

ASPEN Tutorial

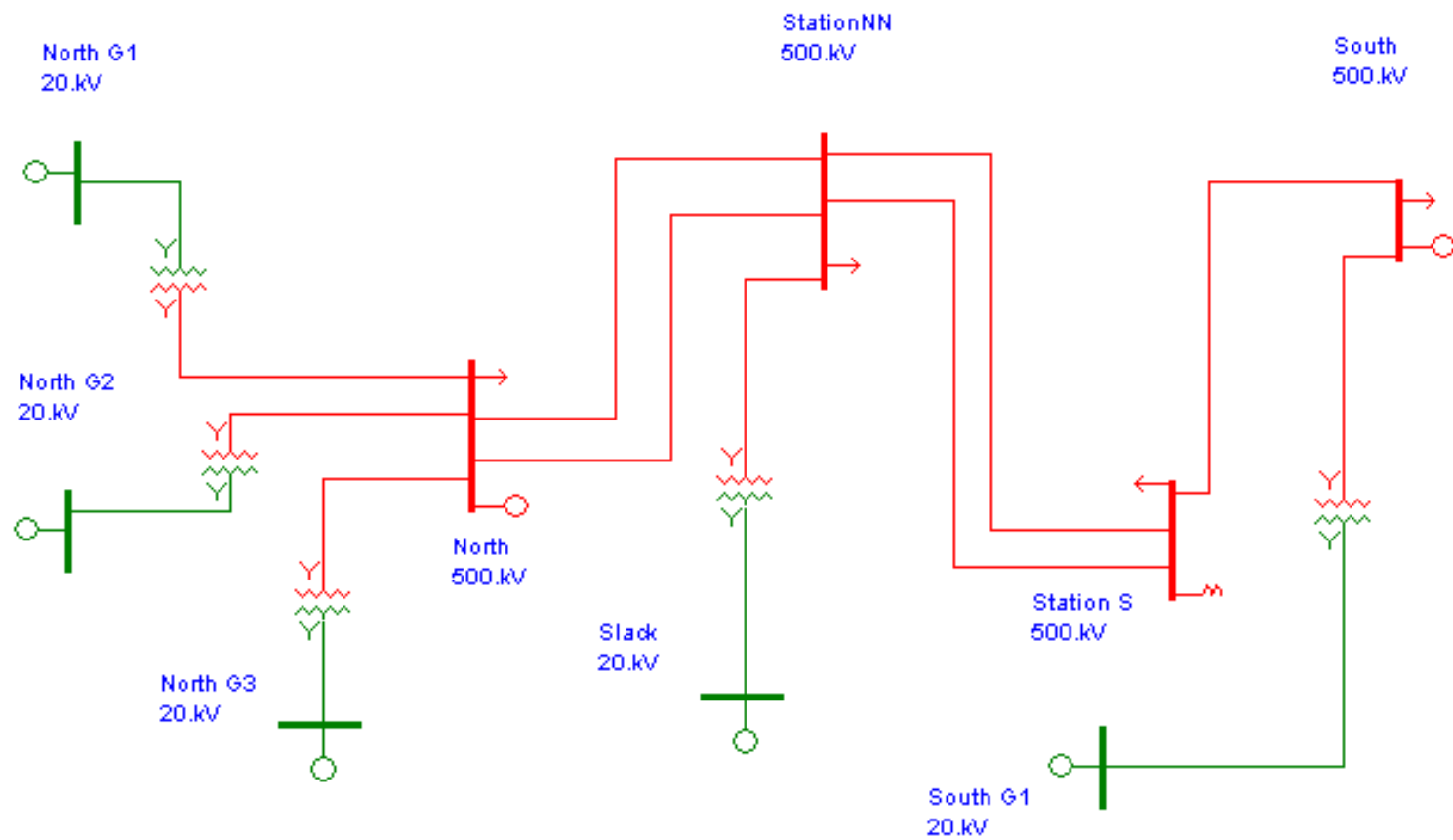
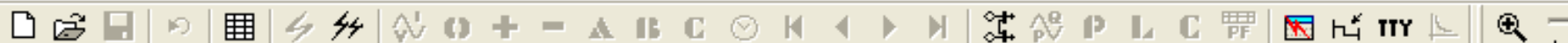
Intro to Software Capabilities

- a. Loadflow
- b. Short circuit, arc flash
- c. Relay application, coordination

Basics of setting up a loadflow

- d. Get the system data, parameters
- e. Basics of program
- f. Draw system configuration
- g. Parameters
 - i. Buses
 - ii. Lines
 - iii. Transformers
 - iv. Generators
 - v. Loadflow configuration
- h. Output
- i. Remedial actions

First - Start program: "Aspen Oneliner"



Generator Data

Generators at 0 Slack 20.kV

Unit '1' On-Line	Edit
	On/Off-Line
	Delete
	New

For Flat-generator-Voltage Start Only

Voltage (pu)= 1. Ref. angle= 0.

Power Flow Regulation

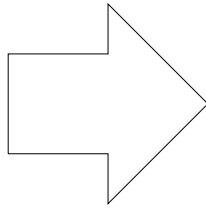
Hold V= 1.05 pu

At Slack 20.kV 0 (PV)

Regulates voltage Fixed P+Q output

Done Help

Last changed Jan 01, 1986



Generating Unit Info

ID= 1 Unit rating= 100. MVA

Impedances (pu based on unit MVA)

Subtransient	0.	+i	0.1	Fill
Transient	0.	+i	0.1	
Synchronous	0.	+j	0.1	
- sequence	0.	+i	0.1	
o sequence	0.	+j	0.1	

Neutral Impedance (in actual Ohms)

0. +j 0.

Scheduled generation (MW)

1050.

P and Q limits (MW and MVAR)

Pmax=	9999.	Qmax=	9999.
Pmin=	-9999.	Qmin=	-9999.

OK Cancel Help

Transmission Line Data

0 Station S 500.kV - 0 South 500.kV

Name= Ckt ID=

Length= ft Type

Branch Parameters

R= X=
 R0= X0=

G1= B1= G2= B2=
 G10= B10= G20= B20=

Current Ratings (A)

A: B: C: D:

Metered at:

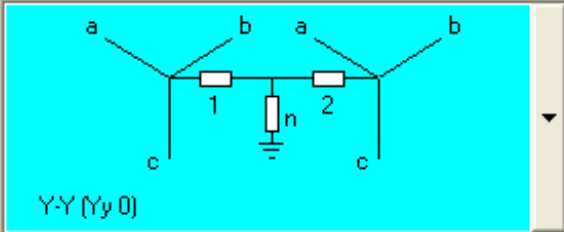
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2-Winding Transformer Data

0 South G1 20.kV - 0 South 500.kV

Name= Ckt ID= MVA1= MVA2= MVA3=

MVA base for per-unit quantities=



Y-Y (Yy 0)

R= X=
 B=
 Ro= Xo=
 Bo=

South G1 20. kV South 500. kV

Tap kV= Tap kV=
 G1*= G2*=
 B1*= B2*=
 G10*= G20*=
 B10*= B20*=

Neutral grounding Z (ohms)

Zg1= +j
 Zg2= +j
 Zgn= +j

*Based on system MVA

Metered at:

Last changed Jan 01, 1986

Bus Info

Bus Data | Breaker Data

Name= Nominal kV=

Bus no.=

Location=

Area no.= Zone no.=

Bus type

Tap bus Transformer Midpoint

Symbol style

Show ID on one-line diagram

State plane coordinates

X = Y =

Substation group no.=

Comments=

Last changed Mar 22, 2002

OK Cancel

Load Data

Loads at 0 South 500.kV

Unit '1' On-Line	<input type="button" value="Edit"/>
	<input type="button" value="On/Off-Line"/>
	<input type="button" value="Delete"/>
	<input type="button" value="New"/>

Load not grounded

Last changed Jan 01, 1986

Load Unit Info

ID=

Constant Power

MW= MVAR=

Constant Current

MW= MVAR=

Constant Impedance

MW= MVAR=

Solve Power Flow

Convergence Criteria	Auto Adjustment Threshold
Max iterations= <input type="text" value="17"/>	MW= <input type="text" value="20."/>
MW Tolerance= <input type="text" value="0.05"/>	MVAR= <input type="text" value="20."/>
MVAR Tolerance= <input type="text" value="0.05"/>	

System slack bus ▾

Misc. Options

Start from last volt. solution Solution Monitor

Start with transformer taps at LTC's center position

Enforce

Generator VAR limits Gen remote volt. control

Transformer taps Switched shunts

Area interchange Phase shifters

Solution Method

Newton-Raphson Fast Decoupled

Figure 6.2 shows a single-line diagram of a five-bus power system. Input data are given in Tables 6.1, 6.2, and 6.3. As shown in Table 6.1, bus 1, to which a generator is connected, is the swing bus. Bus 3, to which a generator and a load are connected, is a voltage-controlled bus. Buses 2, 4, and 5 are load buses. Note that the loads at buses 2 and 3 are inductive since $Q_2 = -Q_{L2} = -0.7$ and $-Q_{L3} = -0.1$ are negative.

For each bus k , determine which of the variables V_k , δ_k , P_k , and Q_k are input data and which are unknowns. Also, compute the elements of the second row of Y_{bus} .

FIGURE 6.2
Single-line diagram for
Example 6.9

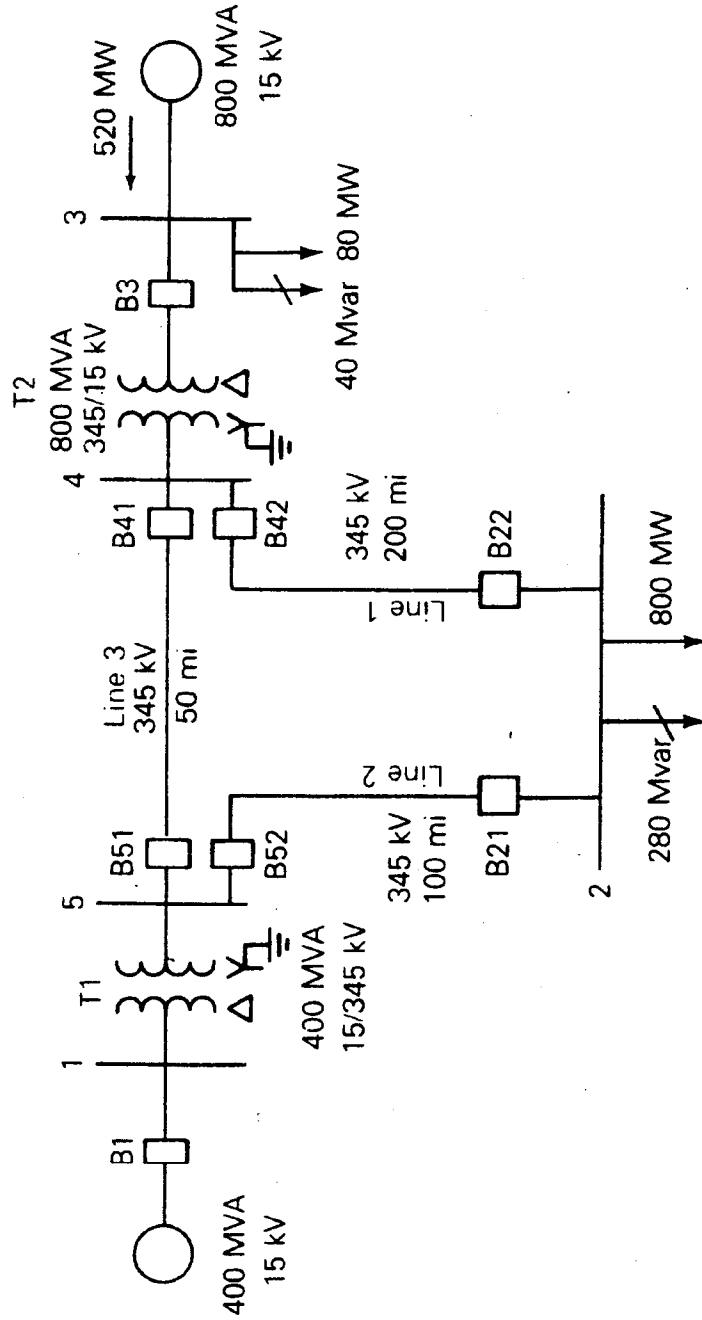


TABLE 6.1
Bus input data for Example 6.9*

Bus	Type	V per unit	δ degrees	P_G per unit	Q_G per unit	P_L per unit	Q_L per unit	Q_{Gmax} per unit	Q_{Gmin} per unit
1	Swing	1.0	0	—	—	0	0	—	—
2	Load	—	—	0	0	8.0	2.8	—	—
3	Constant voltage	1.05	—	5.2	—	0.8	0.4	4.0	-2.8
4	Load	—	—	0	0	0	0	—	—
5	Load	—	—	0	0	0	0	—	—

* $S_{base} = 100$ MVA, $V_{base} = 15$ kV at buses 1, 3, and 345 kV at buses 2, 4, 5

TABLE 6.2
Line input data for Example 6.9

Bus-to-Bus	R' per unit	X' per unit	G' per unit	B' per unit	Maximum MVA per unit
2-4	0.0090	0.100	0	1.72	12.0
2-5	0.0045	0.050	0	0.88	12.0
4-5	0.00225	0.025	0	0.44	12.0

TABLE 6.3
Transformer input data for Example 6.9

Bus-to-Bus	R per unit	X per unit	G_c per unit	B_m per unit	Maximum MVA per unit	Maximum TAP Setting per unit
1-5	0.00150	0.02	0	0	6.0	—
3-4	0.00075	0.01	0	0	10.0	—

SOLUTION The input data and unknowns are listed in Table 6.4. For bus 1, the swing bus, P_1 and Q_1 are unknowns. For bus 3, a voltage-controlled bus, Q_3 and δ_3 are unknowns. For buses 2, 4, and 5, load buses, V_2, V_4, V_5 and $\delta_2, \delta_4, \delta_5$ are unknowns.

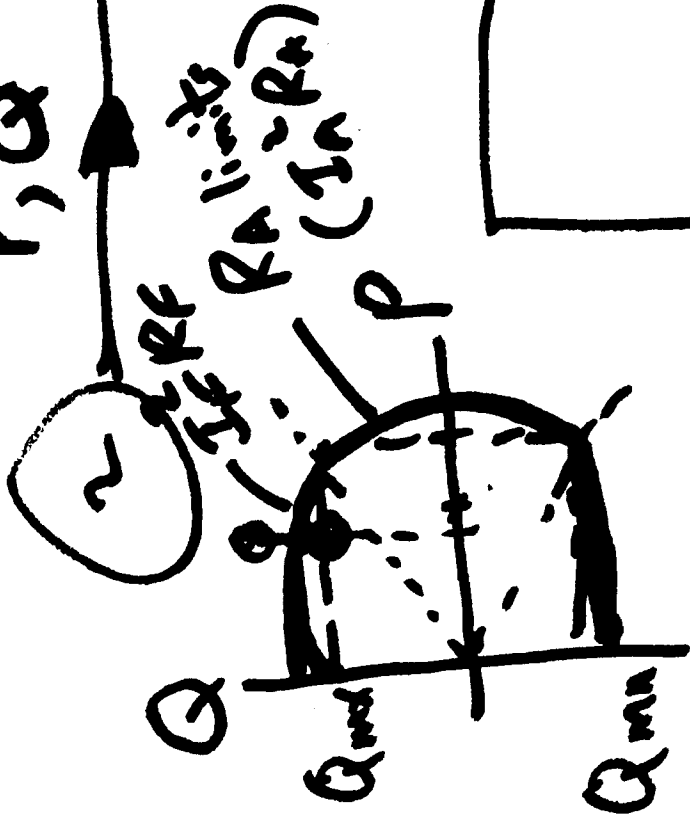
TABLE 6.4
Input data and unknowns for Example 6.9

Bus	Input Data	Unknowns
1	$V_1 = 1.0, \delta_1 = 0$	P_1, Q_1
2	$P_2 = P_{G2} - P_{L2} = -8$ $Q_2 = Q_{G2} - Q_{L2} = -2.8$	V_2, δ_2
3	$V_3 = 1.05$ $P_3 = P_{G3} - P_{L3} = 4.4$	Q_3, δ_3
4	$P_4 = 0, Q_4 = 0$	V_4, δ_4
5	$P_5 = 0, Q_5 = 0$	V_5, δ_5

Solve for 2
 Q & δ . \uparrow
 solved

Gen Bus (P-V Bus)

"slack variable"
 $\sum Q_{in} = 0$



If Q_{min} or Q_{max} are exceeded, change to PQ