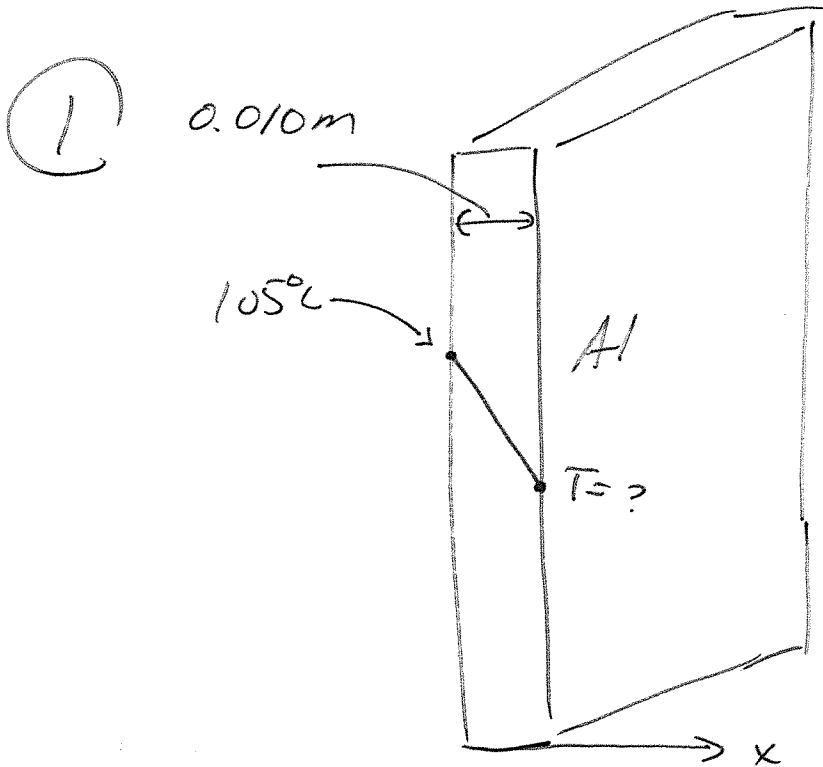


Final Exam
CM3110
Fall 2019

①



Fourier's Law

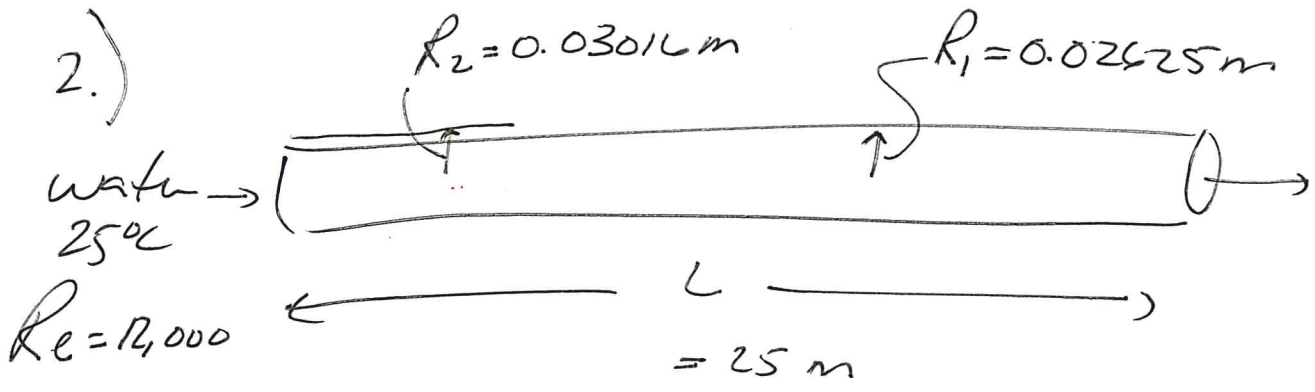
$$\frac{q}{A} = 3.4 \times 10^3 \text{ W/m}^2 = -k \frac{dT}{dx} = -k \left(\frac{T_w - 105}{0.010 \text{ m}} \right)$$

$$k = 206 \frac{\text{W}}{\text{mK}}$$

$$34 \frac{\text{W}}{\text{m}^2} = (105 - T_w) \left(206 \frac{\text{W}}{\text{mK}} \right)$$

$$\boxed{T_w = 104.8^\circ \text{C}} \quad = 378.0 \text{ K}$$

3



- a) $\langle V \rangle$
- b) ΔP

a) $Re = \frac{\rho \langle V \rangle D}{\mu}$

$12000 = \frac{(997.08 \frac{\text{kg}}{\text{m}^3}) \langle V \rangle (2)(0.02625\text{ m})}{8.937 \times 10^{-4} \frac{\text{kg}}{\text{m}\cdot\text{s}}}$

$\langle V \rangle = 0.204873 \frac{\text{m}}{\text{s}} \quad \Bigg| \quad = 0.20 \frac{\text{m}}{\text{s}}$
 (2 sig figs)

b) ΔP ? ① find f from correlation

② then $f = \frac{\Delta P D}{2L\rho\langle V \rangle^2}$

What is f ? Use simplified correlation

(3)

$$f = \frac{1.02}{4} (\log(R_e))^{-2.5}$$

$$= \frac{1.02}{4} (\log(12,000))^{-2.5}$$

$$= 7.5874 \times 10^{-3}$$

$$f = 7.6 \times 10^{-3}$$

0.0076
~ 0.01 if read from chart

(looks reasonable from Moody plot)

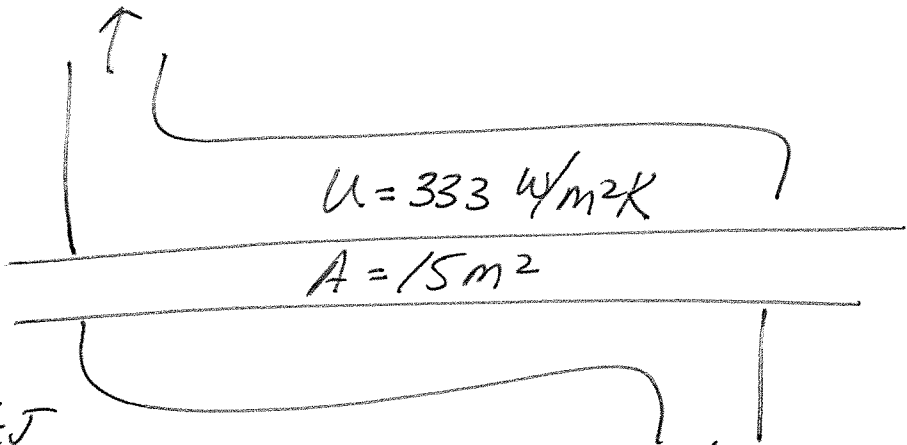
$$7.5874 \times 10^{-3} = \frac{\Delta P (\cancel{\text{ft}})(0.02625 \text{ m})}{(\cancel{\text{ft}})(25 \text{ m})(997.08 \frac{\text{kg}}{\text{m}^3})}$$

$$\times \left(\frac{0.204873 \text{ m}}{5} \right)^2$$

$$\Delta P = 302.423 \frac{\text{kg}}{\text{m s}^2} \frac{\text{Pa m}^2 \cancel{\text{m}} \cancel{\text{s}^2}}{\cancel{\text{m}} \frac{\text{kg}}{\text{m}^3} \cancel{\text{m}}} \left(\frac{14.694 \text{ PSI}}{1.01325 \times 10^5 \text{ Pa}} \right)$$

$$\Delta P = 0.044 \text{ PSI}$$

3)



$$\dot{m} = 1.3 \frac{\text{kg}}{\text{s}}$$

$$C_p = 4.092 \frac{\text{kJ}}{\text{kgK}}$$

25°C

↑ Silthmax

$$C_p' = 12.2 \frac{\text{kJ}}{\text{kgK}}$$

142°C

$$\dot{m}' = 2.1 \frac{\text{kg}}{\text{s}}$$

Heat Exchanger Effectiveness
(inlet temperatures known)

$$\begin{aligned} (mC_p)_{\text{cold}} &= \left(\frac{1.3 \text{ kg}}{\text{s}} \right) \left(4.092 \frac{\text{kJ}}{\text{kgK}} \right) \frac{\text{kW}}{\text{K}} \\ &= 5.32 \frac{\text{kW}}{\text{K}} \leftarrow \text{minimum fluid} \end{aligned}$$

$$\begin{aligned} (mC_p)_{\text{HOT}} &= \left(\frac{2.1 \text{ kg}}{\text{s}} \right) \left(12.2 \frac{\text{kJ}}{\text{kgK}} \right) \frac{\text{kW}}{\text{K}} \\ &= 25.62 \frac{\text{kW}}{\text{K}} \end{aligned}$$

Obtain ϵ from chart

$$NTU = \frac{UA}{(mC_p)_{min}}$$

$$= \frac{\left(333 \frac{W}{m^2K}\right) (15 m^2)}{5.32 \times 10^3 \frac{W}{K}}$$

$$NTU = 0.94$$

$$\frac{(mC_p)_{min}}{(mC_p)_{max}} = \frac{5.32}{25.62} = 0.21$$

Reading chart: $\epsilon = 0.58$

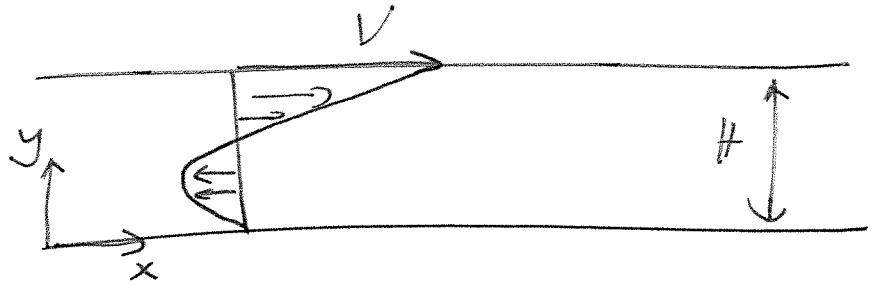
$$Q = (mC_p)_{min} \epsilon (T_{hi} - T_{ci})$$

$$= \left(5.32 \frac{kW}{K}\right) (0.58) (142 - 25) K$$

$$= 360 kW$$

4)

a.



$$U_y = 0$$

$$U_z = 0$$

Steady

incompressible $\Rightarrow \rho = \text{constant}$

$$\underline{g} = \begin{pmatrix} 0 \\ -g \\ 0 \end{pmatrix}_{xyz} \approx \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}_{xyz} \quad (\text{neglect})$$

$$0 = -\frac{\partial p(x)}{\partial x} + \mu \frac{d^2 U_x}{dy^2}$$

BC: $x=0 \quad P=P_0 \quad y=0 \quad U_x=0$
 $x=L \quad P=P_L \quad y=H \quad U_x=V$

The Equation of Continuity and the Equation of Motion in Cartesian, cylindrical, and spherical coordinates

CM3110 Fall 2011 Faith A. Morrison

Continuity Equation, Cartesian coordinates

$$\frac{\partial \rho}{\partial t} + v_x \frac{\partial \rho}{\partial x} + v_y \frac{\partial \rho}{\partial y} + v_z \frac{\partial \rho}{\partial z} + \rho \left(\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} \right) = 0$$

Continuity Equation, cylindrical coordinates

$$\frac{\partial \rho}{\partial t} + \frac{1}{r} \frac{\partial(\rho r v_r)}{\partial r} + \frac{1}{r} \frac{\partial(\rho v_\theta)}{\partial \theta} + \frac{\partial(\rho v_z)}{\partial z} = 0$$

Continuity Equation, spherical coordinates

$$\frac{\partial \rho}{\partial t} + \frac{1}{r^2 \sin \theta} \frac{\partial(\rho r^2 \sin \theta v_r)}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial(\rho v_\theta \sin \theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial(\rho v_\phi \sin \theta)}{\partial \phi} = 0$$

Equation of Motion for an incompressible fluid, 3 components in Cartesian coordinates

$$\rho \left(\frac{\partial v_x}{\partial t} + v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_x}{\partial y} + v_z \frac{\partial v_x}{\partial z} \right) = -\frac{\partial P}{\partial x} + \left(\frac{\partial^2 \tau_{xx}}{\partial x^2} + \frac{\partial^2 \tau_{xy}}{\partial x \partial y} + \frac{\partial^2 \tau_{xz}}{\partial x \partial z} \right) + \rho g_x$$

$$\rho \left(\frac{\partial v_y}{\partial t} + v_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} + v_z \frac{\partial v_y}{\partial z} \right) = -\frac{\partial P}{\partial y} + \left(\frac{\partial^2 \tau_{xy}}{\partial x \partial y} + \frac{\partial^2 \tau_{yy}}{\partial y^2} + \frac{\partial^2 \tau_{yz}}{\partial y \partial z} \right) + \rho g_y$$

$$\rho \left(\frac{\partial v_z}{\partial t} + v_x \frac{\partial v_z}{\partial x} + v_y \frac{\partial v_z}{\partial y} + v_z \frac{\partial v_z}{\partial z} \right) = -\frac{\partial P}{\partial z} + \left(\frac{\partial^2 \tau_{xz}}{\partial x \partial z} + \frac{\partial^2 \tau_{yz}}{\partial y \partial z} + \frac{\partial^2 \tau_{zz}}{\partial z^2} \right) + \rho g_z$$

Equation of Motion for an incompressible fluid, 3 components in cylindrical coordinates

$$\rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} + v_z \frac{\partial v_r}{\partial z} \right) = -\frac{\partial P}{\partial r} + \left(\frac{1}{r} \frac{\partial(\tau_{rr})}{\partial r} + \frac{1}{r} \frac{\partial(\tau_{r\theta})}{\partial \theta} + \frac{1}{r} \frac{\partial(\tau_{rz})}{\partial z} \right) + \rho g_r$$

$$\rho \left(\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + v_\theta \frac{\partial v_\theta}{\partial \theta} + v_z \frac{\partial v_\theta}{\partial z} \right) = -\frac{1}{r} \frac{\partial P}{\partial \theta} + \left(\frac{1}{r^2} \frac{\partial^2 \tau_{r\theta}}{\partial r^2} + \frac{1}{r} \frac{\partial^2 \tau_{\theta\theta}}{\partial \theta^2} + \frac{1}{r} \frac{\partial^2 \tau_{\theta z}}{\partial \theta \partial z} \right) + \rho g_\theta$$

$$\rho \left(\frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + v_\theta \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} \right) = -\frac{\partial P}{\partial z} + \left(\frac{1}{r} \frac{\partial(\tau_{rz})}{\partial r} + \frac{1}{r} \frac{\partial(\tau_{\theta z})}{\partial \theta} + \frac{\partial^2 \tau_{zz}}{\partial z^2} \right) + \rho g_z$$

Equation of Motion for an incompressible fluid, 3 components in spherical coordinates

$$\rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_r}{\partial \phi} + v_r \frac{v_\theta^2}{r} + \frac{v_\phi^2}{r} \right) = -\frac{\partial P}{\partial r} + \left(\frac{1}{r} \frac{\partial(\tau_{rr})}{\partial r} + \frac{1}{r} \frac{\partial(\tau_{r\theta})}{\partial \theta} + \frac{1}{r} \frac{\partial(\tau_{r\phi})}{\partial \phi} + \frac{1}{r} \frac{\partial(\tau_{\theta r})}{\partial \theta} + \frac{1}{r} \frac{\partial(\tau_{\phi r})}{\partial \phi} \right) + \rho g_r$$

$$\rho \left(\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + v_\theta \frac{\partial v_\theta}{\partial \theta} + \frac{v_\phi}{r} \frac{\partial v_\theta}{\partial \phi} + v_r \frac{v_\theta}{r} - \frac{v_\phi^2 \cot \theta}{r} \right) = -\frac{1}{r} \frac{\partial P}{\partial \theta} + \left(\frac{1}{r^2} \frac{\partial^2 \tau_{r\theta}}{\partial r^2} + \frac{1}{r} \frac{\partial^2 \tau_{\theta\theta}}{\partial \theta^2} + \frac{1}{r} \frac{\partial^2 \tau_{\theta\phi}}{\partial \theta \partial \phi} + \frac{1}{r} \frac{\partial^2 \tau_{\phi\theta}}{\partial \phi \partial \theta} \right) + \rho g_\theta$$

$$\rho \left(\frac{\partial v_\phi}{\partial t} + v_r \frac{\partial v_\phi}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\phi}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi} + v_r \frac{v_\phi}{r} + \frac{v_\theta v_\phi \cot \theta}{r} \right) = -\frac{1}{r \sin \theta} \frac{\partial P}{\partial \phi} + \left(\frac{1}{r^2} \frac{\partial(\tau_{r\phi})}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial(\tau_{\theta\phi})}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial(\tau_{\phi\phi})}{\partial \phi} + \frac{1}{r} \frac{\partial(\tau_{\phi r})}{\partial r} + \frac{1}{r} \frac{\partial(\tau_{\phi\theta})}{\partial \theta} \right) + \rho g_\phi$$

$\frac{dv_r}{dt}$
 $\frac{dv_\theta}{dt}$
 $\frac{dv_\phi}{dt}$

Equation of Motion for incompressible, Newtonian fluid (Navier-Stokes equation), 3 components in Cartesian coordinates

$$\rho \left(\frac{\partial v_x}{\partial t} + v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_x}{\partial y} + v_z \frac{\partial v_x}{\partial z} \right) = -\frac{\partial P}{\partial x} + \mu \left(\frac{\partial^2 v_x}{\partial x^2} + \frac{\partial^2 v_x}{\partial y^2} + \frac{\partial^2 v_x}{\partial z^2} \right) + \rho g_x$$

$$\rho \left(\frac{\partial v_y}{\partial t} + v_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} + v_z \frac{\partial v_y}{\partial z} \right) = -\frac{\partial P}{\partial y} + \mu \left(\frac{\partial^2 v_y}{\partial x^2} + \frac{\partial^2 v_y}{\partial y^2} + \frac{\partial^2 v_y}{\partial z^2} \right) + \rho g_y$$

$$\rho \left(\frac{\partial v_z}{\partial t} + v_x \frac{\partial v_z}{\partial x} + v_y \frac{\partial v_z}{\partial y} + v_z \frac{\partial v_z}{\partial z} \right) = -\frac{\partial P}{\partial z} + \mu \left(\frac{\partial^2 v_z}{\partial x^2} + \frac{\partial^2 v_z}{\partial y^2} + \frac{\partial^2 v_z}{\partial z^2} \right) + \rho g_z$$

Equation of Motion for incompressible, Newtonian fluid (Navier-Stokes equation), 3 components in cylindrical coordinates

$$\rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} + v_z \frac{\partial v_r}{\partial z} \right) = -\frac{\partial P}{\partial r} + \mu \left(\frac{1}{r} \frac{\partial(r v_r)}{\partial r} + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} - \frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial^2 v_r}{\partial z^2} \right) + \rho g_r$$

$$\rho \left(\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + v_\theta \frac{\partial v_\theta}{\partial \theta} + v_z \frac{\partial v_\theta}{\partial z} \right) = -\frac{1}{r} \frac{\partial P}{\partial \theta} + \mu \left(\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial(r v_\theta)}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} + \frac{\partial^2 v_\theta}{\partial z^2} \right) + \rho g_\theta$$

$$\rho \left(\frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + v_\theta \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} \right) = -\frac{\partial P}{\partial z} + \mu \left(\frac{1}{r} \frac{\partial}{\partial r} \left(\frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2} \right) + \rho g_z$$

Equation of Motion for incompressible, Newtonian fluid (Navier-Stokes equation), 3 components in spherical coordinates

$$\rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_r}{\partial \phi} + v_r \frac{v_\theta^2}{r} + \frac{v_\phi^2}{r} \right) = -\frac{\partial P}{\partial r} + \mu \left(\frac{\partial}{\partial r} \left(\frac{1}{r^2} \frac{\partial(r^2 v_r)}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial v_r}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_r}{\partial \phi^2} - \frac{2}{r^2} \frac{\partial v_\theta}{\sin \theta} \frac{\partial \theta}{\partial \theta} - \frac{2}{r^2} \frac{\partial v_\phi}{\sin \theta} \frac{\partial \theta}{\partial \phi} \right) + \rho g_r$$

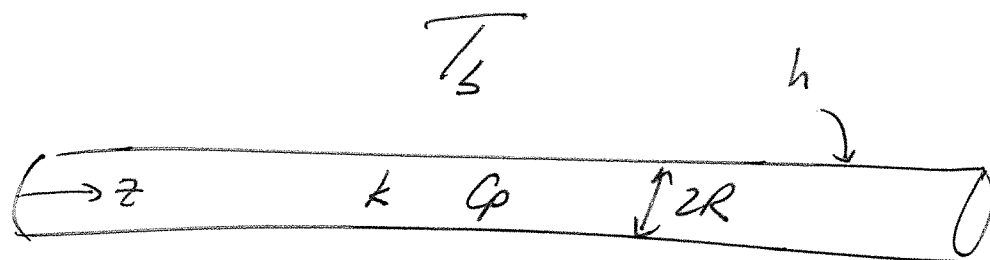
$$\rho \left(\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + v_\theta \frac{\partial v_\theta}{\partial \theta} + \frac{v_\phi}{r} \frac{\partial v_\theta}{\partial \phi} + v_r \frac{v_\theta}{r} - \frac{v_\phi^2 \cot \theta}{r} \right) = -\frac{1}{r} \frac{\partial P}{\partial \theta} + \mu \left(\frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial v_\theta}{\partial \theta} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial v_\theta}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_\theta}{\partial \phi^2} - \frac{2}{r^2} \frac{\partial v_r}{\sin \theta} \frac{\partial \theta}{\partial \theta} + \frac{2}{r^2} \frac{\partial v_\phi}{\sin \theta} \frac{\partial \theta}{\partial \phi} \right) + \rho g_\theta$$

$$\rho \left(\frac{\partial v_\phi}{\partial t} + v_r \frac{\partial v_\phi}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\phi}{\partial \theta} + \frac{v_\phi}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi} + v_r \frac{v_\phi}{r} + \frac{v_\theta v_\phi \cot \theta}{r} \right) = -\frac{1}{r \sin \theta} \frac{\partial P}{\partial \phi} + \mu \left(\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial v_\phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(\frac{1}{\sin \theta} \frac{\partial v_\phi}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 v_\phi}{\partial \phi^2} + \frac{2}{r^2} \frac{\partial v_r}{\sin \theta} \frac{\partial \theta}{\partial \theta} - \frac{2}{r^2} \frac{\partial v_\theta}{\sin \theta} \frac{\partial \theta}{\partial \phi} \right) + \rho g_\phi$$

Note: the r-component of the Navier-Stokes equation in spherical coordinates may be simplified by adding $0 = \frac{1}{r} \nabla \cdot \mathbf{r}$ to the component shown above. This term is zero due to the continuity equation (mass conservation). See Bird et al.

References:
 1. R. B. Bird, W. E. Stewart, and E. N. Lightfoot, *Transport Phenomena*, 2nd edition, Wiley: NY, 2002.
 2. R. B. Bird, R. C. Armstrong, and O. Hassager, *Dynamics of Polymeric Fluids: Volume 1 Fluid Mechanics*, Wiley: NY, 1987.

b)



⑧

$S_0 \frac{W}{m^3}$ due to electric current

$$T(r) = ?$$

steady

$$\underline{v} = 0$$

⊖ symmetry

$$\text{long} \Rightarrow \frac{\partial^2 T}{\partial z^2} = 0$$

$$0 = \frac{k}{r} \frac{d}{dr} \left(r \frac{dT}{dr} \right) + S_0$$

BC: $r=0$ $T = \text{finite}$ or $\frac{\partial T}{\partial r} = 0$
 $r=R$ Newton's law of cooling

$$\Rightarrow -k \frac{dT}{dr} = \frac{q_r}{A} = (T(R) - T_b)(h)$$

The Equation of Energy

in Cartesian, cylindrical, and spherical coordinates for Newtonian fluids of constant density, with source term S . Source could be electrical energy due to current flow, chemical energy, etc. Two cases are presented: the general case where thermal conductivity may be a function of temperature (vector flux $\vec{q} = q/A$ appears in the equations); and the more usual case, where thermal conductivity is constant.

Fall 2013 Faith A. Morrison, Michigan Technological University

Microscopic energy balance, in terms of flux; Gibbs notation

$$\rho \hat{c}_p \left(\frac{\partial T}{\partial t} + \underline{v} \cdot \nabla T \right) = -\nabla \cdot \vec{q} + S$$

Microscopic energy balance, in terms of flux; Cartesian coordinates

$$\rho \hat{c}_p \left(\frac{\partial T}{\partial t} + v_x \frac{\partial T}{\partial x} + v_y \frac{\partial T}{\partial y} + v_z \frac{\partial T}{\partial z} \right) = - \left(\frac{\partial q_x}{\partial x} + \frac{\partial q_y}{\partial y} + \frac{\partial q_z}{\partial z} \right) + S$$

Microscopic energy balance, in terms of flux; cylindrical coordinates

$$\rho \hat{c}_p \left(\frac{\partial T}{\partial t} + v_r \frac{\partial T}{\partial r} + v_\theta \frac{\partial T}{\partial \theta} + v_z \frac{\partial T}{\partial z} \right) = - \left(\frac{1}{r} \frac{\partial (r \hat{q}_r)}{\partial r} + \frac{1}{r} \frac{\partial \hat{q}_\theta}{\partial \theta} + \frac{\partial \hat{q}_z}{\partial z} \right) + S$$

Microscopic energy balance, in terms of flux; spherical coordinates

$$\rho \hat{c}_p \left(\frac{\partial T}{\partial t} + v_r \frac{\partial T}{\partial r} + v_\theta \frac{\partial T}{\partial \theta} + v_\phi \frac{\partial T}{\partial \phi} \right) = - \left(\frac{1}{r^2} \frac{\partial (r^2 \hat{q}_r)}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial (\hat{q}_\theta \sin \theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial \hat{q}_\phi}{\partial \phi} \right) + S$$

Fourier's law of heat conduction, Gibbs notation: $\vec{q} = -k \nabla T$

Fourier's law of heat conduction, Cartesian coordinates:

$$\begin{pmatrix} \hat{q}_x \\ \hat{q}_y \\ \hat{q}_z \end{pmatrix}_{xyz} = \begin{pmatrix} -k \frac{\partial T}{\partial x} \\ -k \frac{\partial T}{\partial y} \\ -k \frac{\partial T}{\partial z} \end{pmatrix}_{xyz}$$

Fourier's law of heat conduction, cylindrical coordinates:

$$\begin{pmatrix} \hat{q}_r \\ \hat{q}_\theta \\ \hat{q}_z \end{pmatrix}_{xyz} = \begin{pmatrix} -k \frac{\partial T}{\partial r} \\ -k \frac{\partial T}{\partial \theta} \\ -k \frac{\partial T}{\partial z} \end{pmatrix}_{r\theta z}$$

Fourier's law of heat conduction, spherical coordinates:

$$\begin{pmatrix} \hat{q}_r \\ \hat{q}_\theta \\ \hat{q}_\phi \end{pmatrix}_{xyz} = \begin{pmatrix} -k \frac{\partial T}{\partial r} \\ -k \frac{\partial T}{\partial \theta} \\ -k \frac{\partial T}{\partial \phi} \end{pmatrix}_{r\theta\phi}$$

The Equation of Energy

for systems with constant k

Microscopic energy balance, constant thermal conductivity; Gibbs notation

$$\rho \hat{c}_p \left(\frac{\partial T}{\partial t} + \underline{v} \cdot \nabla T \right) = k \nabla^2 T + S$$

Microscopic energy balance, constant thermal conductivity; Cartesian coordinates

$$\rho \hat{c}_p \left(\frac{\partial T}{\partial t} + v_x \frac{\partial T}{\partial x} + v_y \frac{\partial T}{\partial y} + v_z \frac{\partial T}{\partial z} \right) = k \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2} \right) + S$$

Microscopic energy balance, constant thermal conductivity; cylindrical coordinates

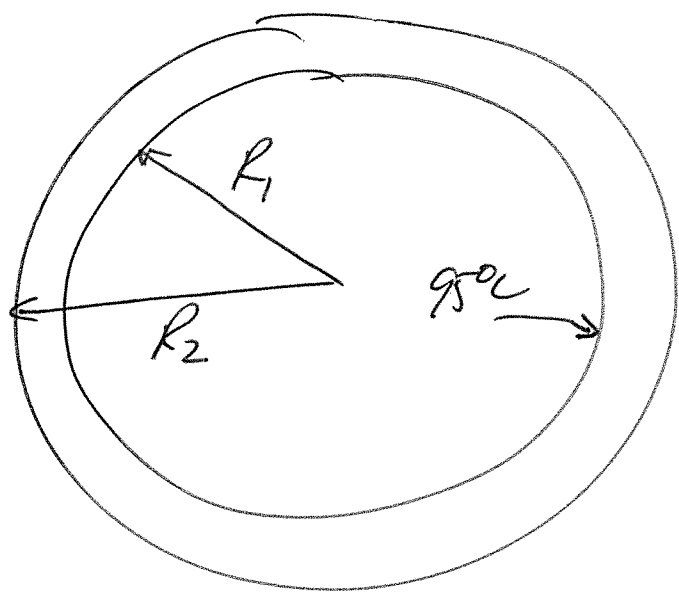
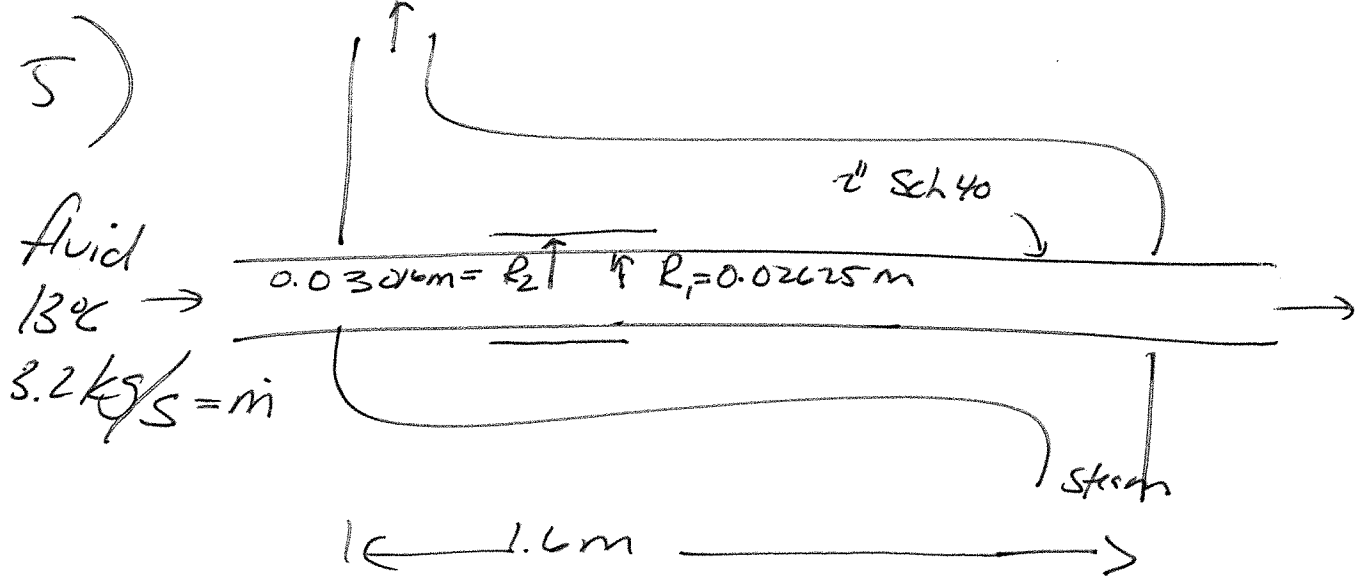
$$\rho \hat{c}_p \left(\frac{\partial T}{\partial t} + v_r \frac{\partial T}{\partial r} + v_\theta \frac{\partial T}{\partial \theta} + v_z \frac{\partial T}{\partial z} \right) = k \left(\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial T}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 T}{\partial \theta^2} + \frac{\partial^2 T}{\partial z^2} \right) + S$$

Microscopic energy balance, constant thermal conductivity; spherical coordinates

$$\rho \hat{c}_p \left(\frac{\partial T}{\partial t} + v_r \frac{\partial T}{\partial r} + v_\theta \frac{\partial T}{\partial \theta} + v_\phi \frac{\partial T}{\partial \phi} \right) = k \left(\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial T}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial T}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 T}{\partial \phi^2} \right) + S$$

steps
 $\nabla = 0$

9



Need to obtain h_{lm} from the literature data correlations (Sieder-Tate)

Turbulent

$$Nu = \frac{h_{lm} D}{k} = 0.027 Re^{0.8} Pr^{\frac{1}{3}} \left(\frac{\mu_b}{\mu_w} \right)^{0.14}$$

(need to check Re)

(11)

$$Re = \frac{\rho V D}{\mu} \quad \text{and } \langle v \rangle$$

$$\langle v \rangle = \frac{Q}{\pi R^2}$$

$$Q = \frac{m}{\rho} = \left(\frac{3.2 \text{ kg}}{s} \right) \left(\frac{m^3}{1022 \text{ kg}} \right)$$

$$= 0.00313112 \frac{m^3}{s}$$

$$= 3.13 \times 10^{-3} \frac{m^3}{s}$$

$$\langle v \rangle = \frac{\left(0.00313112 \frac{m^3}{s} \right)}{\pi (0.02625 m)^2}$$

$$\langle v \rangle = 1.4464 \frac{m}{s}$$

$$Re = \frac{(1022 \frac{kg}{m^3}) (1.4464 \frac{m}{s}) (2) (0.02625 m)}{(8.3 \times 10^{-4} \frac{kg}{m \cdot s})}$$

$$Re = 93,502 \Rightarrow \text{turbulent}$$

(12)

$$Pr = \frac{C_p \mu}{k}$$

$$= \frac{\left(4.3 \frac{\text{kJ}}{\text{kgK}}\right) \left(8.3 \times 10^{-4} \frac{\text{kg}}{\text{ms}}\right) \left(\frac{103 \text{ J}}{\text{kg}}\right)}{0.605 \frac{\text{J}}{\text{smK}}}$$

$$Pr = 5.899$$

$$\frac{\mu_b}{\mu_w} = 1 \quad (\mu \text{ does not vary w/ } T)$$

$$Nu_{lm} = 0.027 Re^{0.8} Pr^{\frac{1}{3}}$$

$$= (0.027)(93502)^{0.8} (5.899)^{\frac{1}{3}}$$

$$Nu_{lm} = 462.324$$

$$Nu = \frac{h_{em} D}{k}$$

(B)

$$h_{lm} = \frac{k}{D} Nu$$

$$= \frac{\left(0.605 \frac{W}{mK}\right) (462.324)}{(2)(0.02425m)}$$

$$= 5327.73 \frac{W}{m^2K}$$

$$h_{lm} = 5300 \frac{W}{m^2K}$$

no more than 2 sig figs

b) (BONUS)

MICRO E-BAR INSIDE:

$$\cancel{\Delta E_p} + \cancel{\Delta E_k} + \Delta H = Q_{in} + \cancel{W_{s, on}}$$

negligible

$$Q_{in} = \sum_{in} \dot{m}_i \hat{H}_i - \sum_{out} \dot{m}_i \hat{H}_i$$

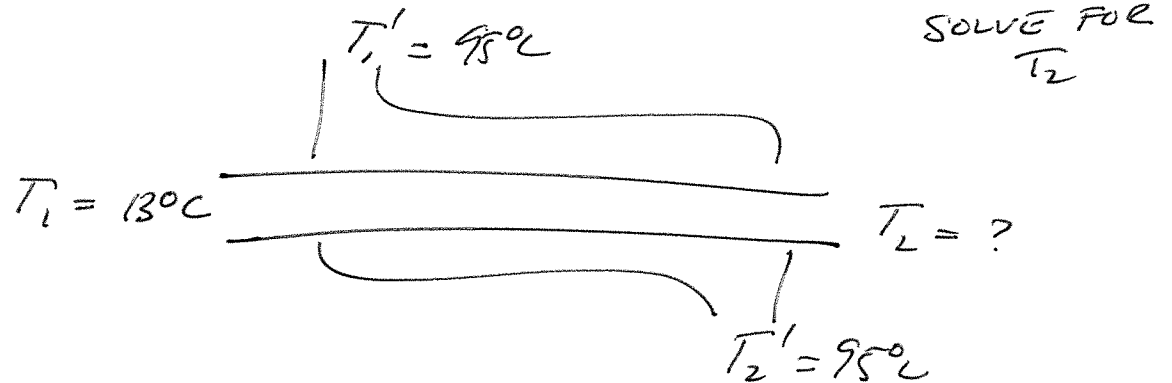
$$= \dot{m} C_p (T_{out} - T_{in})$$

no shaft

From part a) \rightarrow

MACRO
E-BAL \rightarrow (14)

$$Q_{in} = h_{lm} A \Delta T_{lm} = \dot{m} C_p (T_2 - T_1)$$



$$A = \pi D L = \pi (2)(0.02625 \text{ m})(1.6 \text{ m})$$
$$= 0.26389 \text{ m}^2$$

$$\Delta T_{lm} = \frac{82 - (95 - T_2)}{\ln\left(\frac{82}{95 - T_2}\right)} = \frac{\dot{m} C_p}{h_{lm} A} (T_2 - 130^\circ\text{C})$$

$$\alpha = \frac{\dot{m} C_p}{h_{lm} A} = \frac{(3.2 \frac{\text{kg}}{\text{s}})(4.3 \frac{\text{kJ}}{\text{kg}\cdot\text{K}})(\frac{10^3 \text{ J}}{\text{kJ}})}{(5327.73 \frac{\text{W}}{\text{m}^2\cdot\text{K}})(0.26389 \text{ m}^2)}$$

$$\alpha = 9.78708$$

Algebra:

(15)

$$\frac{\cancel{(T_2 - 13)}}{\alpha \cancel{(T_2 - 13)}} = \ln\left(\frac{82}{95 - T_2}\right)$$

$$\frac{82}{95 - T_2} = e^{\frac{1}{\alpha}} = 1.1075778$$

$$95 - T_2 = 74.035$$

$$T_2 = 20.96^\circ\text{C}$$

$$T_2 = 21^\circ\text{C}$$