# **Differentiation and Integration**

You think you know when you learn, are more sure when you can write, even more when you can teach, but certain when you can program.

Alan J. Perlis



#### **Topics to Be Discussed**

• This unit requires the knowledge of differentiation and integration in calculus. • The following topics will be presented: **Forward difference, backward difference and** central difference methods for differentiation. **Richardson extrapolation technique >**Trapezoid, Simpson's 3-point and iterative methods for numerical integration **>**Romberg's method for numerical integration.

#### Numerical Differentiation: 1/14

• If function f(x) is complex, computing f'(x) is difficult and approximation may be needed. • Suppose we wish to compute  $f(x_i)$ . We may choose a  $x_{i+1} > x_i$  and approximate  $f(x_i)$  by the slope  $(f(x_{i+1})-f(x_i))/(x_{i+1}-x_i)$  — forward difference.  $(X_i)$  $f(x_{i+1})$  $f(x_{i+1}) - f(x_i)$  $x_{i+1} - x_i$  $f(x_i)$ 3  $\boldsymbol{x_i}$  $x_{i+1}$ 

#### Numerical Differentiation: 2/14

• Or, we may choose a  $x_{i-1} < x_i$  and use the slope  $(f(x_i)-f(x_{i-1}))/(x_i-x_{i-1})$  as an approximation of  $f(x_i)$  — *backward difference*.



#### Numerical Differentiation: 3/14

• Or, we may choose  $x_{i-1} < x_i$  and  $x_{i+1} > x_i$ , both close to  $x_i$ , and use slope  $(f(x_{i+1})-f(x_{i-1}))/(x_{i+1}-x_{i-1})$ as an approximation of  $f'(x_i)$  — *central difference*.



5

#### Numerical Differentiation: 4/14

- Forward difference, backward difference and central difference methods can be viewed as the use of an *interpolating polynomial of degree 1* that interpolates two chosen points and uses its slope for the derivative of *f*(*x*).
- If we can use interpolating polynomial of degree 1, why don't we use degree 2, degree 3, etc?
- Yes, of course we can. But, higher degree means more points. Normally, three (*i.e.*, degree 2) may be sufficient.

#### Numerical Differentiation: 5/14

- Suppose we wish to compute  $f'(x_i)$ . We may choose  $x_{i+1}$  and  $x_{i+2}$ , both close to  $x_i$ , and evaluate  $f_i$ ,  $f_{i+1}$  and  $f_{i+2}$ .
- Then, we have three points  $(x_i, f_i)$ ,  $(x_{i+1}, f_{i+1})$  and  $(x_{i+2}, f_{i+2})$ .
- An interpolating polynomial of degree 2,  $P_2(x)$ , can be found, and, use  $P_2'(x_i)$  as an approximation of  $f(x_i)$ . See next slide.
- Newton divided difference is a simple tool for this purpose.

#### Numerical Differentiation: 6/14



#### Numerical Differentiation: 7/14

# • Given $x_i < x_{i+1} < x_{i+2}$ , divided difference yields $P_2(x)$ as follows:

 $P_2(x) = f[x_i] + f[x_i, x_{i+1}](x - x_i) + f[x_i, x_{i+1}, x_{i+2}](x - x_i)(x - x_{i+1})$ 

#### • Differentiating $P_2(x)$ yields:

 $P'_{2}(x) = f[x_{i}, x_{i+1}] + f[x_{i}, x_{i+1}, x_{i+2}](2x - (x_{i} + x_{i+1}))$ 

• Plugging  $x_i$  into  $P_2'(x)$  as an approximation of  $f(x_i)$  yields:

$$P_{2}'(x_{i}) = f[x_{i}, x_{i+1}] + f[x_{i}, x_{i+1}, x_{i+2}](x_{i} - x_{i+1})$$

#### Numerical Differentiation: 8/14

- •Normally,  $x_i$ ,  $x_{i+1}$  and  $x_{i+2}$  are *equally spaced* (*i.e.*,  $x_{i+1} x_i = x_{i+2} x_{i+1} = \Delta$ ). This condition makes computation easier.
- •Note that  $f[x_i, x_{i+1}]$  and  $f[x_{i+1}, x_{i+2}]$  are computed as follows:

$$f[x_{i}, x_{i+1}] = \frac{f(x_{i+1}) - f(x_{i})}{\Delta} \quad f[x_{i+1}, x_{i+2}] = \frac{f(x_{i+2}) - f(x_{i+1})}{\Delta}$$

•As a result,  $f[x_i, x_{i+1}, x_{i+2}]$  is

$$f[x_i, x_{i+1}, x_{i+2}] = \frac{f[x_{i+1}, x_{i+2}] - f[x_i, x_{i+1}]}{x_{i+2} - x_i} = \frac{f_{i+2} - 2f_{i+1} + f_i}{2\Delta^2}$$

10

#### Numerical Differentiation: 9/14

• Recall that  $P_2'(x)$  is

$$P_{2}'(x_{i}) = f[x_{i}, x_{i+1}] + f[x_{i}, x_{i+1}, x_{i+2}](x_{i} - x_{i+1})$$

• Plugging  $f[x_i, x_{i+1}]$ ,  $f[x_i, x_{i+1}, x_{i+2}]$  and  $x_i - x_{i+1} = -\Delta$ into  $P_2'(x)$ , we have

$$P_{2}'(x_{i}) = \frac{1}{2\Delta} \left(-3f_{i} + 4f_{i+1} - f_{i+2}\right)$$

• This is the *three-point forward difference*.

#### Numerical Differentiation: 10/14

• If the three chosen points are  $x_{i-2} < x_{i-1} < x_i$ , the interpolating polynomial of degree 2,  $P_2(x)$ , is

 $P_2(x) = f[x_{i-2}] + f[x_{i-2}, x_{i-1}](x - x_{i-2}) + f[x_{i-2}, x_{i-1}, x_i](x - x_{i-2})(x - x_{i-1})$ 

# • Differentiating $P_2(x)$ yields: $P'_2(x) = f[x_{i-2}, x_{i-1}] + f[x_{i-2}, x_{i-1}, x_i](2x - (x_{i-2} + x_{i-1}))$ • Plugging $x_i$ into $P'_2(x)$ yields

 $P_{2}'(x_{i}) = f[x_{i-2}, x_{i-1}] + f[x_{i-2}, x_{i-1}, x_{i}](2x_{i} - (x_{i-2} + x_{i-1}))$ 

#### Numerical Differentiation: 11/14

- If  $x_{i-2}$ ,  $x_{i-1}$  and  $x_i$  are equally spaced (*i.e.*,  $x_{i-1}$   $x_{i-2}$ =  $\Delta$  and  $x_i$  -  $x_{i-1} = \Delta$ ), we have
- $2x_i (x_{i-2} + x_{i-1}) = (x_i x_{i-1}) + (x_i x_{i-2}) = \Delta + 2\Delta = 3\Delta$ **P**<sub>2</sub>'(x) becomes:

$$P_{2}'(x_{i}) = \frac{1}{2\Delta} (f_{i-2} - 4f_{i-1} + 3f_{i})$$

• This is the *three-point backward difference*.



#### Numerical Differentiation: 12/14

• Forward difference uses  $x_i < x_{i+1} < x_{i+2}$ , and backward difference uses  $x_{i-2} < x_{i-1} < x_i$ . Is there a "central" difference that uses  $x_{i-1} < x_i < x_{i+1}$ ?

• You certainly can do this because the  $P_2(x)$  is:

 $P_2(x) = f[x_{i-1}] + f[x_{i-1}, x_i](x - x_{i-1}) + f[x_{i-1}, x_i, x_{i+1}](x - x_{i-1})(x - x_i)$ 

•Some calculations yield the following (exercise):

$$P_{2}'(x_{i}) = \frac{f_{i+1} - f_{i-1}}{2\Delta}$$

• This does not involve  $f_i$  and is the same as the 2point central difference.

## Numerical Differentiation: 13/14

#### •Exercises:

•• If the equally spaced data points are  $x_{i-1} < x_i$  $\langle x_{i+1},$  show that  $P_2(x_i)$  is the following:  $P_2'(x_i) = \frac{f_{i+1} - f_{i-1}}{2\Lambda}$ **Given a parabola** $f(x) = ax^2 + bx + c$  and three points s- $\Delta$ , s and s+ $\Delta$ , show that  $f'(s) = \frac{f(s + \Delta) - f(s - \Delta)}{2\Delta}$ Now we know that the three-point central difference does not make much sense for equally spaced data points.

## Numerical Differentiation: 14/14

#### •Examples:

 $\Box f(x) = e^x, x = 1 \text{ and } \Delta = 0.001$  $\Box f(x) = e^x \text{ and } f(1) = e^1 = 2.718281828$ 

Method	Result
Forward Difference	<b>2.71964142</b>
<b>Backward Difference</b>	<b>2.71962268</b>
<b>Central Difference</b>	<b>2.71828</b> 228
<b>3-point Forward</b>	<b>2.71828091</b>
<b>3-point Backward</b>	<b>2.71828091</b>

## **Richardson Extrapolation: 1/4**

- Richardson has an *extrapolation* scheme that can make the central different method more accurate.
- This extrapolation scheme is very similar to the divided difference scheme:



## **Richardson Extrapolation: 2/4**

 Richardson extrapolation is computed row-byrow. The 0-th entry is a central difference with reduced step size.

initial value of each row.



#### **Richardson Extrapolation: 3/4**

Here is the algorithm of Richardson's method. *x*: input, *n*: number of rows, and ∆: initial step size that will be halved for each row.

DO i = 0, n  

$$d_{i,0} = \frac{f(x+\Delta) - f(x-\Delta)}{2\Delta}$$

$$d_{i,0} = \frac{f(x+\Delta) - f(x-\Delta)}{2\Delta}$$

$$d_{i,0} = 0, i-1$$

$$d_{i,j+1} = d_{i,j} + \frac{d_{i,j} - d_{i-1,j}}{4^{j+1} - 1}$$

$$d_{i,j+1} = d_{i,j} + \frac{d_{i,j} - d_{i-1,j}}{4^{j+1} - 1}$$

$$d_{i,j+1} = d_{i,j} + \frac{d_{i,j} - d_{i-1,j}}{4^{j+1} - 1}$$

$$d_{i,j+1} = d_{i,j} + \frac{d_{i,j} - d_{i-1,j}}{4^{j+1} - 1}$$

$$d_{i,j+1} = d_{i,j} + \frac{d_{i,j} - d_{i-1,j}}{4^{j+1} - 1}$$

$$d_{i,j+1} = d_{i,j} + \frac{d_{i,j} - d_{i-1,j}}{4^{j+1} - 1}$$

$$d_{i,j+1} = d_{i,j} + \frac{d_{i,j} - d_{i-1,j}}{4^{j+1} - 1}$$

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$$d_{i,j+1} = d_{i,j} + \frac{d_{i,j} - d_{i-1,j}}{4^{j+1} - 1}$$

$$d_{i,j+1} = d_{i,j} + \frac{d_{i,j} - d_{i-1,j}}{4^{j+1} - 1}$$

$$d_{i,j+1} = d_{i,j} + \frac{d_{i,j} - d_{i-1,j}}{4^{j+1} - 1}$$

#### **Richardson Extrapolation: 4/4**

• Let  $f(x)=e^x$ . Compute f'(x) at x=1 with n=3 (3 rows) and  $\Delta=1$  (initial step size=1).



## Numerical Integration: 1/4

•Numerical integration means computing the following in a numerical way (*i.e.*, a value rather than a closed form formula).



In fact, the above cannot be integrated precisely in closed form for most functions *f(x)*. As a result, numerical integration is needed.

#### Numerical Integration: 2/4

- One way to compute the integration is to (1) choose a number of data points  $(x_0=a, f_0), (x_1, f_1), \dots, (x_n=b, f_n)$  and (2) find an interpolating polynomial of degree  $n, P_n(x)$ .
- Then, we use  $P_n(x)$  to replace f(x):

$$\int_{a}^{b} f(x) dx \approx \int_{a}^{b} P_{n}(x) dx$$

• Since  $P_n(x)$  is a polynomial, its integration is easy to compute. But, this is a tedious and inefficient procedure.

## Numerical Integration: 3/4

- In fact, one may divide the interval [a,b] into subintervals for better approximation instead of using the whole interval [a,b].
- If the subintervals are small enough, degree 1 or 2 interpolating polynomials may be good enough.



## Numerical Integration: 4/4

- While the subintervals do not have to be of equal length, equally spaced points do make computation easier.
- Therefore, if we choose to divide the interval [a,b] into n subintervals, each of which has length  $\Delta = (b-a)/n$ , the division points are  $x_0 = a$ ,  $x_1 = x_0 + \Delta$ ,  $x_2 = x_0 + 2\Delta$  ...,  $x_i = x_0 + i\Delta$ , ...,  $x_n = x_0 + n\Delta = b$ .
- The integration becomes:

$$\int_{a}^{b} f(x) dx = \sum_{i=0}^{n-1} \int_{x_{i}}^{x_{i}+\Delta} f(x) dx$$

#### **Trapezoid Rule: 1/5**

The trapezoid bounded by (a,0), (a, f(a)), (b, f(b)) and (b,0) has an area close to the area below y=f(x) bounded by x=a and x=b.



#### **Trapezoid Rule: 2/5**

- If [*a*,*b*] is divided into *n* equally spaced intervals with length  $\Delta = (b-a)/n$ . Then,  $x_i = x_0 + i\Delta$ .
- The area  $A_i$  of the *i*-th  $(0 \le i \le n-1)$  trapezoid is  $(f_i + f_{i+1})\Delta/2$ .
- The approximation is the sum of all  $A_i$ 's.



#### **Trapezoid Rule: 3/5**

• Therefore, the sum of all areas  $A_0, A_1, ..., A_{n-1}$  as an approximation of the integration is easy to compute.

$$\int_{a}^{b} f(x)dx \approx A_{0} + A_{1} + \dots + A_{n-1}$$

$$= \frac{\Delta}{2}(f_{0} + f_{1}) + \frac{\Delta}{2}(f_{1} + f_{2}) + \dots + \frac{\Delta}{2}(f_{n-1} + f_{n})$$

$$= \frac{\Delta}{2}[f_{0} + 2(f_{1} + f_{2} + \dots + f_{n-1}) + f_{n}]$$

$$= \Delta \left[\frac{f_{0} + f_{n}}{2} + \sum_{i=1}^{n-1} f_{i}\right]$$
27

## **Trapezoid Rule: 4/5**

• Recall the following trapezoid rule:

$$\int_{a}^{b} f(x)dx \approx \Delta \left[\frac{f_{0} + f_{n}}{2} + \sum_{i=1}^{n-1} f_{i}\right]$$

• The following is a possible implementation:

```
! INPUT: a, b, n

\Delta = (b-a)/n \quad ! \text{ step size}
x = a + \Delta \quad ! x1 \text{ here}
s = 0.0 \quad ! \text{ sum of } f(x_1) \text{ to } f(x_{n-1})
DO i = 1, n-1 ! cumulate each term

s = s + f(x)
x = x + \Delta
END DO

Result = ((f(a)+f(b))/2+s)*\Delta
```

#### **Trapezoid Rule: 5/5**

- Consider the integration of  $e^x$  from 0 to 1. The correct result is  $e^1 e^0 = 1.718282$ .
- If [0,1] is divided into 4 subintervals, we have n=4 and  $\Delta=0.25$ .



#### Simpson's 3-Point Rule: 1/12

Trapezoid rule is an approximation of f(x) on [x<sub>i</sub>,x<sub>i+1</sub>] with a line (*i.e.*, degree 1 polynomial).
Simpson's 3-point rule approximates f(x) on [x<sub>i</sub>,x<sub>i+2</sub>] with a parabola (*i.e.*, degree 2 polynomial) that interpolates (x<sub>i</sub>, f<sub>i</sub>), (x<sub>i+1</sub>, f<sub>i+1</sub>) and (x<sub>i+2</sub>, f<sub>i+2</sub>).



#### Simpson's 3-Point Rule: 2/12

• Since the  $P_2(x)$  that interpolates  $(x_i, f_i), (x_{i+1}, f_{i+1})$ and  $(x_{i+2}, f_{i+2})$  can easily be found, we have

$$\int_{x_i}^{x_{i+2}} f(x) dx \approx \int_{x_i}^{x_{i+2}} P_2(x) dx$$

- Since  $P_2(x)$  is a degree 2 polynomial, its integration is very easy.
- How do we find this  $P_2(x)$ ? Should we use Lagrange or Newton divided difference?
- It turns out we don't need these tools!

#### Simpson's 3-Point Rule: 3/12

- We still use equally spaced subintervals.
- Since translation does not change integration result, we translate x<sub>i+1</sub> to 0 so that x<sub>i</sub>=-∆ and x<sub>i+2</sub>=∆. This will simplify our calculation.
- Let the interpolating polynomial be  $c+bx+ax^2$



#### Simpson's 3-Point Rule: 4/12

• The integration of the polynomial  $c+bx+ax^2$ from - $\Delta$  to  $\Delta$  is easy to compute as follows:



#### Simpson's 3-Point Rule: 5/12

How to compute *c* and *a* in P<sub>2</sub>(x) = c+bx+ax<sup>2</sup>?
From the setup, we have

$$\begin{array}{lll} f_i &=& P_2(-\Delta) = c - b\Delta + a\Delta^2 & c \text{ is known} \\ f_{i+1} &=& P_2(0) = c \\ f_{i+2} &=& P_2(\Delta) = c + b\Delta + a\Delta^2 \end{array}$$

•Adding the first and the third equations together and solving for *a* yield the following:

$$a = \frac{1}{2\Delta^2} (f_i - 2f_{i+1} + f_{i+2})$$

#### Simpson's 3-Point Rule: 6/12

#### • What do we have now?

$$\int_{-\Delta}^{\Delta} f(x) dx \approx (2\Delta) \left[ c + \frac{a}{3} \Delta^2 \right]$$

$$c = f_{i+1}$$

$$a = \frac{1}{2\Delta^2} \left( f_i - 2f_{i+1} + f_{i+2} \right)$$

Plugging *a* and *c* into the integration yields:

$$\int_{-\Delta}^{\Delta} f(x) dx \approx \frac{\Delta}{3} \left[ f_i + 4 f_{i+1} + f_{i+2} \right]$$

•Note that this result does not depend on the  $x_i$ 's!

#### Simpson's 3-Point Rule: 7/12

Compute ∫<sub>0</sub><sup>1</sup> e<sup>x</sup> dx = e<sup>1</sup> - e<sup>0</sup> = 1.718281828...
 We need 3 equally spaced points x<sub>0</sub>=0, x<sub>1</sub>=0.5 and x<sub>2</sub>=1. Thus, Δ=0.5.



#### Simpson's 3-Point Rule: 8/12

- For a general integration problem, we need to divide [*a*,*b*] into an *even number* of subintervals, and apply Simpson's 3-point rule to two consecutive ones.
- More precisely, apply Simpson's 3-point rule to  $[x_0,x_1,x_2], [x_2,x_3,x_4], [x_4,x_5,x_6], ..., [x_{n-2},x_{n-1},x_n].$
- Note that Simpson's 3-point rule only depends on the  $f_i$ 's and the length of subinterval  $\Delta$ .
- For convenience, we shall use n = 2m, where *n* is the number of subintervals, and  $\Delta = (b-a)/n$ .

#### Simpson's 3-Point Rule: 9/12

- Consider the following results from integrating two consecutive subintervals.
- Odd indices *f*<sub>i</sub>'s have coefficient 4  $\frac{\Delta}{3}$  $[x_0, x_1, x_2]$ even indices  $f_i$ 's have coefficient 2  $[x_2, x_3, x_4]$  $4f_{5}$  $[x_4, x_5, x_6]$  $+ f_{6}$  $f_0$  and  $f_{2m}$  appear exactly once  $[x_{2m-4}, x_{2m-3}, x_{2m-2}] \quad \frac{\Delta}{3} [f_{2m-4} + 4f_{2m-3}]$  $[x_{2m-2}, x_{2m-1}, x_{2m}] \qquad \frac{\Delta}{3} [f_{2m-2} + 4f_{2m-1}]$ 38

#### Simpson's 3-Point Rule: 10/12

• The following is a computation scheme:



#### Simpson's 3-Point Rule: 11/12



Result = (f(a)+f(b)+4\*odd

+ 2\*even) \* $\Delta/3_{40}$ 

#### Simpson's 3-Point Rule: 12/12

• Integrate  $1/(1+x^2)$  from 0 to 1. The answer is 0.78539816...



## **Iterative Methods**

- •An iterative method increases the number of subdivisions until the process converges.
- Since trapezoid and Simpson 3-point rules are simple, we shall look at how they can be modified to become "*iterative*."
- We may start with a coarse subdivision of [*a*,*b*], and compute the integration.
- If two successive integration results are close to each other, stop.
- Otherwise, refine the subdivision and do again!

#### **Iterative Trapezoid Method: 1/4**

- Initially, we have one subinterval [a,b], and  $\Delta = b a$ .
- The integration is  $I_0 = \Delta \times (f(a) + f(b))/2$
- In the next iteration, the length of each subinterval is halved (*i.e.*,  $\Delta = \Delta/2$ ) and the number of subintervals is doubled.
- Thus, if the previously computed result *I<sub>n</sub>* with *n* subintervals is not very different from the newly computed result *I<sub>2n</sub>* with 2*n* subintervals, then stop. Otherwise, start the next iteration.

#### **Iterative Trapezoid Method: 2/4**

- Trapezoid method has a simple relationship between  $I_n$  and  $I_{2n}$ .
- It uses the following formula:

$$\int_{a}^{b} f(x)dx \approx \Delta \left[\frac{f_{0} + f_{n}}{2} + \sum_{i=1}^{n-1} f_{i}\right]$$

Only need to update this sum!

• Let  $K_n$  be the previous sum, then  $K_{2n}$  can be obtained by adding new values.



#### **Iterative Trapezoid Method: 3/4**

$\int^1 1 \pi$		$\pi/4 \approx 0.785398163$			
$\int_0 \frac{1}{1+x^2} dx \approx \frac{1}{4}$		Δ=0.5	Δ=0.25	Δ=0.125	
	0	1			
	0.125			0.984615384	
	0.25		0.94117647		
	0.375			0.876712328	
	0.5	0.8			
	0.625			0.719101123	
	0.75		0.64		
	0.875	(		0.566371681	
	1	0.5			
	Prev. Sum	0	0.8	2.381176471	
<b>←</b>	New Sum	0.8	1.581176471	3.146800518	
f(0) + f(1)	This Sum	0.8	2.381176471	5.527976989	
$\frac{f(0) + f(1)}{2} = 0.75$	Integration	0.775	0.782794117	0.784747123 45	

#### **Iterative Trapezoid Method: 4/4**

#### • The following is a possible algorithm:

! Initialization	DO
! Int - integration	$\Delta 2 = \Delta/2$
! This - new integration	$x = a + \Delta 2$
! Prev - previous sum	Next = 0
! Next - new sum	DO i = 1, Intervals
	Next = Next + $f(x)$
Fixed = (f(a) + f(b))/2	$\mathbf{x} = \mathbf{x} + \Delta$
Int = Fixed	END DO
Prev = 0	This = (Fixed+Prev+Next) $\Delta 2$
$\Delta$ = b-a	IF ( This - Int  < $\varepsilon$ ) EXIT
Intervals = 1	Prev = Next
	Int = This
	$\Delta = \Delta 2$

END DO

```
Intervals = Intervals*2
```

#### Iterative Simpson Method: 1/3

- Simpson method can also be made iterative.
- •All newly added points have odd indices!
- •All original points have *even* indices!



#### **Iterative Simpson Method: 2/3**



#### Iterative Simpson Method: 3/3

```
! Initialization

! Integrate over [a,b]

! Extra = f(a)+f(b)

\Delta = (b-a)/2

Fixed = f(a)+f(b)

Even = 0

Odd = f(a+\Delta)

Int = (Fixed+4*Odd)*\Delta/3

Intervals = 2
```

```
DO
  New Even = Even + Odd
  New Odd = 0
  \Lambda 2 = \Lambda / 2
  x = a + \Lambda 2
  DO i = 1, Intervals
     New Odd = New Odd + f(x)
     \mathbf{x} = \mathbf{x} + \mathbf{A}
  END DO
  New Int = (Fixed+4*New Odd+
               2*New Even)*\Delta 2/3
  IF (|New_Int - Int| < \varepsilon) EXIT
  Even = New Even
  Odd = New_Odd
  Int = New Int
  Intervals=Intervals+Intervals
  \Lambda = \Lambda 2
                                   49
END DO
```

## **Romberg's Method: 1/4**

- •Romberg's method for integration is similar to Richardson's method for differentiation.
- Romberg's method extrapolates the results from two successive values computed with the iterative trapezoid (or Simpson) method.



#### Romberg's Method: 2/4

- Romberg's method requires an update from  $I_n$  to  $I_{2n}$ , where  $I_k$  is the integration from k intervals.
- $I_n$  is computed as follows:  $I_n = \Delta_n \left[ \frac{f_0 + f_n}{2} + \sum_{i=1}^{n-1} f_i \right]$ •  $I_{2n}$  is computed as  $I_{2n} = \Delta_{2n} \left[ \frac{f_0 + f_1}{2} + (original) + (new) \right]$

• Since  $\Delta_{2n} = \Delta_n/2$ , we have

$$I_{2n} = I_n / 2 + \Delta_{2n} \times (new)$$

## Romberg Method: 3/4



#### **Romberg Method: 4/4**

#### • The following is an example:



# The End