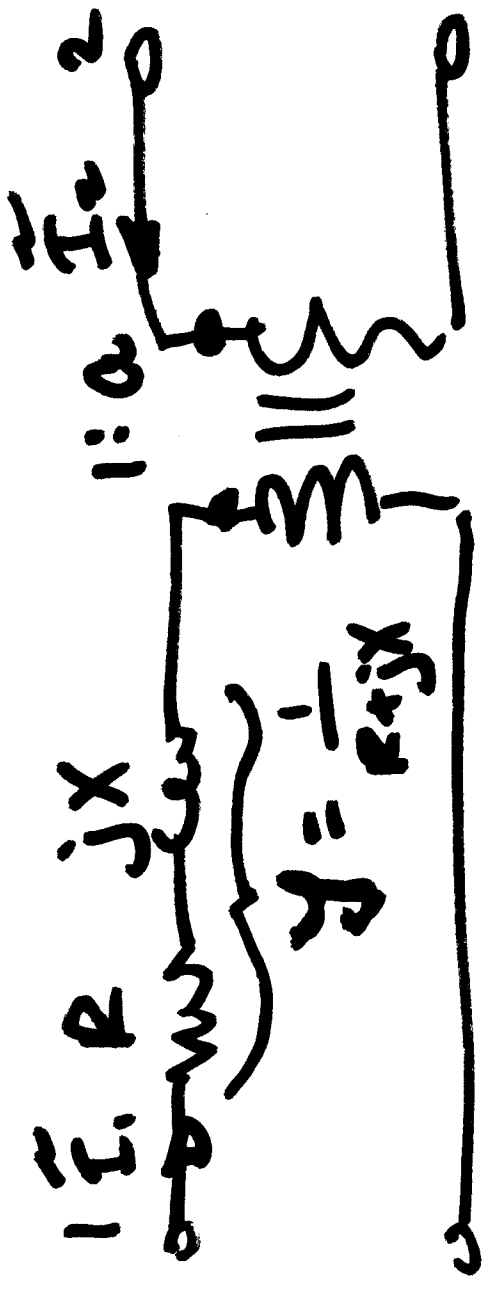


Topics for Today:

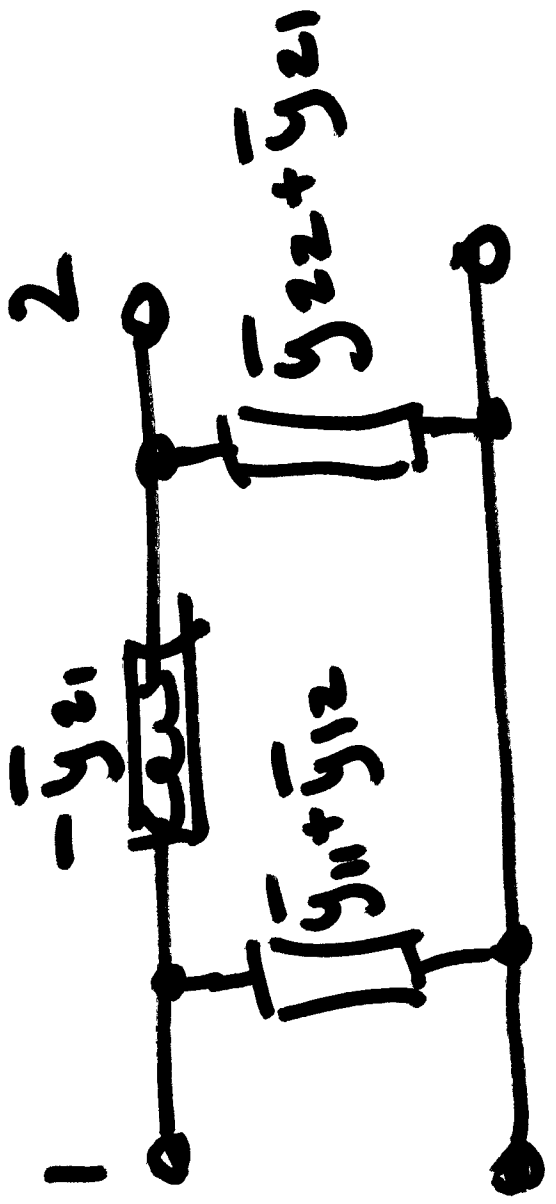
- Announcements
- Learning Center hrs TBA
- Office: EERC 614. Phone: 906.487.2857
- Recommended problems from Ch.3, solutions posted
- SYNCH homework due Oct 10th, 9am.
- Next: Transmission Line Parameters, Chapters 4,5,6

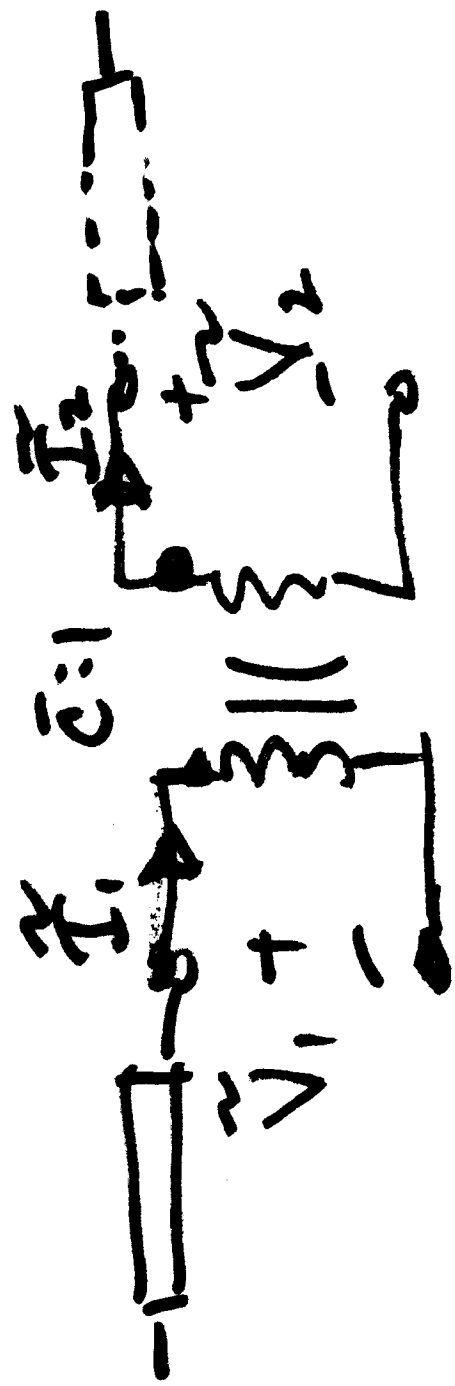
Transformers - wrapup on off-nominal turns ratio
Synchronous Machines - Chapter 3.

- Basic internal structure of machines, cylindrical vs. salient
- Field windings
- Calculation with X_d and X_q .
- Calculation Example(s)
- Concepts behind SYNCH exercise set.
- S-S behavior - X_d ; Dynamic behavior - X_d'
- Short-circuit behavior - X_d'' ; s-s, transient, subtransient



$$\begin{bmatrix} I_1 \\ I_2 \end{bmatrix} \begin{bmatrix} Y_{12} \\ Y_{22} \end{bmatrix} = \begin{bmatrix} H_{11} & H_{12} \end{bmatrix}$$





$$\vec{I} = \vec{I}_1 + \vec{I}_2$$

$$\vec{S}_1 = \vec{S}_2$$

$$\vec{V}_1 \vec{I}_1^* = \vec{V}_2 \vec{I}_2^*$$

$$\vec{I}_2^* = \frac{\vec{V}_1}{\vec{V}_2} \vec{I}_1^*$$

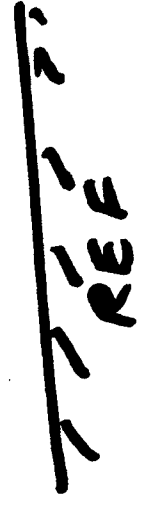
$$\vec{I}_2^* = \vec{I}_1^*$$

Detailed derivations!

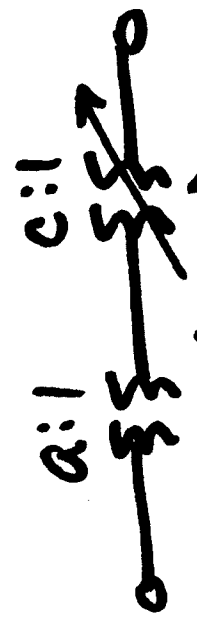
Basis Approach: Develop π -Equiv and handle just like T-Line.



Per-unit per-phase



Tap-Changers
- LTC's
- Phase-Shift



NOMINAL TRANS RATIO \uparrow \pm Adjustment (PS) in phase angle (LTC) or volt mag (LTC)

XFMRS - Use \bullet L-N (Φ A-N)
Per Phase Eguin.



Modify
 $y_{55} = y_{56}$
 $y_{65} = y_{66}$

In [Ybus] $y_{56} = -\frac{1}{Z_{66}}$

(and y_{65})
 $y_{55} = y_{55} + Z_{54}$
 $y_{66} = y_{66} + "$

Basis 2-winding
 XFMR is simple.

How about?

- LTC (or TCUL)
- Phase Shifter (PS)

Tap Changing XFMRs - Variations (P.u. Representations)

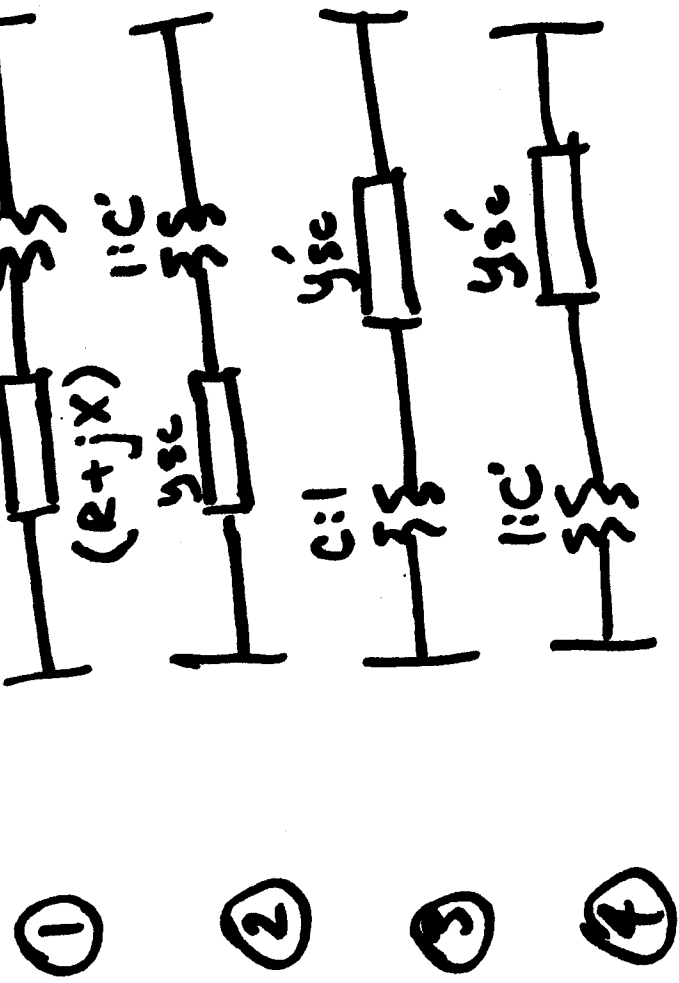
"From" Bus "To" Bus

$$y_{sc} = \frac{1}{R+jX}$$

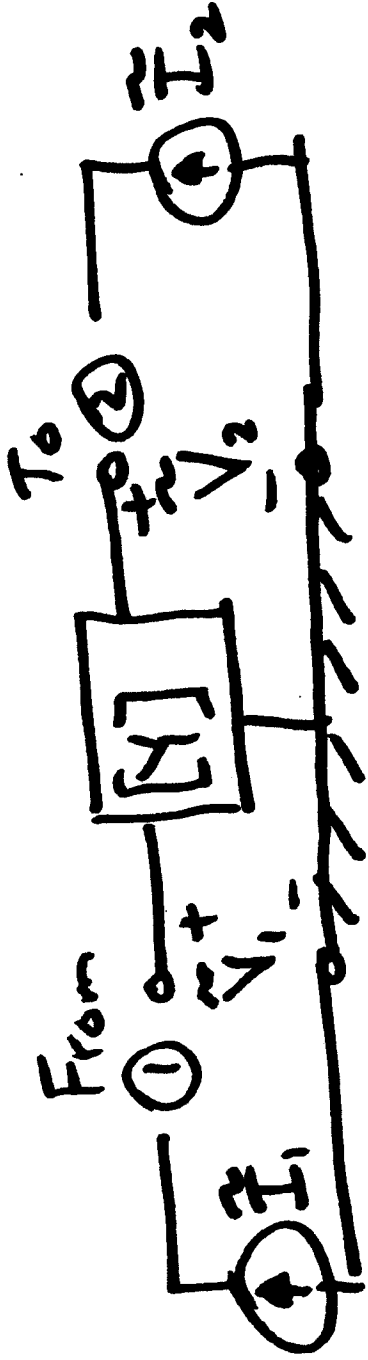
"C" is off-nominal turns ratio. In general C is complex.

C is real for LTC.
C is complex for PS.

If $|C| \neq 1$ then magnitude change.
If C is complex, Phase Shift.

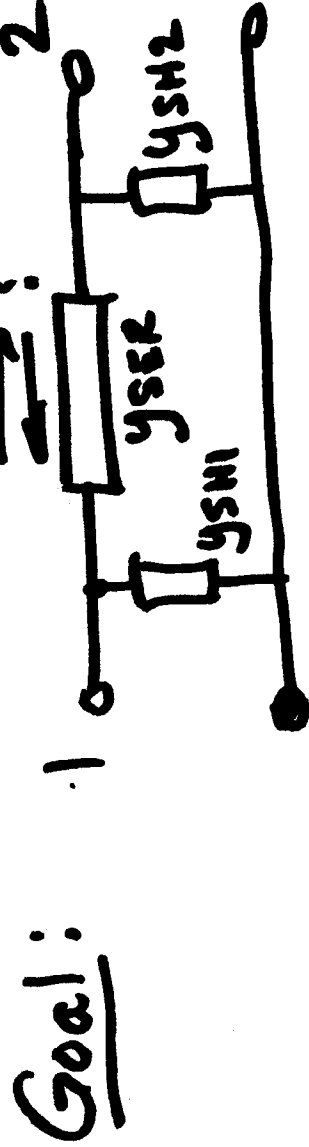


Standard Approach:



$$\begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} I_1 \\ I_2 \end{bmatrix}$$

$$\begin{aligned} y_{11} &= y_{SER} + y_{SH1} \\ y_{12} &= -y_{SER} \\ y_{21} &= -y_{SER} \\ y_{22} &= y_{SER} + y_{SH2} \end{aligned}$$



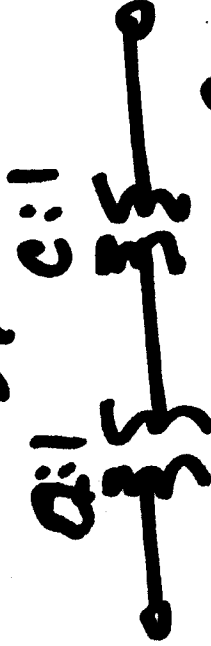
TAP-CHANGERS

a

On One-Line Diags:



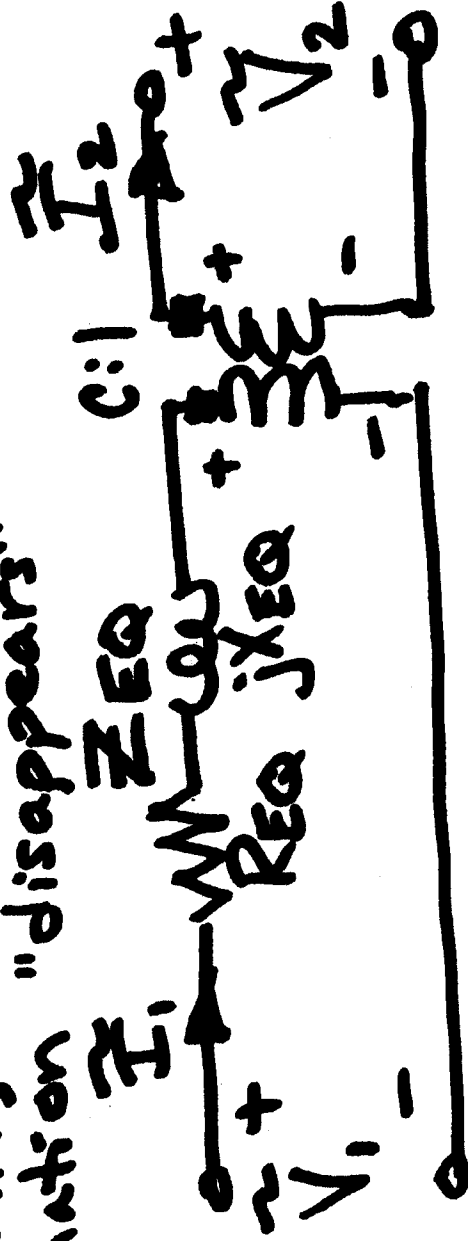
Conceptually:



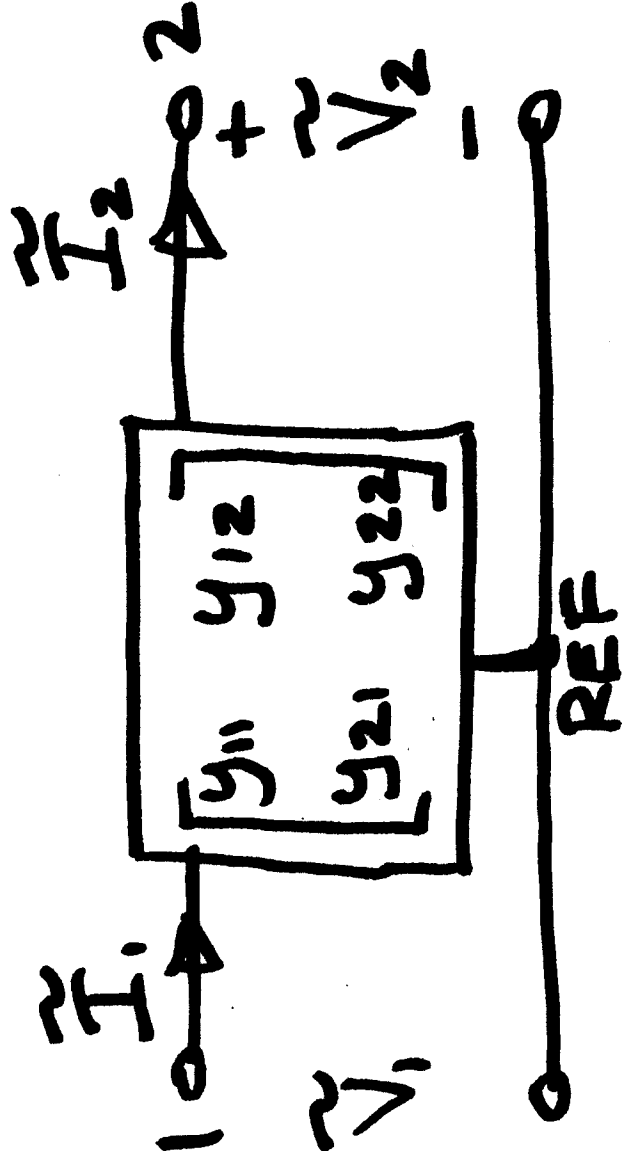
Nominal
Voltage
Ratio

↑ off-nominal
turns ratio
due to
Tap Changer

In per unit, nominal
transformation "disappears"



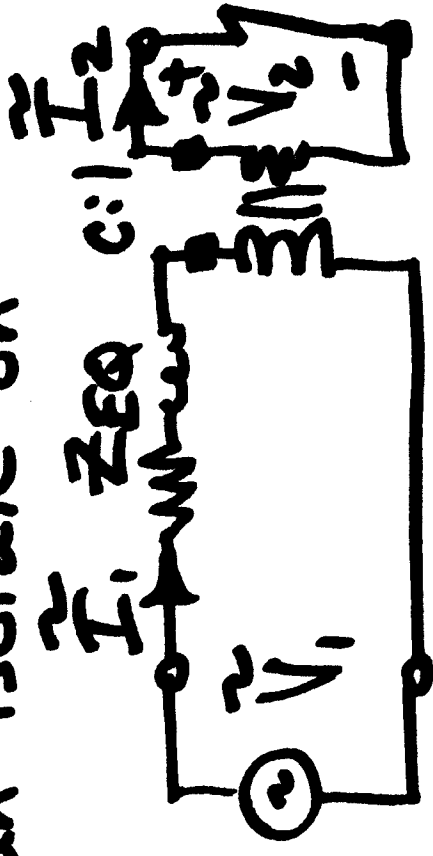
Generically, we can describe this as a 2-node [Y]



where

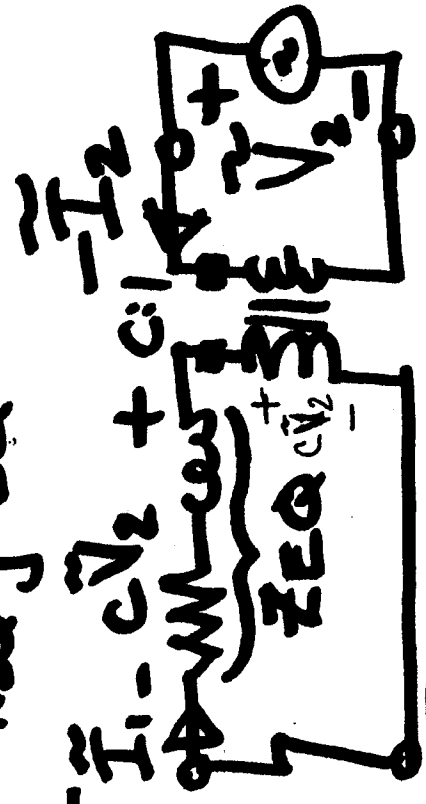
$$\begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} I_1 \\ -I_2 \end{bmatrix}$$

Strategically using shorts ~~on~~
~~the values of [Y]~~, we can isolate on
 the values of [Y].



$$y_{11} = \frac{\tilde{I}_1}{\tilde{V}_1} \Big|_{\tilde{V}_2=0}$$

$$= \frac{1}{Z_{EQ}} = Y_{EQ} = \frac{1}{R_{EQ} + jX_{EQ}}$$



$$y_{22} = \frac{-\tilde{I}_2}{\tilde{V}_2} \Big|_{\tilde{V}_1=0}$$

$$= \frac{1}{Z_{EQ} / |C|^2} = |C|^2 Y_{EQ}$$

$$\vec{I}_1 = -\frac{c\vec{V}_2}{z_{EQ}}; \quad -\vec{I}_2 = -\frac{\vec{I}_1 \cdot c^*}{z_{EQ}} = -\left[\frac{c\vec{V}_2}{z_{EQ}}\right] c^*$$

$$= \frac{|c|^2 \vec{V}_2}{z_{EQ}}$$

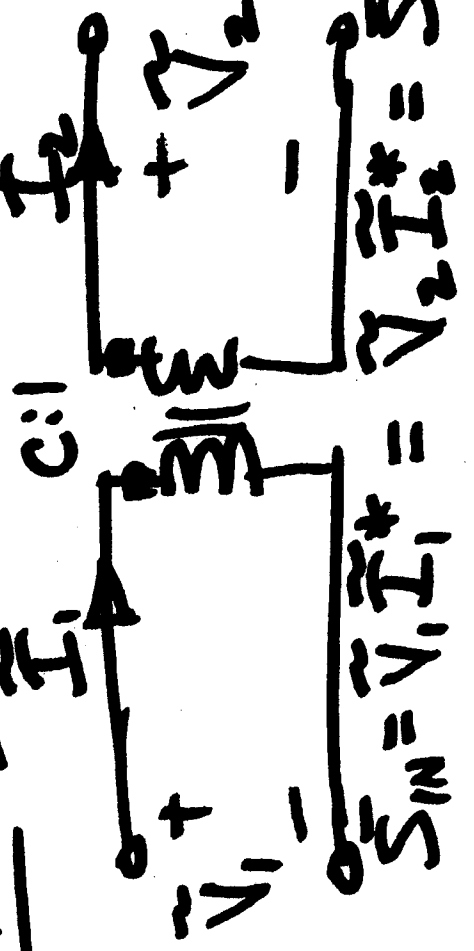
Note: $\frac{I_2}{I_1} = c^*$

$$y_{12} = \frac{\tilde{I}_1}{\tilde{V}_2} \Big|_{\tilde{V}_1=0} = \frac{-C\tilde{V}_2/Z_{EQ}}{\tilde{V}_2} = -CY_{EQ}^d$$

$$y_{21} = \frac{-\tilde{I}_2}{\tilde{V}_1} \Big|_{\tilde{V}_2=0} = \frac{-C^*\tilde{I}_1}{\tilde{V}_1} = -C^*Y_{EQ}$$

Note: Ideal XFR, by definition, has

"C" is voltage ratio.



$$C = \frac{V_2}{V_1}$$

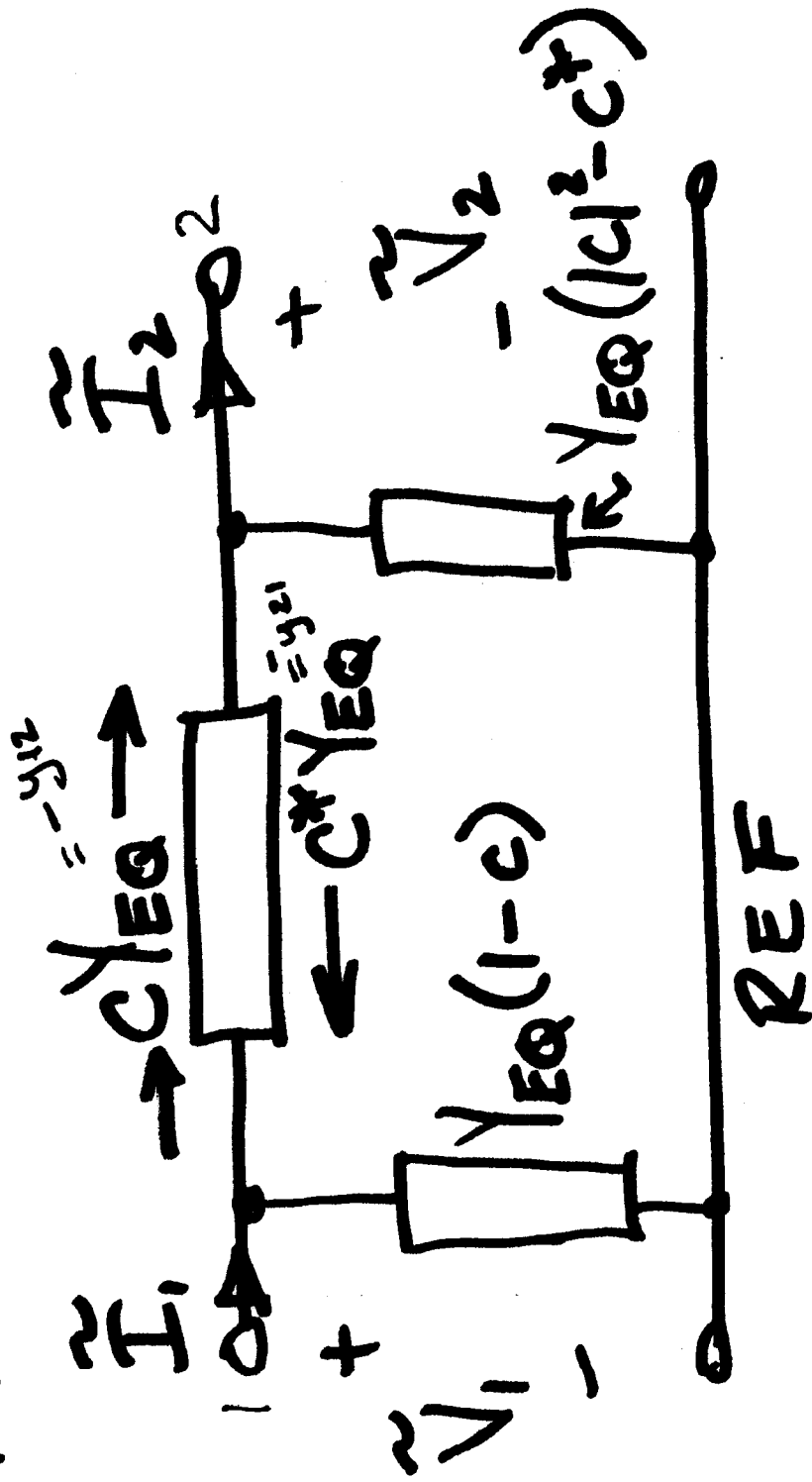
$$C = \frac{I_2}{I_1}$$

$$\frac{I_2}{I_1} = C^*$$

If we "reverse engineer" our e)

$[Y]$ into an equivalent 2-bus

network, then



f

Observations:

- LTC (TCL) has a C that is Real.

\therefore Transfer Admittances

$$C Y_{EQ} = C^* Y_{EQ} \\ \Rightarrow \text{Bilateral. } (y_{12} = y_{21})$$

- Phase-Shifter (PS) has complex C .

\therefore Transfer admittances

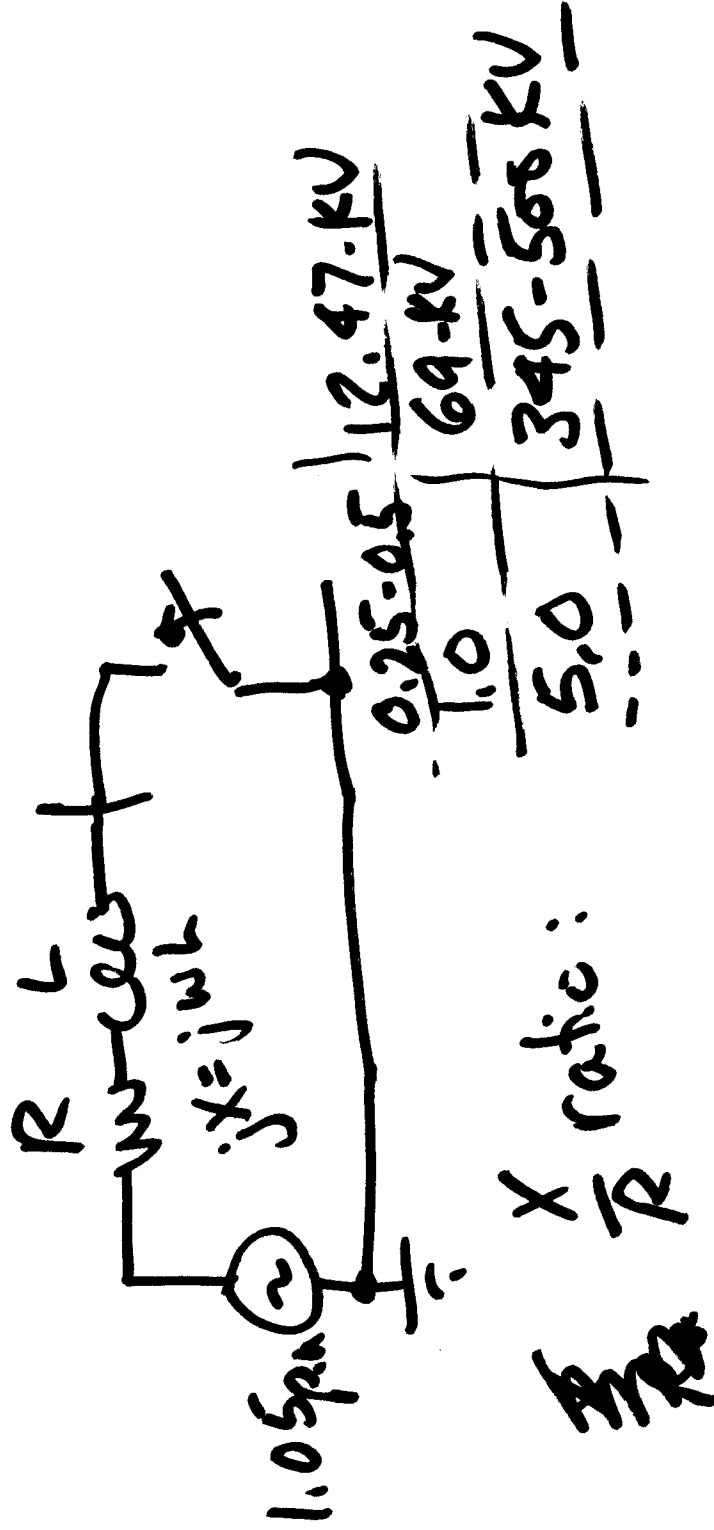
$$C Y_{EQ} \neq C^* Y_{EQ}$$

$$y_{12} \neq y_{21}$$

Not Bilateral.

$[Y]$ not symm.
(about main diag.)

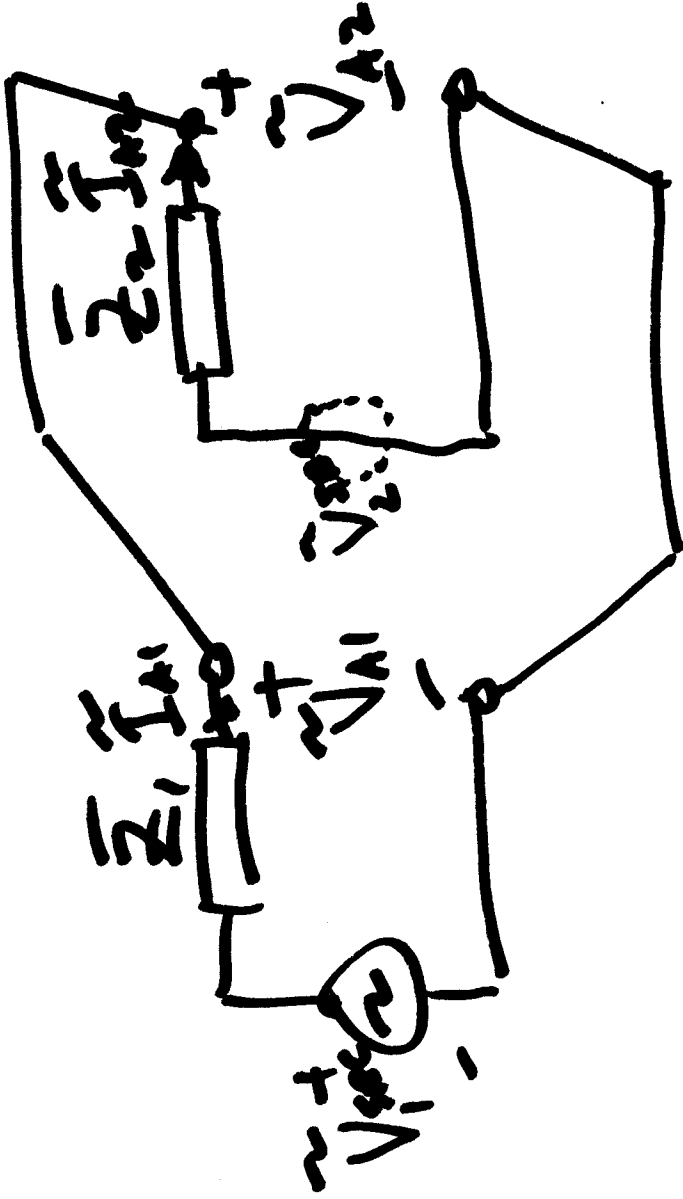
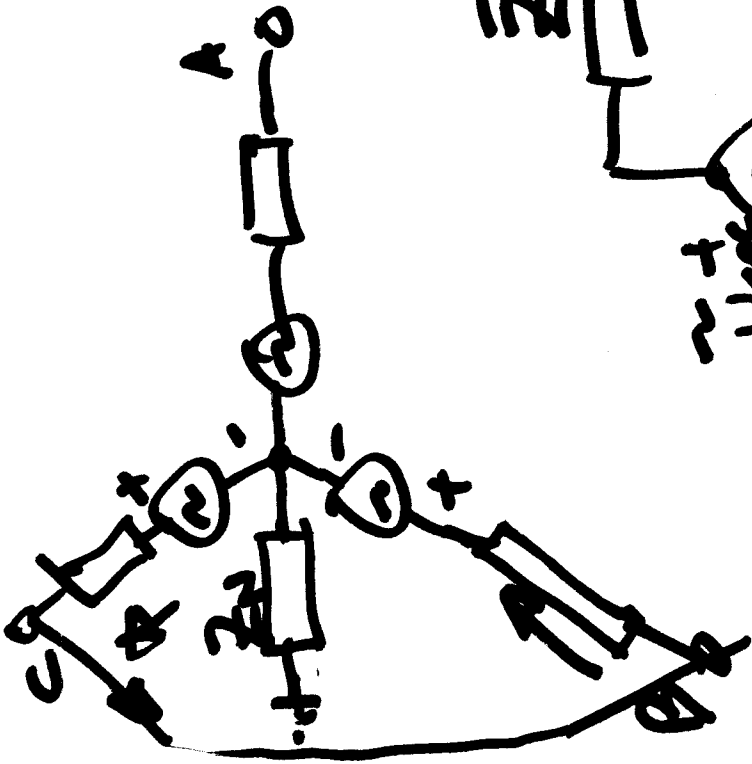
- S.C. Calc
- Induced Force ✓



$$|Z_{sc}| = |R + j\omega L| : \underline{\underline{5\%}}, \underline{\underline{10\%}}$$

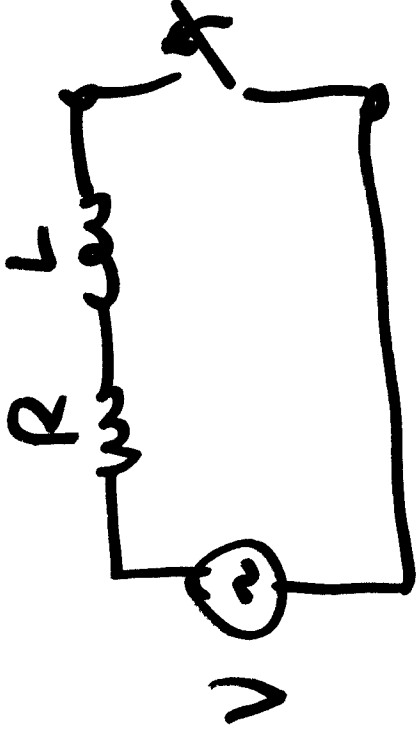
on 100 MVA Base

L-L Fault



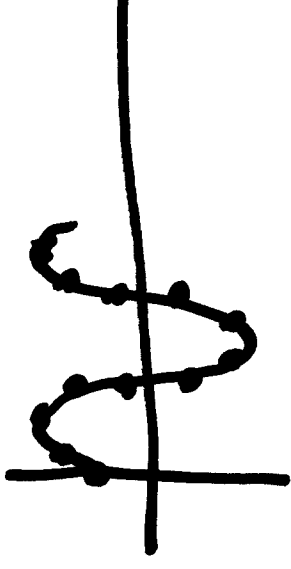
$$[I_s] = \begin{bmatrix} I_{A0} \\ I_{A1} \\ I_{A2} \end{bmatrix}$$

$$[V_s] = \begin{bmatrix} V_{A0} \\ V_{A1} \\ V_{A2} \end{bmatrix}$$

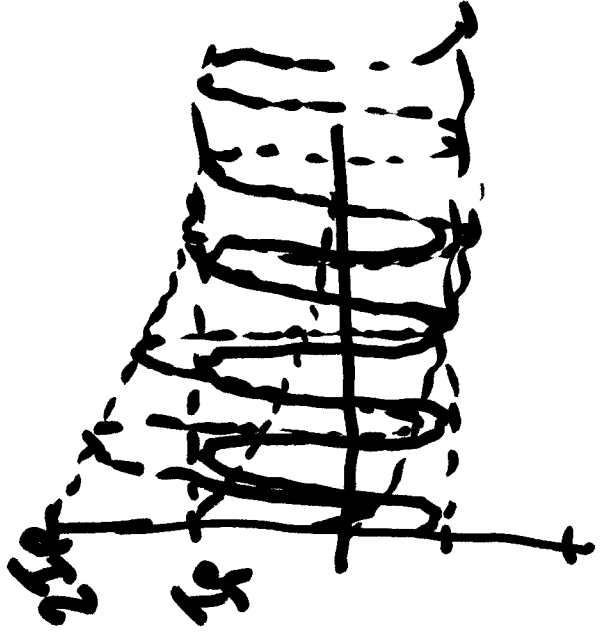


§ 10.1

$$v(t) = V_{max} \sin(\omega t + \alpha)$$



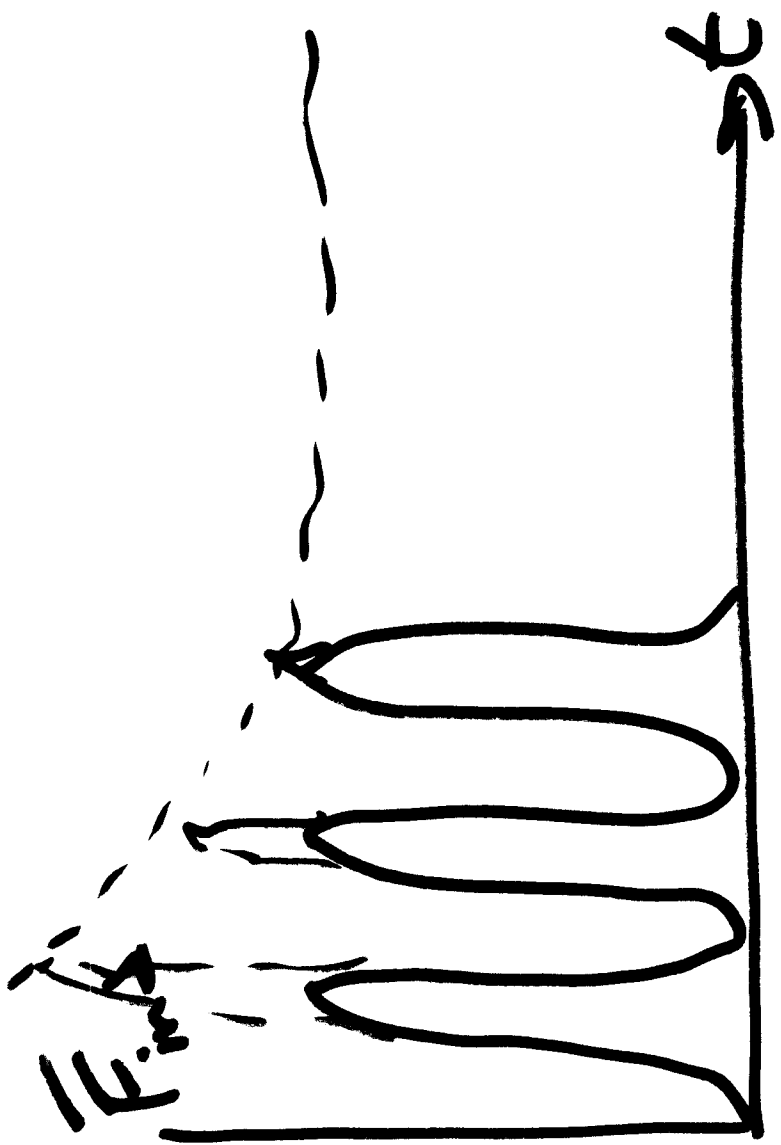
Eqn. 10.2 $i(t) = \frac{V_{max}}{|Z|} \left[\sin(\omega t + \alpha - \theta) - e^{-\frac{R}{L}t} \sin(\alpha - \theta) \right]$



$$|Z| = \sqrt{R^2 + (\omega L)^2}$$

$$\theta = \tan^{-1} \frac{\omega L}{R}$$

Fig. 10.1



Input:

①

X, R, Z_{sc}
 V : prefault voltage

②

L : Span Length

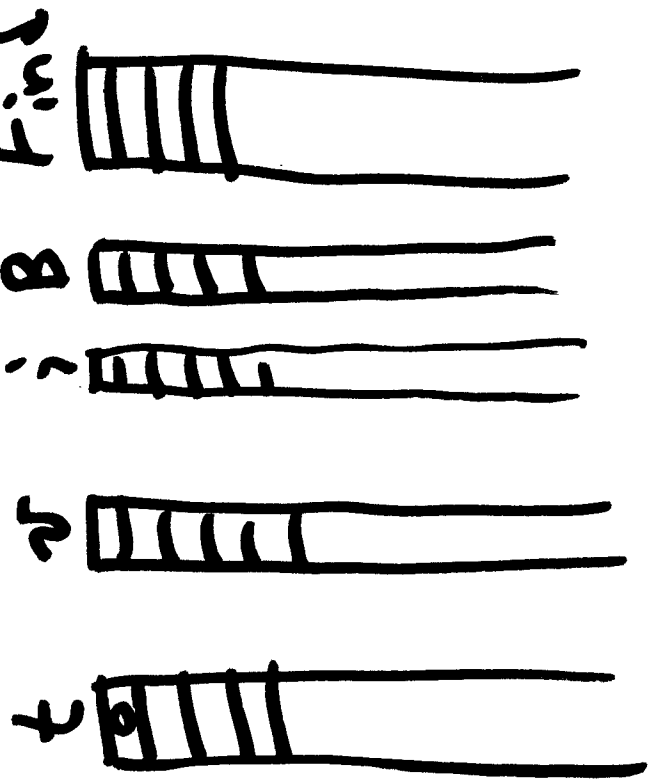
d : Spacing

Δt :

Find = $i(\bar{A} \times \bar{B})$

Data Structure

②



③ CODING

④ Plotting