A mixed FEM for the quad-curl eigenvalue problem

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Abstract The quad-curl problem arises in the study of the electromagnetic interior transmission problem and magnetohydrodynamics (MHD). In this paper, we study the quad-curl eigenvalue problem and propose a mixed method using edge elements. Assuming stringent regularity of the solution of the quad-curl source problem, we prove the convergence and show that the divergence-free condition can be bypassed.

Keywords quad-curl eigenvalue problem \cdot spectral approximation \cdot mixed finite element method \cdot edge element

Mathematics Subject Classification (2000) 65N30 · 35Q60

1 Introduction

The quad-curl problem arises in inverse electromagnetic scattering theory for inhomogeneous media [13] and magnetohydrodynamics (MHD) equations [15]. To compute eigenvalues, one usually starts with the corresponding source problem. The construction of conforming finite elements with suitable regularity for the quad-curl problem is extremely technical and prohibitively expensive even if such finite elements exist.

In this paper, we propose a mixed finite element method for the quad-curl source problem. The major advantage of this approach lies in the fact that only curl-conforming edge elements are needed [14]. Then we employ the method to compute quad-curl eigenvalues. We prove convergence following [1]. Unlike the Maxwell eigenvalue problem, which has been studied extensively in the literature (see, for example [7] and [3]), there are few results on the quad-curl

Department of Mathematical Sciences Michigan Technological University Tel.: +1-906-487-2068 Fax: +1-906-487-3133 E-mail: jiguangs@mtu.edu source problem. Recently Zheng et al. [15] propose a non-conforming finite element method. To the author's knowledge, this paper is the first numerical treatment of the quad-curl eigenvalue problem.

The rest of the paper is organized as follows. Section 2 contains some preliminaries. In Section 3, we propose a mixed finite element method for the the quad-curl problem and prove its convergence. In Section 4, we employ the mixed method for the quad-curl eigenvalue problem. In addition, we show that the divergence-free condition, which is usually treated using Lagrange multipliers, can be ignored for the eigenvalue problem.

2 Preliminaries

2.1 Function Spaces

Let $D \subset \mathbb{R}^3$ be a convex, simply connected Lipschitz polyhedral domain. The boundary of D is assumed to be connected with unit outward normal $\boldsymbol{\nu}$. We denote by (\cdot, \cdot) the $L^2(D)$ inner product and by $\|\cdot\|$ the $L^2(D)$ norm. The variational approach we shall describe for the quad-curl problem requires several Hilbert spaces. We define

$$H^{s}(\operatorname{curl}; D) := \left\{ \mathbf{u} \in L^{2}(D)^{3} \mid \operatorname{curl}^{j} \mathbf{u} \in L^{2}(D)^{3}, 1 \le j \le s \right\}$$

equipped with the scalar product

$$(\mathbf{u}, \mathbf{v})_{H^s(\operatorname{curl};D)} = (\mathbf{u}, \mathbf{v}) + \sum_{j=1}^s (\operatorname{curl}^j \mathbf{u}, \operatorname{curl}^j \mathbf{v})$$

and the corresponding norm $\|\cdot\|_{H^s(\operatorname{curl};D)}$. We shall use the standard notation $H(\operatorname{curl};D)$ when s = 1. Next we define

$$H_0(\operatorname{curl}; D) := \left\{ \mathbf{u} \in H(\operatorname{curl}; D) \mid \mathbf{u} \times \boldsymbol{\nu} = 0 \text{ on } \partial D \right\},\$$

$$H_0^2(\operatorname{curl}; D) := \left\{ \mathbf{u} \in H^2(\operatorname{curl}; D) \mid \mathbf{u} \times \boldsymbol{\nu} = 0 \text{ and } (\operatorname{curl} \mathbf{u}) \times \boldsymbol{\nu} = 0 \text{ on } \partial D \right\}.$$

We also need the space $H(\operatorname{div}; D)$ of functions with square-integrable divergence defined by

$$H(\operatorname{div}; D) = \{ \mathbf{u} \in L^2(D)^3 \mid \operatorname{div} \mathbf{u} \in L^2(D) \},\$$

equipped with the scalar product

$$(\mathbf{u}, \mathbf{v})_{H(\operatorname{div};D)} = (\mathbf{u}, \mathbf{v}) + (\operatorname{div} \mathbf{u}, \operatorname{div} \mathbf{v})$$

and the corresponding norm $\|\cdot\|_{H(\operatorname{div},D)}$.

Taking the divergence-free condition into account, we define

$$X = \{ \mathbf{u} \in H(\operatorname{curl}; D) \cap H(\operatorname{div}; D) | \operatorname{div} \mathbf{u} = 0 \text{ in } D \}, Y = \{ \mathbf{u} \in H_0(\operatorname{curl}; D) \cap H(\operatorname{div}; D) | \operatorname{div} \mathbf{u} = 0 \text{ in } D \}, H(\operatorname{div}^0; D) = \{ \mathbf{u} \in H(\operatorname{div}; D) | \operatorname{div} \mathbf{u} = 0 \text{ in } D \}.$$

For functions in Y, the following Friedrichs inequality holds.

Lemma 1 (see, for example, Corollary 3.51 of [12]) Suppose that D is a bounded Lipschitz domain. If D is simply connected, and has a connected boundary, there is a constant $C \ge 0$ such that for every $\mathbf{u} \in Y$,

$$\|\mathbf{u}\| \le C \|\operatorname{curl} \mathbf{u}\|. \tag{1}$$

2.2 The edge element

We give a short introduction of edge elements [14]. We assume that the domain D is covered by a regular tetrahedral mesh. We denote the mesh by \mathcal{T}_h where h is the maximum diameter of the elements in \mathcal{T}_h . Let P_k be the space of polynomials of maximum total degree k and \tilde{P}_k the space of homogeneous polynomials of degree k. We define

$$R_k = (P_{k-1})^3 \oplus \{ \mathbf{p} \in (\tilde{P}_k)^3 \mid \mathbf{x} \cdot \mathbf{p}(\mathbf{x}) = 0 \text{ for all } \mathbf{x} \in \mathbb{R}^3 \}.$$

The curl-conforming edge element space [14] is given by

$$U_h = \{ \mathbf{v} \in H(\operatorname{curl}; D) \mid \mathbf{v}|_K \in R_k \text{ for all } K \in \mathcal{T}_h \}.$$

The $H_0(\operatorname{curl}; D)$ conforming edge element space is simply

$$U_{0,h} = \{ \mathbf{u}_h \in U_h \mid \boldsymbol{\nu} \times \mathbf{u}_h = 0 \quad \text{on } \partial D \},$$
⁽²⁾

which can be easily obtained by setting the degrees of freedom associated with edges and faces on ∂D to zero. Let $\mathbf{r}_h \mathbf{u} \in U_h$ be the global interpolant. The following result holds.

Lemma 2 (Lemma 5.38 of [12]) Suppose there are constants $\delta > 0$ and p > 2 such that $\mathbf{u} \in H^{1/2+\delta}(K)^3$ and $\operatorname{curl} \mathbf{u} \in L^p(K)^3$ for each $K \in \mathcal{T}_h$. Then $\mathbf{r}_h \mathbf{u}$ is well-defined and bounded.

The following result provides error estimates for the interpolant.

Lemma 3 (Theorem 5.41 of [12]) Let \mathcal{T}_h be a regular mesh on D. Then (1) If $\mathbf{u} \in H^s(D)^3$ and $\operatorname{curl} \mathbf{u} \in H^s(D)^3$ for $1/2 + \delta \leq s \leq k$ for $\delta > 0$ then

$$\begin{aligned} \|\mathbf{u} - \mathbf{r}_{h}\mathbf{u}\|_{L^{2}(D)^{3}} + \|\mathrm{curl}(\mathbf{u} - \mathbf{r}_{h}\mathbf{u})\|_{L^{2}(D)^{3}} \\ &\leq Ch^{s}\left(\|\mathbf{u}\|_{H^{s}(D)^{3}} + \|\mathrm{curl}\,\mathbf{u}\|_{H^{s}(D)^{3}}\right). \end{aligned} (3)$$

(2) If $\mathbf{u} \in H^{1/2+\delta}(K)^3$, $0 < \delta \le 1/2$ and $\operatorname{curl} \mathbf{u}|_K \in P_k$, then

$$\|\mathbf{u} - \mathbf{r}_h \mathbf{u}\|_{L^2(D)^3} \le C \left(h_K^{1/2+\delta} \|\mathbf{u}\|_{H^{1/2+\delta}(K)^3} + h_K \|\operatorname{curl} \mathbf{u}\|_{L^2(K)^3} \right)$$

(3) If $\mathbf{u} \in H^s(D)^3$ and $\operatorname{curl} \mathbf{u} \in H^s(D)^3$ for $1/2 + \delta \leq s \leq k$ and $\delta > 0$, the following result holds

$$\|\operatorname{curl}(\mathbf{u}-\mathbf{r}_h\mathbf{u})\|_{L^2(D)^3} \le Ch^s \|\operatorname{curl}\mathbf{u}\|_{H^s(D)^3}.$$

The following inverse inequality for edge elements will be useful in the forthcoming error analysis (see Section 3.6 of [10]).

Lemma 4 Let \mathcal{T}_h be a regular mesh for D. Then for $\mathbf{u}_h \in U_h$,

$$\mathbf{u}_h\|_{H(\operatorname{curl};D)} \le Ch^{-1}\|\mathbf{u}_h\|$$

for some constant C independent of \mathbf{u}_h and h.

2.3 The curl-curl problem

The curl-curl problem has been studied extensively in the literature. We just collect some results for later use and refer the readers to [10] and [11] for details. The problem is stated as follows. For $\mathbf{f} \in H(\operatorname{div}^0; D)$, find \mathbf{u} such that

 $\operatorname{curl}\operatorname{curl}\mathbf{u} = \mathbf{f} \qquad \qquad \text{in } D, \qquad (4a)$

$$\operatorname{div} \mathbf{u} = 0 \qquad \qquad \operatorname{in} D, \qquad (4b)$$

$$\mathbf{u} \times \boldsymbol{\nu} = 0 \qquad \qquad \text{on } \partial D. \tag{4c}$$

The mixed form is to find $(\mathbf{u}, p) \in H_0(\operatorname{curl}; D) \times H_0^1(D)$ such that

$$(\operatorname{curl} \mathbf{u}, \operatorname{curl} \boldsymbol{\phi}) + (\operatorname{grad} p, \boldsymbol{\phi}) = (\mathbf{f}, \boldsymbol{\phi}) \quad \text{for all } \boldsymbol{\phi} \in H_0(\operatorname{curl}; D), \quad (5a)$$

$$(\mathbf{u}, \operatorname{grad} q) = 0$$
 for all $q \in H_0^1(D)$. (5b)

Let the finite element space for $H_0^1(D)$ be given by

$$S_h = \left\{ p_h \in H^1_0(D) \mid p_h \mid_K \in P_k \text{ for all } K \in \mathcal{T}_h \right\}.$$

It follows that $\operatorname{grad} S_h \subset U_{0,h}$. The discrete Helmholtz decomposition can be defined via

$$U_{0,h} = Y_h \oplus \operatorname{grad} S_h$$

where Y_h is given by

$$Y_h = \{ \mathbf{u}_h \in U_{0,h} \mid (\mathbf{u}_h, \operatorname{grad} \xi_h) = 0 \quad \text{for all } \xi_h \in S_h \}.$$
(6)

Then the discrete problem for (5) is to find $(\mathbf{u}_h, p_h) \in U_{0,h} \times S_h$ such that

$$(\operatorname{curl} \mathbf{u}_h, \operatorname{curl} \boldsymbol{\phi}_h) + (\operatorname{grad} p_h, \boldsymbol{\phi}_h) = (\mathbf{f}, \boldsymbol{\phi}_h) \quad \text{for all } \boldsymbol{\phi}_h \in U_{0,h},$$
 (7a)

$$(\mathbf{u}_h, \operatorname{grad} q_h) = 0$$
 for all $q_h \in S_h$. (7b)

Lemma 5 (discrete Friedrichs inequality of Y_h) Let D be a bounded simply connected Lipschitz domain. There exists a positive constant C independent of h such that, for h small enough,

$$\|\mathbf{u}_h\| \le C \|\operatorname{curl} \mathbf{u}_h\| \quad \text{for all } \mathbf{u}_h \in Y_h$$

Lemma 6 The discrete problem (7) has a unique solution $(\mathbf{u}_h, p_h) \in U_{0,h} \times S_h$ with $p_h = 0$. In addition, if $(\mathbf{u}, p) \in H_0(\operatorname{curl}; D) \times H_0^1(D)$ is the solution of (4) with p = 0, there exists a constant C independent of h, \mathbf{u} , and \mathbf{u}_h such that

$$\|\mathbf{u} - \mathbf{u}_h\|_{H(\operatorname{curl})} \le C \inf_{\mathbf{v}_h \in U_{0,h}} \|\mathbf{u} - \mathbf{v}_h\|_{H(\operatorname{curl})}.$$

3 The Quad-curl Problem

The quad-curl problem is defined as follows. For $\mathbf{f} \in H(\operatorname{div}^0; D)$, find \mathbf{u} such that

$$(\operatorname{curl})^4 \mathbf{u} = \mathbf{f}$$
 in D , (8a)

$$\operatorname{div} \mathbf{u} = 0 \qquad \qquad \text{in } D, \tag{8b}$$

$$\mathbf{u} \times \boldsymbol{\nu} = 0 \qquad \qquad \text{on } \boldsymbol{\Gamma}, \tag{8c}$$

$$(\operatorname{curl} \mathbf{u}) \times \boldsymbol{\nu} = 0$$
 on $\boldsymbol{\Gamma}$. (8d)

In this section, we first prove the well-posedness of the quad-curl problem. Then we propose a mixed formulation. To this end, we let V and W be given by

$$V := \left\{ \mathbf{u} \in H_0^2(\operatorname{curl}; D) \cap H(\operatorname{div}; D) \mid \operatorname{div} \mathbf{u} = 0 \right\},\tag{9}$$

$$W := \{ \mathbf{u} \in H^2(\operatorname{curl}; D) \cap H(\operatorname{div}; D) \mid \operatorname{div} \mathbf{u} = 0 \}.$$
(10)

We define a bilinear form $\mathcal{C}: V \times V \to \mathbb{R}$ by

$$\mathcal{C}(\mathbf{u}, \mathbf{v}) := (\operatorname{curl}\operatorname{curl}\mathbf{u}, \operatorname{curl}\operatorname{curl}\mathbf{v}) \quad \text{for all } \mathbf{u}, \mathbf{v} \in V.$$
(11)

Let $\mathbf{f} \in H(\operatorname{div}^0; D)$. The weak formulation for the quad-curl problem is to find $\mathbf{u} \in V$ such that

$$\mathcal{C}(\mathbf{u}, \mathbf{v}) = (\mathbf{f}, \mathbf{v}) \quad \text{for all } \mathbf{v} \in V.$$
(12)

Theorem 1 There exists a unique solution $\mathbf{u} \in V$ to (12).

Proof Due to the fact that functions in V are divergence-free, using the Friedrichs inequality twice, we see that the bilinear form C is elliptic on V. Then Lax-Milgram lemma implies that there exists a unique solution \mathbf{u} of (12) in V. \Box

To the author's knowledge, there are no regularity results for the quad-curl problem in the literature. For Maxwell's equations, it is well-known that nonconvexity leads to singularities, see [7] and [8]. For the biharmonic equation with clamped plate boundary conditions, convexity is sufficient for the solution to be in H^3 [9]. Therefore the mixed finite element method given in [6] for the corresponding biharmonic eigenvalue problem does not produce spurious modes. However, whether convexity is sufficient for the quad-curl solution to be in $H^3(\text{curl}; D)$ is a non-trivial open problem. On the other hand, for biharmonic eigenvalue problems on non-convex domains, mixed finite methods compute spurious modes [4]. Thus non-convexity might lead to the failure of the mixed method for the quad-curl eigenvalue problem. For simplicity, we shall make the following assumption in the rest of the paper.

Assumption: The solution **u** of (12) belongs to $H^3(\operatorname{curl}; D)$.

Let $\phi = \operatorname{curl} \operatorname{curl} \mathbf{u}$. We define

$$a(\mathbf{u}, \mathbf{v}) = (\mathbf{u}, \mathbf{v}), \quad b(\mathbf{u}, \mathbf{v}) = -(\operatorname{curl} \mathbf{u}, \operatorname{curl} \mathbf{v}).$$

The mixed formulation for the quad-curl problem can be stated as follows. For $\mathbf{f} \in H(\operatorname{div}^0; D)$, find $(\mathbf{u}, \boldsymbol{\phi}) \in Y \times X$ such that

$$a(\mathbf{f}, \mathbf{v}) + b(\boldsymbol{\phi}, \mathbf{v}) = 0,$$
 for all $\mathbf{v} \in Y,$ (13a)

$$b(\mathbf{u}, \boldsymbol{\psi}) = -(\boldsymbol{\phi}, \boldsymbol{\psi}),$$
 for all $\boldsymbol{\psi} \in X.$ (13b)

In the following, we derive the equivalence of the above mixed formulation to the quad-curl problem. We employ a technique similar to that in Section 7.1 of [6] for the biharmonic equation.

The solution of the quad-curl problem is the solution of the following unconstrained minimization problem: Find ${\bf u}$ such that

$$J(\mathbf{u}) = \inf_{\mathbf{v} \in V} J(\mathbf{v}) \tag{14}$$

where

$$J(\mathbf{v}) = \frac{1}{2} \int_{D} |\operatorname{curl}^2 \mathbf{v}|^2 \, \mathrm{d}x - \int_{D} \mathbf{f} \cdot \mathbf{v} \, \mathrm{d}x.$$
(15)

This follows because (12) is the Euler-Lagrange equation for the minimization problem. Equivalently we consider the constrained minimization problem associated with the quadratic form

$$\mathcal{J}(\mathbf{v}, \boldsymbol{\psi}) = \frac{1}{2} \int_{D} |\boldsymbol{\psi}|^2 \, \mathrm{d}x - \int_{D} \mathbf{f} \cdot \mathbf{v} \, \mathrm{d}x \tag{16}$$

for $(\mathbf{v}, \boldsymbol{\psi}) \in V \times L^2(D)^3$ such that $\operatorname{curl}^2 \mathbf{v} = \boldsymbol{\psi}$.

We define

$$\mathcal{V} := \left\{ (\mathbf{v}, \boldsymbol{\psi}) \in Y \times L^2(D)^3 \mid \beta((\mathbf{v}, \boldsymbol{\psi}), \boldsymbol{\mu}) = 0 \text{ for all } \boldsymbol{\mu} \in X \right\},\$$

where

$$\beta((\mathbf{v}, \boldsymbol{\psi}), \boldsymbol{\mu}) = \int_D \operatorname{curl} \mathbf{v} \cdot \operatorname{curl} \boldsymbol{\mu} \, \mathrm{d}x - \int_D \boldsymbol{\psi} \cdot \boldsymbol{\mu} \, \mathrm{d}x.$$
(17)

Thus the problem can be stated as: Find $(\mathbf{u}, \boldsymbol{\phi}) \in \mathcal{V}$ such that

$$\int_D \boldsymbol{\phi} \cdot \boldsymbol{\psi} \, \mathrm{d}x = \int_D \mathbf{f} \cdot \mathbf{v} \, \mathrm{d}x \quad \text{for all } (\mathbf{v}, \boldsymbol{\psi}) \in \mathcal{V}.$$

Lemma 7 The mapping

$$(\mathbf{v}, oldsymbol{\psi}) \in \mathcal{V}
ightarrow \|oldsymbol{\psi}\|$$

is a norm over \mathcal{V} . Furthermore, we have

$$\mathcal{V} := \left\{ (\mathbf{v}, \boldsymbol{\psi}) \in V \times L^2(D)^3 \mid \operatorname{curl}^2 \mathbf{v} = \boldsymbol{\psi} \right\}.$$

Proof The lemma follows directly from the Friedrichs inequality.

Theorem 2 If $\mathbf{u} \in V$ is the solution of (14), we have that

$$\mathcal{J}(\mathbf{u},\operatorname{curl}^{2}\mathbf{u}) = \inf_{(\mathbf{v},\boldsymbol{\psi})\in\mathcal{V}} \mathcal{J}(\mathbf{v},\boldsymbol{\psi}).$$
(18)

and $(\mathbf{u}, \operatorname{curl}^2 \mathbf{u}) \in \mathcal{V}$ is the unique solution of (18).

Proof Since

$$((\mathbf{u}, \boldsymbol{\phi}), (\mathbf{v}, \boldsymbol{\psi})) \in \mathcal{V} \times \mathcal{V} \to \int_D \boldsymbol{\phi} \cdot \boldsymbol{\psi} \, \mathrm{d}x$$

is continuous and \mathcal{V} -elliptic,

$$(\mathbf{v}, \boldsymbol{\psi}) \in \mathcal{V} \to \int_D \mathbf{f} \cdot \mathbf{v} \, \mathrm{d}x$$

is continuous, the minimization problem of finding $(\mathbf{u}^*, \boldsymbol{\phi}) \in \mathcal{V}$ such that

$$\mathcal{J}(\mathbf{u}^*, oldsymbol{\phi}) = \inf_{(\mathbf{v}, oldsymbol{\psi}) \in \mathcal{V}} \mathcal{J}(\mathbf{v}, oldsymbol{\psi})$$

has a unique solution that satisfies

$$\int_D \boldsymbol{\phi} \cdot \boldsymbol{\psi} \, \mathrm{d}x = \int_D \mathbf{f} \cdot \mathbf{v} \, \mathrm{d}x \quad \text{for all } (\mathbf{v}, \boldsymbol{\psi}) \in \mathcal{V}.$$

From Lemma 7, we see that $\mathbf{u}^* \in V$ and that $\operatorname{curl}^2 \mathbf{u}^* = \boldsymbol{\phi}$. We have

$$\int_D \operatorname{curl}^2 \mathbf{u} \cdot \operatorname{curl}^2 \mathbf{v} \, \mathrm{d}x = \int_D \mathbf{f} \cdot \mathbf{v} \, \mathrm{d}x.$$

Consequently \mathbf{u}^* is the solution \mathbf{u} of (14).

Based on the above theorem, we define two solution operators $A: H(\text{div}^0; D) \to X$ and $B: H(\text{div}^0; D) \to Y$ for (13) such that

$$A\mathbf{f} = \boldsymbol{\phi}, \quad B\mathbf{f} = \mathbf{u}. \tag{19}$$

We can write (13) as

$$a(A\mathbf{f}, \mathbf{v}) + b(\mathbf{v}, B\mathbf{f}) = 0, \qquad \text{for all } \mathbf{v} \in X, \qquad (20a)$$

$$b(A\mathbf{f}, \mathbf{q}) = -(\mathbf{f}, \mathbf{q}), \qquad \text{for all } \mathbf{q} \in Y. \qquad (20b)$$

$$\mathcal{V}_h = \{ (\mathbf{v}_h, \boldsymbol{\psi}_h) \in Y_h \times X_h \mid \beta((\mathbf{v}_h, \boldsymbol{\psi}_h), \boldsymbol{\mu}_h) = 0 \quad \text{for all } \boldsymbol{\mu}_h \in X_h \},\$$

where X_h is such that

$$U_h = X_h \oplus \operatorname{grad} S_h.$$

Note that $X_h \not\subset X$. Functions in X_h are said to be discrete divergence-free. The discrete problem corresponding to (16) is to find $(\mathbf{u}_h, \phi_h) \in \mathcal{V}_h$ such that

$$\mathcal{J}(\mathbf{u}_h, \boldsymbol{\phi}_h) = \inf_{(\mathbf{v}_h, \boldsymbol{\psi}_h) \in \mathcal{V}_h} \mathcal{J}(\mathbf{v}_h, \boldsymbol{\psi}_h).$$
(21)

It is easy to see that the discrete problem (21) has a unique solution and the element $(\mathbf{u}_h, \boldsymbol{\phi}_h) \in \mathcal{V}_h$ satisfies

$$\int_{D} \boldsymbol{\phi}_{h} \cdot \boldsymbol{\psi}_{h} \, \mathrm{d}x = \int_{D} \mathbf{f} \cdot \mathbf{v}_{h} \, \mathrm{d}x \quad \text{for all } (\mathbf{v}_{h}, \boldsymbol{\psi}_{h}) \in \mathcal{V}_{h}.$$
(22)

Theorem 3 Let (\mathbf{u}, ϕ) and (\mathbf{u}_h, ϕ_h) be solutions of (18) and (21), respectively, and assume that $\mathbf{u} \in H^3(\operatorname{curl}; D)$. There exists a constant C independent of h such that

$$\|\operatorname{curl} \mathbf{u} - \operatorname{curl} \mathbf{u}_{h}\| + \|\operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\phi}_{h}\| \leq C\left(\inf_{(\mathbf{v}_{h}, \boldsymbol{\psi}_{h}) \in \mathcal{V}_{h}} \left(\|\operatorname{curl} \mathbf{u} - \operatorname{curl} \mathbf{v}_{h}\| + \|\operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\psi}_{h}\|\right) + \inf_{\boldsymbol{\mu}_{h} \in X_{h}} \|\operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\mu}_{h}\|_{H(\operatorname{curl})}\right).$$
(23)

Proof Assuming that $\mathbf{u} \in H^3(\operatorname{curl}; D)$, we have

$$\int_D \operatorname{curl}(\operatorname{curl}^2 \mathbf{u}) \cdot \operatorname{curl} \mathbf{v} \, \mathrm{d}x = \int_D \operatorname{curl}^2 \mathbf{u} \cdot \operatorname{curl}^2 \mathbf{v} \, \mathrm{d}x = \int_D \mathbf{f} \cdot \mathbf{v} \, \mathrm{d}x$$

for all $\mathbf{v} \in \mathcal{D}(D)^3$, the space of smooth functions with compact support in D. Hence for all $\mathbf{v} \in H_0(\operatorname{curl}; D)$, the following holds

$$\int_{D} \operatorname{curl}(\operatorname{curl}^{2} \mathbf{u}) \cdot \operatorname{curl} \mathbf{v} \, \mathrm{d}x = \int_{D} \mathbf{f} \cdot \mathbf{v} \, \mathrm{d}x.$$
(24)

Thus for any $\mathbf{v} \in H_0(\operatorname{curl}; D)$ and $\boldsymbol{\psi} \in L^2(D)^3$, we have

$$\beta\left((\mathbf{v},\boldsymbol{\psi}),\operatorname{curl}^{2}\mathbf{u}\right) = \int_{D}\mathbf{f}\cdot\mathbf{v}\,\mathrm{d}x - \int_{D}\boldsymbol{\psi}\cdot\operatorname{curl}^{2}\mathbf{u}\,\mathrm{d}x.$$

For any $(\mathbf{v}_h, \boldsymbol{\psi}_h) \in \mathcal{V}_h$ and $\boldsymbol{\mu}_h \in X_h$, using the fact that $\beta((\mathbf{v}_h, \boldsymbol{\psi}_h), \boldsymbol{\mu}_h) = 0$, (24), and (22), we have

$$\beta \left((\mathbf{u}_{h} - \mathbf{v}_{h}, \phi_{h} - \psi_{h}), \operatorname{curl}^{2} \mathbf{u} - \mu_{h} \right)$$

$$= \int_{D} \operatorname{curl}(\mathbf{u}_{h} - \mathbf{v}_{h}) \cdot \operatorname{curl}(\operatorname{curl}^{2} \mathbf{u} - \mu_{h}) \, \mathrm{d}x$$

$$- \int_{D} (\phi_{h} - \psi_{h}) \cdot (\operatorname{curl}^{2} \mathbf{u} - \mu_{h}) \, \mathrm{d}x$$

$$= \int_{D} \operatorname{curl}(\mathbf{u}_{h} - \mathbf{v}_{h}) \cdot \operatorname{curl} \operatorname{curl}^{2} \mathbf{u} \, \mathrm{d}x - \int_{D} \operatorname{curl}(\mathbf{u}_{h} - \mathbf{v}_{h}) \cdot \operatorname{curl} \mu_{h} \, \mathrm{d}x$$

$$- \int_{D} (\phi_{h} - \psi_{h}) \cdot \operatorname{curl}^{2} \mathbf{u} \, \mathrm{d}x + \int_{D} (\phi_{h} - \psi_{h}) \cdot \mu_{h} \, \mathrm{d}x$$

$$= \int_{D} \operatorname{curl}(\mathbf{u}_{h} - \mathbf{v}_{h}) \cdot \operatorname{curl} \operatorname{curl}^{2} \mathbf{u} \, \mathrm{d}x - \int_{D} (\phi_{h} - \psi_{h}) \cdot \operatorname{curl}^{2} \mathbf{u} \, \mathrm{d}x$$

$$= \int_{D} \operatorname{f} \cdot (\mathbf{u}_{h} - \mathbf{v}_{h}) \, \mathrm{d}x - \int_{D} (\phi_{h} - \psi_{h}) \cdot \operatorname{curl}^{2} \mathbf{u} \, \mathrm{d}x$$

$$= \int_{D} \phi_{h} \cdot (\phi_{h} - \psi_{h}) \, \mathrm{d}x - \int_{D} (\phi_{h} - \psi_{h}) \cdot \operatorname{curl}^{2} \mathbf{u} \, \mathrm{d}x$$

$$= -\int_{D} (\operatorname{curl}^{2} \mathbf{u} - \phi_{h}) \cdot (\phi_{h} - \psi_{h}) \, \mathrm{d}x.$$

On the other hand, for all $\mu_h \in X_h$, one has

$$\int_{D} \operatorname{curl} \mathbf{u}_{h} \cdot \operatorname{curl} \boldsymbol{\mu}_{h} \mathrm{d} x = \int_{D} \boldsymbol{\phi}_{h} \cdot \boldsymbol{\mu}_{h} \mathrm{d} x,$$
$$\int_{D} \operatorname{curl} \mathbf{v}_{h} \cdot \operatorname{curl} \boldsymbol{\mu}_{h} \mathrm{d} x = \int_{D} \boldsymbol{\psi}_{h} \cdot \boldsymbol{\mu}_{h} \mathrm{d} x.$$

Taking the difference and letting $\boldsymbol{\mu}_h = \mathbf{u}_h - \mathbf{v}_h$, we have

$$\int_D \operatorname{curl}(\mathbf{u}_h - \mathbf{v}_h) \cdot \operatorname{curl}(\mathbf{u}_h - \mathbf{v}_h) dx = \int_D (\boldsymbol{\phi}_h - \boldsymbol{\psi}_h) \cdot (\mathbf{u}_h - \mathbf{v}_h) dx,$$

which implies

$$\|\operatorname{curl}(\mathbf{u}_h - \mathbf{v}_h)\| \le C \|\boldsymbol{\phi}_h - \boldsymbol{\psi}_h\|,\tag{26}$$

where C is the constant in the discrete Friedrichs inequality.

Using the above inequality and (25), we have

$$\begin{aligned} \left| \int_{D} (\operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\phi}_{h}) \cdot (\boldsymbol{\phi}_{h} - \boldsymbol{\psi}_{h}) \, \mathrm{d}x \right| \\ &= \left| \beta \left((\mathbf{u}_{h} - \mathbf{v}_{h}, \boldsymbol{\phi}_{h} - \boldsymbol{\psi}_{h}), \operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\mu}_{h} \right) \right| \\ &\leq \left\| \operatorname{curl}(\mathbf{u}_{h} - \mathbf{v}_{h}) \right\| \left\| \operatorname{curl}(\operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\mu}_{h}) \right\| + \left\| \boldsymbol{\phi}_{h} - \boldsymbol{\psi}_{h} \right\| \left\| \operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\mu}_{h} \right\| \\ &\leq C \| \boldsymbol{\phi}_{h} - \boldsymbol{\psi}_{h} \| \left\| \operatorname{curl}(\operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\mu}_{h}) \right\| + \left\| \boldsymbol{\phi}_{h} - \boldsymbol{\psi}_{h} \right\| \left\| \operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\mu}_{h} \right\| \\ &\leq C_{1} \| \boldsymbol{\phi}_{h} - \boldsymbol{\psi}_{h} \| \left\| \operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\mu}_{h} \right\|_{H(\operatorname{curl})}, \end{aligned}$$

where $C_1 = \max\{C, 1\}$. Thus we have that

$$\begin{split} \|\boldsymbol{\phi}_{h} - \boldsymbol{\psi}_{h}\|^{2} \\ &= -\int_{D} (\boldsymbol{\phi}_{h} - \boldsymbol{\psi}_{h}) \cdot (\operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\phi}_{h}) \, \mathrm{d}x + \int_{D} (\boldsymbol{\phi}_{h} - \boldsymbol{\psi}_{h}) \cdot (\operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\psi}_{h}) \, \mathrm{d}x \\ &\leq C_{1} \|\boldsymbol{\phi}_{h} - \boldsymbol{\psi}_{h}\| \, \|\operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\mu}_{h}\|_{H(\operatorname{curl})} + \|\boldsymbol{\phi}_{h} - \boldsymbol{\psi}_{h}\| \, \|\operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\psi}_{h}\| \end{split}$$

and hence

$$\|\boldsymbol{\phi}_h - \boldsymbol{\psi}_h\| \le C_1 \|\operatorname{curl}^2 \mathbf{u} - \boldsymbol{\mu}_h\|_{H(\operatorname{curl})} + \|\operatorname{curl}^2 \mathbf{u} - \boldsymbol{\psi}_h\|$$

Moreover, we have that

 $\|\operatorname{curl} \mathbf{u} - \operatorname{curl} \mathbf{u}_h\| + \|\operatorname{curl}^2 \mathbf{u} - \boldsymbol{\phi}_h\|$

 $\leq \|\operatorname{curl} \mathbf{u} - \operatorname{curl} \mathbf{v}_h\| + \|\operatorname{curl} \mathbf{v}_h - \operatorname{curl} \mathbf{u}_h\| + \|\operatorname{curl}^2 \mathbf{u} - \boldsymbol{\psi}_h\| + \|\boldsymbol{\psi}_h - \boldsymbol{\phi}_h\| \\ \leq \|\operatorname{curl} \mathbf{u} - \operatorname{curl} \mathbf{v}_h\| + \|\operatorname{curl}^2 \mathbf{u} - \boldsymbol{\psi}_h\| + (1+C)\|\boldsymbol{\psi}_h - \boldsymbol{\phi}_h\|,$

where we have used (26). Combining the above inequalities, we obtain

$$\begin{aligned} \|\operatorname{curl} \mathbf{u} - \operatorname{curl} \mathbf{u}_{h}\| + \|\operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\phi}_{h}\| \\ &\leq \|\operatorname{curl} \mathbf{u} - \operatorname{curl} \mathbf{v}_{h}\| + \|\operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\psi}_{h}\| \\ &+ (1+C) \left(C_{1} \|\operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\mu}_{h}\|_{H(\operatorname{curl})} + \|\operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\psi}_{h}\| \right) \\ &\leq \|\operatorname{curl} \mathbf{u} - \operatorname{curl} \mathbf{v}_{h}\| + (2+C) \|\operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\psi}_{h}\| + (1+C)C_{1} \|\operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\mu}_{h}\|_{H(\operatorname{curl})}. \end{aligned}$$

The proof is complete by taking the infimum of the right side over all $(\mathbf{v}_h, \boldsymbol{\psi}_h) \in \mathcal{V}_h$ and $\boldsymbol{\mu}_h \in X_h$.

Theorem 4 Let $(\mathbf{u}, \boldsymbol{\phi})$ and $(\mathbf{u}_h, \boldsymbol{\phi}_h)$ solve (18) and (21), respectively. Let $\alpha(h) = C_1/h$ where C_1 is the constant in Lemma 4. Then there exists a constant C independent of the mesh size h such that

$$\begin{aligned} \|\operatorname{curl} \mathbf{u} - \operatorname{curl} \mathbf{u}_h\| + \|\operatorname{curl}^2 \mathbf{u} - \boldsymbol{\phi}_h\| \\ &\leq C \left\{ (1 + \alpha(h)) \inf_{\mathbf{v}_h \in Y_h} \|\operatorname{curl} \mathbf{u} - \operatorname{curl} \mathbf{v}_h\| + \inf_{\boldsymbol{\mu}_h \in X_h} \|\operatorname{curl}^2 \mathbf{u} + \boldsymbol{\mu}_h\|_{H(\operatorname{curl})} \right\} \end{aligned}$$

Proof Let $(\mathbf{v}_h, \boldsymbol{\psi}_h) \in \mathcal{V}_h$ and $\boldsymbol{\mu}_h \in X_h$. Writing $\mathbf{w}_h = \boldsymbol{\mu}_h + \boldsymbol{\psi}_h$, we have that $\beta((\mathbf{v}_h, \boldsymbol{\psi}_h), \mathbf{w}_h) = 0$, i.e.,

$$\int_{D} \operatorname{curl} \mathbf{v}_{h} \cdot \operatorname{curl} \mathbf{w}_{h} \, \mathrm{d}x - \int_{D} \boldsymbol{\psi}_{h} \cdot \mathbf{w}_{h} \, \mathrm{d}x = 0.$$

Using the fact that $\boldsymbol{\nu} \times \operatorname{curl} \mathbf{u} = 0$ on ∂D , we obtain

$$\int_D \operatorname{curl} \operatorname{curl} \mathbf{u} \cdot \mathbf{w}_h \, \mathrm{d}x = \int_D \operatorname{curl} \mathbf{u} \cdot \operatorname{curl} \mathbf{w}_h \, \mathrm{d}x.$$

Combining the above two equations, we have

$$\int_{D} (\operatorname{curl} \operatorname{curl} \mathbf{u} - \boldsymbol{\psi}_{h}) \cdot \mathbf{w}_{h} \, \mathrm{d}x = \int_{D} \operatorname{curl}(\mathbf{u} - \mathbf{v}_{h}) \cdot \operatorname{curl} \mathbf{w}_{h} \, \mathrm{d}x$$

Hence we have that

$$\left| \int_{D} (\operatorname{curl} \operatorname{curl} \mathbf{u} - \boldsymbol{\psi}_{h}) \cdot \mathbf{w}_{h} \, \mathrm{d}x \right| \leq \|\operatorname{curl} \mathbf{u} - \operatorname{curl} \mathbf{v}_{h}\| \|\operatorname{curl} \mathbf{w}_{h}\| \\ \leq \alpha(h) \|\operatorname{curl} \mathbf{u} - \operatorname{curl} \mathbf{v}_{h}\| \|\mathbf{w}_{h}\|$$

and

$$\|\mathbf{w}_{h}\|^{2} = \int_{D} (\boldsymbol{\mu}_{h} + \operatorname{curl}\operatorname{curl}\mathbf{u}) \cdot \mathbf{w}_{h} \, \mathrm{d}x + \int_{D} (\boldsymbol{\psi}_{h} - \operatorname{curl}\operatorname{curl}\mathbf{u}) \cdot \mathbf{w}_{h} \, \mathrm{d}x$$
$$\leq \|\boldsymbol{\mu}_{h} + \operatorname{curl}\operatorname{curl}\mathbf{u}\| \, \|\mathbf{w}_{h}\| + \alpha(h) \|\operatorname{curl}\mathbf{u} - \operatorname{curl}\mathbf{v}_{h}\| \, \|\mathbf{w}_{h}\|.$$

From this inequality, we have that

$$\begin{aligned} \|\operatorname{curl}\operatorname{curl}\mathbf{u} - \boldsymbol{\psi}_h\| &\leq \|\operatorname{curl}\operatorname{curl}\mathbf{u} + \boldsymbol{\mu}_h\| + \|\mathbf{w}_h\| \\ &\leq 2\|\operatorname{curl}\operatorname{curl}\mathbf{u} + \boldsymbol{\mu}_h\| + \alpha(h)\|\operatorname{curl}\mathbf{u} - \operatorname{curl}\mathbf{v}_h\|, \end{aligned}$$

and thus,

$$\begin{split} \inf_{\substack{(\mathbf{v}_h, \psi_h) \in \mathcal{V}_h}} \left(\| \operatorname{curl} \mathbf{u} - \operatorname{curl} \mathbf{v}_h \| + \| \operatorname{curl} \operatorname{curl} \mathbf{u} - \psi_h \| \right) \\ & \leq (1 + \alpha(h)) \inf_{\mathbf{v}_h \in Y_h} \| \operatorname{curl} \mathbf{u} - \operatorname{curl} \mathbf{v}_h \| + 2 \inf_{\boldsymbol{\mu}_h \in X_h} \| \operatorname{curl} \operatorname{curl} \mathbf{u} + \boldsymbol{\mu}_h \|. \end{split}$$

Combination of this inequality and (23) completes the proof.

Theorem 5 Let $(\mathbf{u}, \boldsymbol{\phi})$ and $(\mathbf{u}_h, \boldsymbol{\phi}_h)$ be the solutions of (18) and (21), respectively. Furthermore, assume that $\operatorname{curl}^i \mathbf{u} \in H^s(D)^3$, i = 1, 2, 3 and s is the same as in Lemma 3. Then there exists a constant C independent of the mesh size h such that

$$\|\operatorname{curl} \mathbf{u} - \operatorname{curl} \mathbf{u}_h\| + \|\operatorname{curl}^2 \mathbf{u} - \phi_h\| \le Ch^{s-1} \left(\|\mathbf{u}\|_{H^s(D)^3} + \|\operatorname{curl} \mathbf{u}\|_{H^s(D)^3} \right).$$
(27)

Proof We define the Fortin operator $\Pi_h : Y \to Y_h$ such that $\Pi_h \mathbf{u}$ is the first component \mathbf{u}_h of (7) with $(\mathbf{f}, \boldsymbol{\phi}_h)$ replaced by $(\operatorname{curl} \mathbf{u}, \operatorname{curl} \boldsymbol{\phi}_h)$ (see Sec. 3 of [2]). According to Lemma 6, we have that

$$\|\mathbf{u} - \Pi_h \mathbf{u}\|_{H(\operatorname{curl})} \le C \inf_{\mathbf{v}_h \in U_{0,h}} \|\mathbf{u} - \mathbf{v}_h\|_{H(\operatorname{curl})}$$

Using Lemma 3, we have that

$$\left\|\operatorname{curl} \mathbf{u} - \operatorname{curl} \Pi_h \mathbf{u}\right\| \le Ch^s \left(\|\mathbf{u}\|_{H^s(D)^3} + \|\operatorname{curl} \mathbf{u}\|_{H^s(D)^3}\right).$$

For $\mathbf{w} = \text{curl}\,\text{curl}\,\mathbf{u}$, we define the H(curl;D) orthogonal projection $P_h: H(\text{curl};D) \to U_h$ such that

$$(\operatorname{curl}(\mathbf{w} - P_h \mathbf{w}), \operatorname{curl} \boldsymbol{\phi}_h) + (\mathbf{w} - P_h \mathbf{w}, \boldsymbol{\phi}_h) = 0 \text{ for all } \boldsymbol{\phi}_h \in U_h.$$

Then Cea's Lemma leads to the following estimate (see Sec. 7.2 of [12])

$$\|\mathbf{w} - P_h \mathbf{w}\|_{H(\operatorname{curl})} = \inf_{\boldsymbol{\mu}_h \in U_h} \|\mathbf{w} - \boldsymbol{\mu}_h\|_{H(\operatorname{curl})}.$$

Letting $\phi_h = \operatorname{grad} \xi_h$ for $\xi_h \in S_h$, we find that $P_h \mathbf{w}$ is discrete divergence-free, i.e., $P_h \mathbf{w} \in X_h$. Thus we have that

$$\inf_{\boldsymbol{\mu}_h \in X_h} \|\operatorname{curl}^2 \mathbf{u} - \boldsymbol{\mu}_h\|_{H(\operatorname{curl})} \leq \inf_{\boldsymbol{\mu}_h \in U_h} \|\operatorname{curl}^2 \mathbf{u} - \boldsymbol{\mu}_h\|_{H(\operatorname{curl})}$$

From Lemma 3, we have that

$$\inf_{\boldsymbol{\mu}_h \in U_h} \|\operatorname{curl}^2 \mathbf{u} - \boldsymbol{\mu}_h\|_{H(\operatorname{curl})} \le Ch^s \left(\|\operatorname{curl}^2 \mathbf{u}\|_{H^s(D)^3} + \|\operatorname{curl}^3 \mathbf{u}\|_{H^s(D)^3} \right)$$

for some constants C independent of h. Using Theorem 4, we obtain that

$$\begin{aligned} \|\operatorname{curl} \mathbf{u} - \operatorname{curl} \mathbf{u}_{h}\| + \|\operatorname{curl}^{2} \mathbf{u} - \boldsymbol{\phi}_{h}\| \\ &\leq C \left(1 + \frac{C_{1}}{h}\right) h^{s} \left(\|\mathbf{u}\|_{H^{s}(D)^{3}} + \|\operatorname{curl} \mathbf{u}\|_{H^{s}(D)^{3}}\right) \\ &\quad + Ch^{s} \left(\|\operatorname{curl}^{2} \mathbf{u}\|_{H^{s}(D)^{3}} + \|\operatorname{curl}^{3} \mathbf{u}\|_{H^{s}(D)^{3}}\right) \\ &\leq Ch^{s-1} \left(\|\mathbf{u}\|_{H^{s}(D)^{3}} + \|\operatorname{curl} \mathbf{u}\|_{H^{s}(D)^{3}}\right) \\ &\quad + Ch^{s} \left(\|\operatorname{curl}^{2} \mathbf{u}\|_{H^{s}(D)^{3}} + \|\operatorname{curl}^{3} \mathbf{u}\|_{H^{s}(D)^{3}}\right) \\ &\leq Ch^{s-1} \left(\|\mathbf{u}\|_{H^{s}(D)^{3}} + \|\operatorname{curl} \mathbf{u}\|_{H^{s}(D)^{3}}\right). \end{aligned}$$

We now use the theory from Section 2.3 to prove an L^2 -norm convergence result for $\mathbf{u} - \mathbf{u}_h$. Of course, since we are using edge elements of the first kind [14], the convergence rate in L^2 cannot be better than the convergence rate in H(curl). So nothing would be gained from a duality argument.

Theorem 6 Under the conditions of Theorem 5, there exists a constant C independent of \mathbf{u} , \mathbf{u}_h and h such that

$$\|\mathbf{u} - \mathbf{u}_h\| \le Ch^{s-1} \left(\|\mathbf{u}\|_{H^s(D)^3} + \|\operatorname{curl} \mathbf{u}\|_{H^s(D)^3} \right).$$

Proof Let $\mathbf{v}_h \in Y_h$ be the first component of the solution of (7) with $\mathbf{f} = \operatorname{curl} \operatorname{curl} \mathbf{u}$ so that \mathbf{u} is the exact solution. By Lemma 6 and Lemma 3, we have that

$$\|\mathbf{u} - \mathbf{v}_h\|_{H(\operatorname{curl};D)} \le Ch^s \left(\|\mathbf{u}\|_{H^s(D)^3} + \|\operatorname{curl} \mathbf{u}\|_{H^s(D)^3} \right).$$
(28)

Then, using the triangle inequality and the discrete Friedrichs inequality in Lemma 5, we have that

$$\begin{aligned} \|\mathbf{u} - \mathbf{u}_h\| &\leq \|\mathbf{u} - \mathbf{v}_h\| + \|\mathbf{v}_h - \mathbf{u}_h\| \\ &\leq \|\mathbf{u} - \mathbf{v}_h\| + C\|\operatorname{curl}(\mathbf{v}_h - \mathbf{u}_h)\| \\ &\leq C(\|\mathbf{u} - \mathbf{v}_h\|_{H(\operatorname{curl};D)} + \|\operatorname{curl}(\mathbf{u} - \mathbf{u}_h)\|). \end{aligned}$$

Combination of Theorem 5 and (28) completes the proof.

4 The Quad-curl Eigenvalue Problem

The quad-curl eigenvalue problem is to find λ and **u** such that

$$(\operatorname{curl})^4 \mathbf{u} = \lambda \mathbf{u}$$
 in D , (29a)

$$\operatorname{div} \mathbf{u} = 0 \qquad \qquad \text{in } D, \qquad (29b)$$

$$\mathbf{u} \times \boldsymbol{\nu} = 0 \qquad \qquad \text{on } \partial D, \qquad (29c)$$

$$(\operatorname{curl} \mathbf{u}) \times \boldsymbol{\nu} = 0 \qquad \text{on } \partial D. \qquad (29d)$$

We call λ a quad-curl eigenvalue and **u** the associated eigenfunction. Due to the well-posedness of the quad-curl problem, we can define an operator $T: L^2(D)^3 \to L^2(D)^3$ such that $T\mathbf{f} = \mathbf{u}$ for (12). It is obvious that T is selfadjoint. Furthermore, because of the compact imbedding of V into $L^2(D)^3$, T is a compact operator.

The weak formulation is to find $(\lambda, \mathbf{u}) \in \mathbb{R} \times V$ such that

$$\mathcal{C}(\mathbf{u}, \mathbf{q}) = \lambda(\mathbf{u}, \mathbf{q}) \quad \text{for all } \mathbf{q} \in V.$$
(30)

It is clear that λ is an eigenvalue satisfying (30) if and only if $\mu = 1/\lambda$ is an eigenvalue of T.

Lemma 8 There is an infinite discrete set of quad-curl eigenvalues $\lambda_j > 0, j = 1, 2, ...$ and corresponding eigenfunctions $\mathbf{u}_j \in V$, $\mathbf{u}_j \neq \mathbf{0}$ such that (30) is satisfied and $0 < \lambda_1 \leq \lambda_2 \leq ...$ Furthermore

$$\lim_{j \to \infty} \lambda_j = \infty.$$

The eigenfunctions satisfy $(\mathbf{u}_j, \mathbf{u}_l)_{L^2(D)^3} = 0$ if $j \neq l$.

Proof Applying the Hilbert-Schmidt theory (see, for example, Theorem 2.36 of [12]), we immediately have the above theorem.

Using the Helmholtz decomposition, we can easily obtain the following result. Thus we omit its proof.

Lemma 9 The quad-curl eigenvalues coincide with the non-zero eigenvalues of the following problem. Find $(\lambda, \mathbf{u}) \in \mathbb{R} \times H_0^2(\text{curl}; D)$ such that

$$\mathcal{C}(\mathbf{u},\mathbf{q}) = \lambda(\mathbf{u},\mathbf{q}) \quad \text{for all } \mathbf{q} \in H^2_0(\text{curl};D).$$
(31)

Then the quad-curl eigenvalue problem in mixed form can be written as: Find $\lambda \in \mathbb{R}$, $(\mathbf{0}, \mathbf{0}) \neq (\mathbf{u}, \boldsymbol{\phi}) \in W \times X$ satisfying

 $a(\boldsymbol{\phi}, \mathbf{v}) + b(\mathbf{v}, \mathbf{u}) = 0, \quad \text{for all } \mathbf{v} \in X,$ (32a)

$$b(\boldsymbol{\phi}, \mathbf{q}) = -\lambda(\mathbf{u}, \mathbf{q}), \text{ for all } \mathbf{q} \in Y.$$
 (32b)

It is easy to see that if $(\lambda, (\mathbf{u}, \boldsymbol{\phi}))$ is an eigenpair of (32), then $\lambda B \mathbf{u} = \mathbf{u}, \mathbf{u} \neq \mathbf{0}$, i.e., (λ, \mathbf{u}) is a quad-curl eigenpair. If $\lambda B \mathbf{u} = \mathbf{u}, \mathbf{u} \neq \mathbf{0}$, then there exists $\boldsymbol{\phi} \in X$ such that $(\lambda, (\mathbf{u}, \boldsymbol{\phi}))$ is an eigenpair of (32).

The mixed finite element method for the quad-curl problem can be stated as follows. For $\mathbf{f} \in H(\operatorname{div}^0; D)$, find $A_h \mathbf{f} \in Y_h$, $B_h \mathbf{f} \in X_h$ such that

$$a(A_h \mathbf{f}, \mathbf{v}_h) + b(\mathbf{v}_h, B_h \mathbf{f}) = 0,$$
 for all $\mathbf{v}_h \in X_h,$ (33a)

$$b(A_h \mathbf{f}, \mathbf{q}_h) = -(\mathbf{f}, \mathbf{q}_h),$$
 for all $\mathbf{q}_h \in Y_h.$ (33b)

From Theorems 5 and 6, we have that

$$\|(B - B_h)\mathbf{f}\| \le Ch^{s-1} \left(\|B\mathbf{f}\|_s + \|\operatorname{curl} B\mathbf{f}\|_s\right),\tag{34}$$

$$\|(A - A_h)\mathbf{f}\| \le Ch^{s-1} \left(\|B\mathbf{f}\|_s + \|\operatorname{curl} B\mathbf{f}\|_s \right).$$
(35)

In the following, we assume that $\|\mathbf{u}\|_s \leq C \|\mathbf{f}\|$ and $\|\operatorname{curl} \mathbf{u}\|_s \leq C \|\mathbf{f}\|$ holds for the quad-curl problem and some constant C. Note that when s = 2, the above regularity results are a consequence of Lemma 1 and the fact that \mathbf{u} is the solution of the quad-curl problem. Thus we have the norm convergence

$$\lim_{h \to 0} ||B - B_h|| = 0 \text{ and } \lim_{h \to 0} ||A - A_h|| = 0.$$

The discrete eigenvalue problem is to find $\lambda_h \in \mathbb{R}$, $(\mathbf{u}_h, \boldsymbol{\phi}_h) \in Y_h \times X_h$ such that

$$a(\boldsymbol{\phi}_h, \mathbf{v}_h) + b(\mathbf{v}_h, \mathbf{u}_h) = 0,$$
 for all $\mathbf{v}_h \in X_h,$ (36a)

$$b(\boldsymbol{\phi}_h, \mathbf{q}_h) = -\lambda_h(\mathbf{u}_h, \mathbf{q}_h), \qquad \text{for all } \mathbf{q}_h \in Y_h.$$
(36b)

Theorem 7 The discrete quad-curl eigenvalues of (36) coincide with the nonzero eigenvalues of the following problem. Find $\lambda_h \in \mathbb{R}$ and $\mathbf{u}_h \in U_{0,h}, \phi_h \in U_h$ such that

$$(\boldsymbol{\phi}_h, \mathbf{v}_h) - (curl \mathbf{v}_h, curl \mathbf{u}_h) = 0,$$
 for all $\mathbf{v}_h \in U_h,$ (37a)

$$(curl \boldsymbol{\phi}_h, curl \mathbf{q}_h) = -\lambda_h(\mathbf{u}_h, \mathbf{q}_h), \quad for \ all \ \mathbf{q}_h \in U_{0,h}.$$
 (37b)

Proof We write

$$\mathbf{u}_h = \mathbf{u}_h^0 + \nabla \varphi_h, \quad \mathbf{u}_h^0 \in Y_h, \varphi_h \in S_h.$$

Letting $\mathbf{q}_h = \nabla \xi_h$ in (37b), we have that

$$0 = (\phi_h, \operatorname{curl} \nabla \xi_h) = -\lambda_h(\mathbf{u}_h, \nabla \xi_h) = \lambda_h(\nabla \varphi_h, \nabla \xi_h) \quad \text{for all } \xi_h \in S_h$$

Then either $\lambda_h = 0$ or $(\nabla \varphi_h, \nabla \xi_h) = 0$ for all $\xi_h \in S_h$. It is clear that if $\lambda_h \neq 0$, we have $(\nabla \varphi_h, \nabla \xi_h) = 0$ for all $\xi_h \in S_h$, which implies $\nabla \varphi_h = 0$. Thus $\mathbf{u}_h = \mathbf{u}_h^0$, which is discrete divergence-free.

Let μ be a non-zero eigenvalue of B. The ascent α of $\mu - B$ is defined as the smallest integer such that $N((\mu - B)^{\alpha}) = N((\mu - B)^{\alpha+1})$, where Ndenotes the null space. Let $m = \dim N((\mu - B)^{\alpha})$ be the algebraic multiplicity of μ . The geometric multiplicity of μ is $\dim N(\mu - B)$. Note that since B is self-adjoint, the two multiplicities are same. Then there are m eigenvalues of $B_h, \mu_1(h), \ldots, \mu_m(h)$ such that

$$\lim_{h \to 0} \mu_j(h) = \mu, \quad \text{for } j = 1, \dots, m.$$
(38)

Theorem 8 Let $\lambda = 1/\mu$ be an exact quad-curl eigenvalue with multiplicity m and $\lambda_{j,h}, j = 1, \ldots, m$ be the corresponding computed eigenvalues. Then we have that

$$|\lambda - \lambda_{j,h}| \le Ch^{2s-2} \tag{39}$$

for some constant C.

Proof From (34) and (35), we have that

$$||(B - B_h)|| \le Ch^{s-1}$$
 and $||(A - A_h)|| \le Ch^{s-1}$.

Then the theorem is verified using Theorem 11.1 of [1].

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