</p> $\underline{\Sigma} = \begin{pmatrix} \dot{\gamma}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$ $\dot{\gamma}(t) = \begin{cases} \dot{\gamma}_0 & t < 0 \\ 0 & t \geq 0 \end{cases}$ <p>Material Stress Response:</p>  <p>Material Functions:</p> <p>Shear stress decay function $\Psi_1^*(t, \dot{\gamma}_0) = \frac{\tau_{12}(t)}{\dot{\gamma}_0}$</p> <p>First normal stress decay coefficient $\Psi_1^*(t, \dot{\gamma}_0) = \frac{\tau_{11}(t) - \tau_{22}(t)}{\dot{\gamma}_0}$</p> <p>Second normal stress decay coefficient $\Psi_2^*(t, \dot{\gamma}_0) = \frac{\tau_{33}(t) - \tau_{11}(t)}{\dot{\gamma}_0}$</p>
<p>d) Step strain</p> <p>Step Strain Shear Flow Material Functions</p> <p>Imposed Kinematics:</p> $\underline{\Sigma} = \begin{pmatrix} \dot{\gamma}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$ $\dot{\gamma}(t) = \begin{cases} 0 & t < 0 \\ \dot{\gamma}_0 & 0 \leq t < t_0 \\ 0 & t \geq t_0 \end{cases}$ <p>Material Stress Response:</p>  <p>Material Functions:</p> <p>Relaxation modulus $G^*(t, \dot{\gamma}_0) = \frac{\tau_{12}(t, \dot{\gamma}_0)}{\dot{\gamma}_0}$</p> <p>First normal stress relaxation modulus $G_1^*(t, \dot{\gamma}_0) = \frac{\tau_{11}(t) - \tau_{22}(t)}{\dot{\gamma}_0}$</p> <p>Second normal stress relaxation modulus $G_2^*(t, \dot{\gamma}_0) = \frac{\tau_{33}(t) - \tau_{11}(t)}{\dot{\gamma}_0}$</p>	<p>e) SAOS</p> <p>Small-Amplitude Oscillatory Shear Material Functions</p> <p>Imposed Kinematics:</p> $\underline{\Sigma} = \begin{pmatrix} \dot{\gamma}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$ $\dot{\gamma}(t) = \dot{\gamma}_0 \cos(\omega t)$ <p>Material Stress Response:</p>  <p>$\delta = \text{phase difference between stress and strain waves}$</p> <p>Material Functions:</p> <p>SAOS stress $\frac{\tau_{12}(t, \dot{\gamma}_0)}{\dot{\gamma}_0} = \tau_0 \sin(\omega t + \delta) = G' \sin(\omega t) + G'' \cos(\omega t)$</p> <p>Storage modulus $G'(\omega) = \frac{\tau_0}{\dot{\gamma}_0} \cos(\delta)$</p> <p>Loss modulus $G''(\omega) = \frac{\tau_0}{\dot{\gamma}_0} \sin(\delta)$</p>	<p>f) Creep</p> <p>Creep Shear Flow Material Functions</p> <p>Imposed Stress:</p> $\underline{\Sigma} = \begin{pmatrix} \tau_{12}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$ $\tau_{12}(t) = \begin{cases} 0 & t < 0 \\ \tau_0 & 0 \leq t < t_0 \\ 0 & t \geq t_0 \end{cases}$ <p>Material Kinematic Response:</p> <p>For creep, the material response is the form of deformation stress is specified.</p>  <p>Material Function:</p> <p>Shear creep compliance $J(t, \tau_0) = \frac{\gamma(t, \tau_0)}{\tau_0}$</p>

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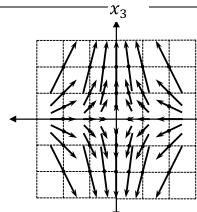
Part II-A. Continuum versus molecular modeling



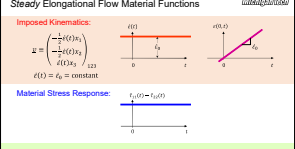
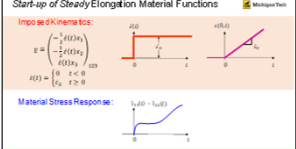
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Elongation Material Functions

$$\underline{v} \equiv \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{123}$$



"Recipe cards"

<p>a) Steady</p> <p>Steady Elongational Flow Material Functions</p> <p>Imposed Kinematics:</p> $\underline{\Sigma} = \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{123}$ $\dot{\epsilon}(t) = \dot{\epsilon}_0 = \text{constant}$ <p>Material Stress Response:</p>  <p>Material Functions:</p> <p>Elongational Viscosity $\eta_e(\dot{\epsilon}_0) = \frac{\tau_{11} - \tau_{22}}{\dot{\epsilon}_0} = \frac{\tau_{33} - \tau_{11}}{\dot{\epsilon}_0}$</p> <p>Alternatively, $\eta(\dot{\epsilon}_0)$</p>	<p>b) Start-up</p> <p>Start-up of Steady Elongation Material Functions</p> <p>Imposed Kinematics:</p> $\underline{\Sigma} = \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{123}$ $\dot{\epsilon}(t) = \begin{cases} 0 & t < 0 \\ \dot{\epsilon}_0 & t \geq 0 \end{cases}$ <p>Material Stress Response:</p>  <p>Material Functions:</p> <p>Elongational Stress-growth Function $\Psi_1^*(t, \dot{\epsilon}_0) = \frac{\tau_{11}(t) - \tau_{22}(t)}{\dot{\epsilon}_0}$</p> <p>Alternatively, $\Psi^*(t, \dot{\epsilon}_0)$</p>	<p>c) Cessation</p> <p style="text-align: center; padding: 20px;">(currently unobservable)</p>
<p>d) Step strain</p> <p style="text-align: center; padding: 20px;">(exists, but less often discussed)</p>	<p>e) SAOE</p> <p style="text-align: center; padding: 20px;">(exists, but easily converted to SAOS so is redundant)</p>	<p>f) Creep</p> <p style="text-align: center; padding: 20px;">(exists)</p>

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Steady Shear Flow Material Functions Michigan Tech

Imposed Kinematics:

$$\underline{v} \equiv \begin{pmatrix} \dot{\zeta}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$$

$$\dot{\zeta}(t) = \dot{\gamma}_0 = \text{constant}$$

Material Stress Response:

Material Functions:

First normal-stress coefficient $\Psi_1(\dot{\gamma}_0) \equiv \frac{\tilde{\tau}_{11} - \tilde{\tau}_{22}}{\dot{\gamma}_0^2} = \frac{-(\tau_{11} - \tau_{22})}{\dot{\gamma}_0^2}$

Second normal-stress coefficient $\Psi_2(\dot{\gamma}_0) \equiv \frac{\tilde{\tau}_{22} - \tilde{\tau}_{33}}{\dot{\gamma}_0^2} = \frac{-(\tau_{22} - \tau_{33})}{\dot{\gamma}_0^2}$

Viscosity $\eta(\dot{\gamma}_0) \equiv \frac{\tilde{\tau}_{21}}{\dot{\gamma}_0} = \frac{-\tau_{21}}{\dot{\gamma}_0}$

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Start-up of Steady Shear Flow Material Functions Michigan Tech

Imposed Kinematics:

$$\underline{v} \equiv \begin{pmatrix} \dot{\zeta}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$$

$$\dot{\zeta}(t) = \begin{cases} 0 & t < 0 \\ \dot{\gamma}_0 & t \geq 0 \end{cases}$$

Material Stress Response:

Material Functions:

Shear stress growth function $\eta^+(t, \dot{\gamma}_0) \equiv \frac{\tilde{\tau}_{21}(t)}{\dot{\gamma}_0} = \frac{-\tau_{21}(t)}{\dot{\gamma}_0}$

First normal-stress growth coefficient $\Psi_1^+(t, \dot{\gamma}_0) \equiv \frac{\tilde{\tau}_{11} - \tilde{\tau}_{22}}{\dot{\gamma}_0^2}$

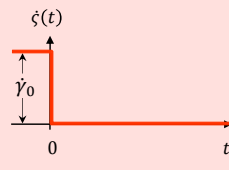
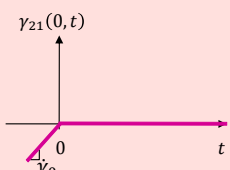
Second normal-stress growth coefficient $\Psi_2^+(t, \dot{\gamma}_0) \equiv \frac{\tilde{\tau}_{22} - \tilde{\tau}_{33}}{\dot{\gamma}_0^2}$

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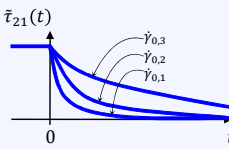
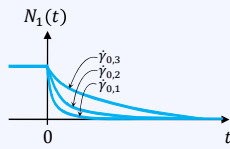
Cessation of Steady Shear Flow Material Functions Michigan Tech

Imposed Kinematics:

$$\underline{v} \equiv \begin{pmatrix} \dot{\zeta}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$$

$$\dot{\zeta}(t) = \begin{cases} \dot{\gamma}_0 & t < 0 \\ 0 & t \geq 0 \end{cases}$$



Material Stress Response:

Material Functions:

Shear stress decay function $\eta^-(t, \dot{\gamma}_0) \equiv \frac{\bar{\tau}_{21}(t)}{\dot{\gamma}_0} = \frac{-\tau_{21}(t)}{\dot{\gamma}_0}$

First normal-stress decay coefficient $\Psi_1^-(t, \dot{\gamma}_0) \equiv \frac{\bar{\tau}_{11} - \bar{\tau}_{22}}{\dot{\gamma}_0^2}$

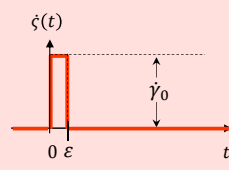
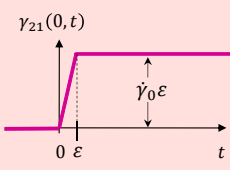
Second normal-stress decay coefficient $\Psi_2^-(t, \dot{\gamma}_0) \equiv \frac{\bar{\tau}_{22} - \bar{\tau}_{33}}{\dot{\gamma}_0^2}$

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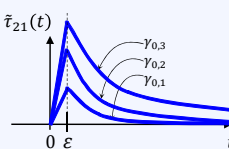
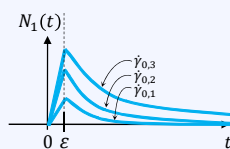
Step Strain Shear Flow Material Functions Michigan Tech

Imposed Kinematics:

$$\underline{v} \equiv \begin{pmatrix} \dot{\zeta}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$$

$$\dot{\zeta}(t) = \lim_{\varepsilon \rightarrow 0} \begin{cases} 0 & t < 0 \\ \dot{\gamma}_0 & 0 \leq t < \varepsilon \\ 0 & t \geq \varepsilon \end{cases}$$



Material Stress Response:

Material Functions:

Relaxation modulus $G(t, \gamma_0) \equiv \frac{\bar{\tau}_{21}(t, \gamma_0)}{\gamma_0} = \frac{-\tau_{21}(t, \gamma_0)}{\gamma_0}$

First normal-stress relaxation modulus $G_{\Psi_1}(t, \gamma_0) \equiv \frac{\bar{\tau}_{11} - \bar{\tau}_{22}}{\gamma_0^2}$

Second normal-stress relaxation modulus $G_{\Psi_2}(t, \gamma_0) \equiv \frac{\bar{\tau}_{22} - \bar{\tau}_{33}}{\gamma_0^2}$

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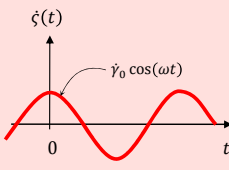
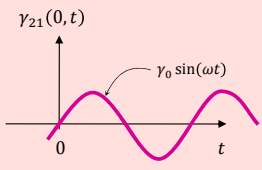
Small-Amplitude Oscillatory Shear Material Functions

Imposed Kinematics:

$$\underline{v} \equiv \begin{pmatrix} \dot{\zeta}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$$

$$\dot{\zeta}(t) = \dot{\gamma}_0 \cos(\omega t)$$

$$\gamma_0 = \frac{\dot{\gamma}_0}{\omega}$$

Material Stress Response:

$$\bar{\tau}_{21}(t) = \tilde{\tau}_0 \sin(\omega t + \delta)$$

δ = phase difference between stress and strain waves

$N_1(t) = N_2(t) = 0$
(linear viscoelastic regime)

Material Functions:

SAOS stress $\frac{\bar{\tau}_{21}(t, \gamma_0)}{\gamma_0} = \frac{-\tau_{21}(t, \gamma_0)}{\gamma_0} = \tilde{\tau}_0 \sin(\omega t + \delta) = G' \sin(\omega t) + G'' \cos(\omega t)$

Storage modulus $G'(\omega) \equiv \frac{\tilde{\tau}_0}{\gamma_0} \cos(\delta)$ Loss modulus $G''(\omega) \equiv \frac{\tilde{\tau}_0}{\gamma_0} \sin(\delta)$

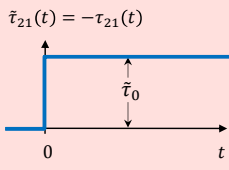
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Creep Shear Flow Material Functions

Imposed Stress

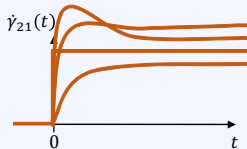
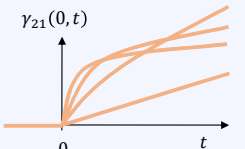
$$\underline{v} \equiv \begin{pmatrix} \dot{\gamma}_{21}(t)x_2 \\ 0 \\ 0 \end{pmatrix}_{123}$$

$$\bar{\tau}_{21}(t) = -\tau_{21}(t) = \begin{cases} 0 & t < 0 \\ \tilde{\tau}_0 & 0 \leq t < t_2 \\ 0 & t \geq t_2 \end{cases}$$



Material Kinematic Response:

For *creep*, the material response is the form of deformation (stress is specified).

Material Function:

Shear creep compliance $J(t, \tilde{\tau}_0) \equiv \frac{\gamma_{21}(0, t; \tilde{\tau}_0)}{\tilde{\tau}_0}$

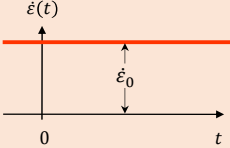
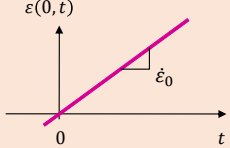
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Steady Elongational Flow Material Functions Michigan Tech

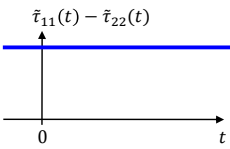
Imposed Kinematics:

$$\underline{v} \equiv \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{123}$$

$$\dot{\epsilon}(t) = \dot{\epsilon}_0 = \text{constant}$$

Material Stress Response:



Material Functions:

Elongational Viscosity $\eta_e(\dot{\epsilon}_0) \equiv \frac{\bar{\tau}_{33} - \bar{\tau}_{11}}{\dot{\epsilon}_0} = \frac{-(\tau_{33} - \tau_{11})}{\dot{\epsilon}_0}$

Alternatively, $\bar{\eta}(\dot{\epsilon}_0)$

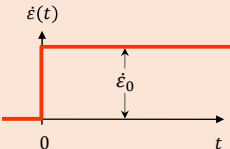
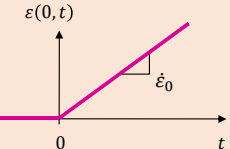
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Start-up of Steady Elongation Material Functions Michigan Tech

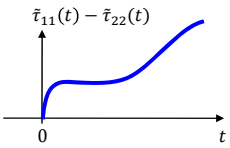
Imposed Kinematics:

$$\underline{v} \equiv \begin{pmatrix} -\frac{1}{2}\dot{\epsilon}(t)x_1 \\ -\frac{1}{2}\dot{\epsilon}(t)x_2 \\ \dot{\epsilon}(t)x_3 \end{pmatrix}_{123}$$

$$\dot{\epsilon}(t) = \begin{cases} 0 & t < 0 \\ \dot{\epsilon}_0 & t \geq 0 \end{cases}$$

Material Stress Response:




Material Functions:

Elongational Start-up Function $\eta_e^+(t, \dot{\epsilon}_0) \equiv \frac{\bar{\tau}_{33} - \bar{\tau}_{11}}{\dot{\epsilon}_0} = \frac{-(\tau_{33} - \tau_{11})}{\dot{\epsilon}_0}$

Alternatively, $\bar{\eta}^+(t, \dot{\epsilon}_0)$

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What exactly do we observe when we subject non-Newtonian fluids to deformation?



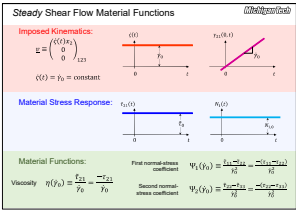
Summary

Rheological Material Functions

- Are the answer to the question *“What exactly do we observe when we subject non-Newtonian fluids to deformation?”*
- Are based on continuum view
- Provide a framework/vocabulary of comparison
- Help to categorize and organize observed material responses


Material Functions do not:

- Identify a material conclusively
- Tell us the form of $\underline{\tau}(\underline{v})$



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What exactly do we observe when we subject non-Newtonian fluids to deformation?



Summary

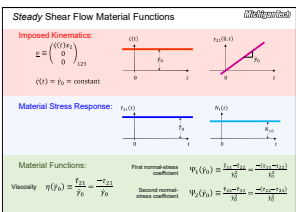
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Cannot conclusively identify, but can classify and can be used to assess proposed models



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Summary

Rheological Material Functions

- Are the answer to the question “*What exactly do we observe when we subject non-Newtonian fluids to deformation?*”
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- Provide a framework/vocabulary of comparison
- Help to categorize and organize observed material responses

Material Functions do not:

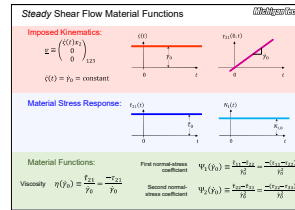
- Identify a material conclusively
- Tell us the form of $\underline{\underline{\tau}}(\underline{\underline{\nu}})$

Cannot conclusively identify, but can classify and can be used to assess proposed models

Except for Newtonian fluids, the structure of the model for stress is not known $\underline{\underline{\tau}}(\underline{\underline{\nu}}) = ?$, and remains a mystery

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What exactly do we observe when we subject non-Newtonian fluids to deformation?



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