

## Topics for Today:

- Questions/Comments on Homework #4 ?
- LU Factorization (needed for each iteration)
- Loadflow Formulation: “NR Details” handout (Week 4)
- NR Algorithm implementation.
- More on Transformers, phase shifters

## Coming up:

- More MatLab - build Jacobian, solve for  $\Delta\delta$  and  $\Delta V$ , iterate.
- Data structures
- Reordering to avoid zero divides and/or speed up solution.

# LU Factorization (Crout's Method)

There are two approaches: - "in situ" methods  
- Sparse matrix storage.

- By rows (example shown here)
- By columns (your text's approach)

## Basic Procedure:

1. Copy Column one
2. Divide Row 1 off-diagonal entries by diagonal term of Row 1.
3. For each element  $i, j$  where  $i > 1$  and  $j > 1$ , subtract from it the product of  $a_{i1} \cdot a_{1j}$ .
4. If the resulting sub-matrix is of order 2 or greater, go back to step 1 and perform the same operations on that sub-matrix. rank

## Example:

$$[A][x] = [Y]$$

$$[L][u][x] = [Y]$$

$$[L][z] = [Y] \rightarrow \text{solve for } z \text{ (1)}$$

$$[u][x] = [z] \rightarrow \text{solve for } [x] \text{ (2)}$$

step 2

$$\begin{array}{c}
 \boxed{4 \ 4 \ 2} \\
 \hline
 2 \\
 3 \\
 2 \ 4 \ -1 \ 2 \\
 4 \ 2 \ 1 \ 1
 \end{array}$$

$[L][u]$

$\Rightarrow$

$$\begin{array}{c}
 \textcircled{1} \\
 \hline
 \begin{array}{c}
 \underbrace{2 \ 2 \ 2 \ 1}_{\textcircled{2}} \\
 \hline
 3 \ 3 \\
 \hline
 2 \ 4 \\
 \hline
 -3 \ 6 \ 3 \\
 \hline
 0 \ -5 \ 0 \\
 \hline
 -6 \ -7 \ -3
 \end{array}
 \end{array}$$

$$\begin{bmatrix}
 \emptyset & 2 & 2 & 1 \\
 \emptyset & \emptyset & -2 & -1 \\
 \emptyset & \emptyset & \emptyset & \emptyset \\
 \emptyset & \emptyset & \emptyset & \emptyset
 \end{bmatrix}$$

$u =$

CHECK!

$[L][u] = [A]$

$$\begin{array}{c}
 \hline
 2 \ 2 \ 2 \ 1 \\
 \hline
 3 \ -3 \ -2 \ -1 \\
 \hline
 2 \ 0 \\
 \hline
 4 \ -6 \ -19 \ -9
 \end{array}$$

$L =$

$\Rightarrow$

$$\begin{bmatrix}
 2 & 0 & 0 & 0 \\
 3 & -3 & 0 & 0 \\
 2 & 0 & -5 & 0 \\
 4 & -6 & -19 & -9
 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 0 & 0 & 6 \\ 0 & 0 & 8 & 4 \\ 0 & 4 & 2 & 6 \\ 0 & 4 & 0 & 6 \end{bmatrix} = \begin{bmatrix} \times & \times & \times & \times \\ \times & \times & \times & \times \\ \times & \times & \times & \times \\ \times & \times & \times & \times \end{bmatrix} = \begin{bmatrix} 8 & 4 & 0 & 0 \\ 0 & 4 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

"A Fill" = changing a zero to non zero entry.

Key: Re-order the equations to minimize fills.

# Jacobian Structures

$$\begin{bmatrix} \frac{\partial P}{\partial s} & \frac{\partial P}{\partial v} \\ \frac{\partial Q}{\partial s} & \frac{\partial Q}{\partial v} \end{bmatrix} \begin{bmatrix} \Delta s \\ \Delta v \end{bmatrix} = \begin{bmatrix} \Delta P \\ \vdots \\ \Delta Q \end{bmatrix}$$

## 8. Equation Forms

$$\text{nr} = \text{find}(Y(i:0))$$

$$\text{nr} = \text{find}(Y(i:))$$

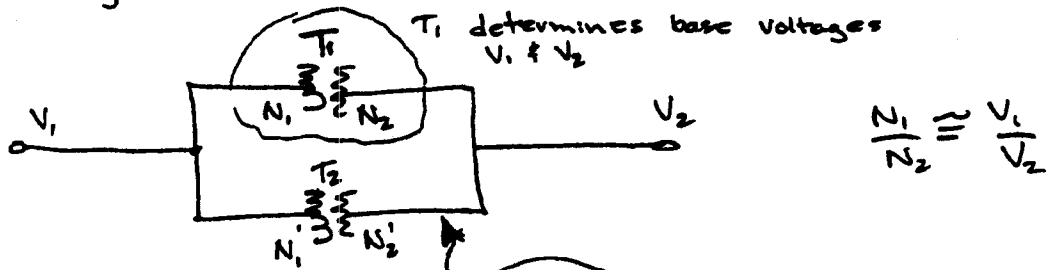
$$\text{nr} = [1 \ 2 \ 3 \ 4 \ 5]$$

for  $n = 1$  to length(nZr)

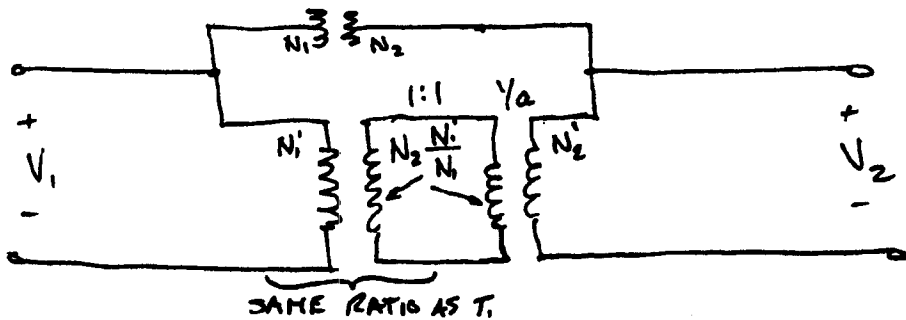
...  
    { (i, nZr(n))  
    ...  
end

OR: for  $n = nZr$   
...  
end

# Paralleling Transformers of Unlike Turns Ratio



What happens for  $\frac{N_1'}{N_2'} \neq \frac{N_1}{N_2}$  ?



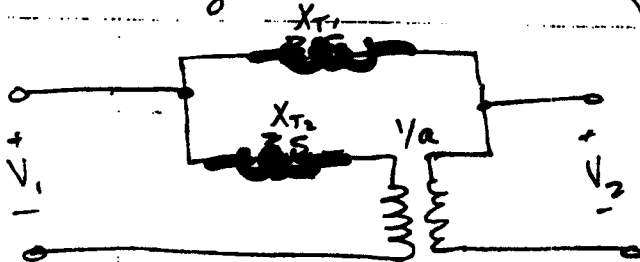
Replace  $T_2$  with 2 XFMRs :- First is same ratio as  $T_1$

$$\frac{N_1}{N_2} = \frac{N_1'}{X}$$

Second XFMR has ratio of off-nominal turns

$$X = N_2 \frac{N_1'}{N_1}$$

Per unit equivalent:



$$\frac{1}{a} = \frac{\left( N_2 \frac{N_1'}{N_1} \right)}{N_2'}$$

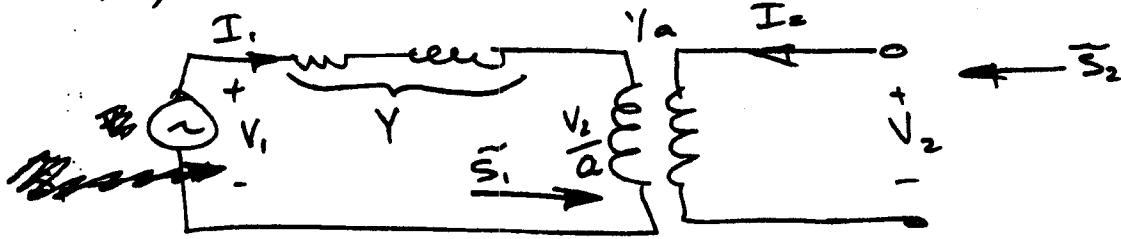
$$\therefore a = \frac{N_1}{N_2} \frac{N_2'}{N_1'} = \text{p.u. turns ratio}$$

Three Methods to Analyze:

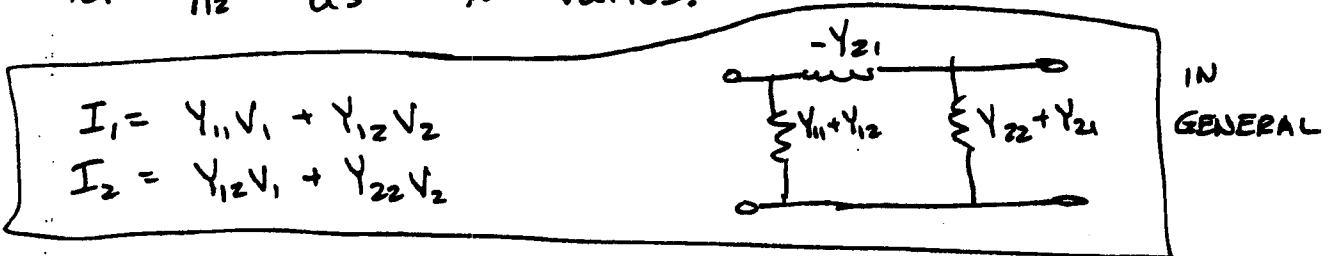
- 1) Admittance Method -
- 2) Circuit Theory -
- 3) Circulating Current Method (Approximate) -

# METHOD 1

So,



So we must find a way to model  $Y$  for  $Y_{12}$  as  $Y_a$  varies.



$$\tilde{S}_1 = -\tilde{S}_2$$

$$\hat{S}_1 = \frac{V_2}{a} I_1^*$$

$$S_2 = V_2 I_2^*$$

$$\frac{V_2}{a} I_1^* = -V_2 I_2^*$$

$$I_1^* = -a I_2^*$$

$$I_1 = -a^* I_2$$

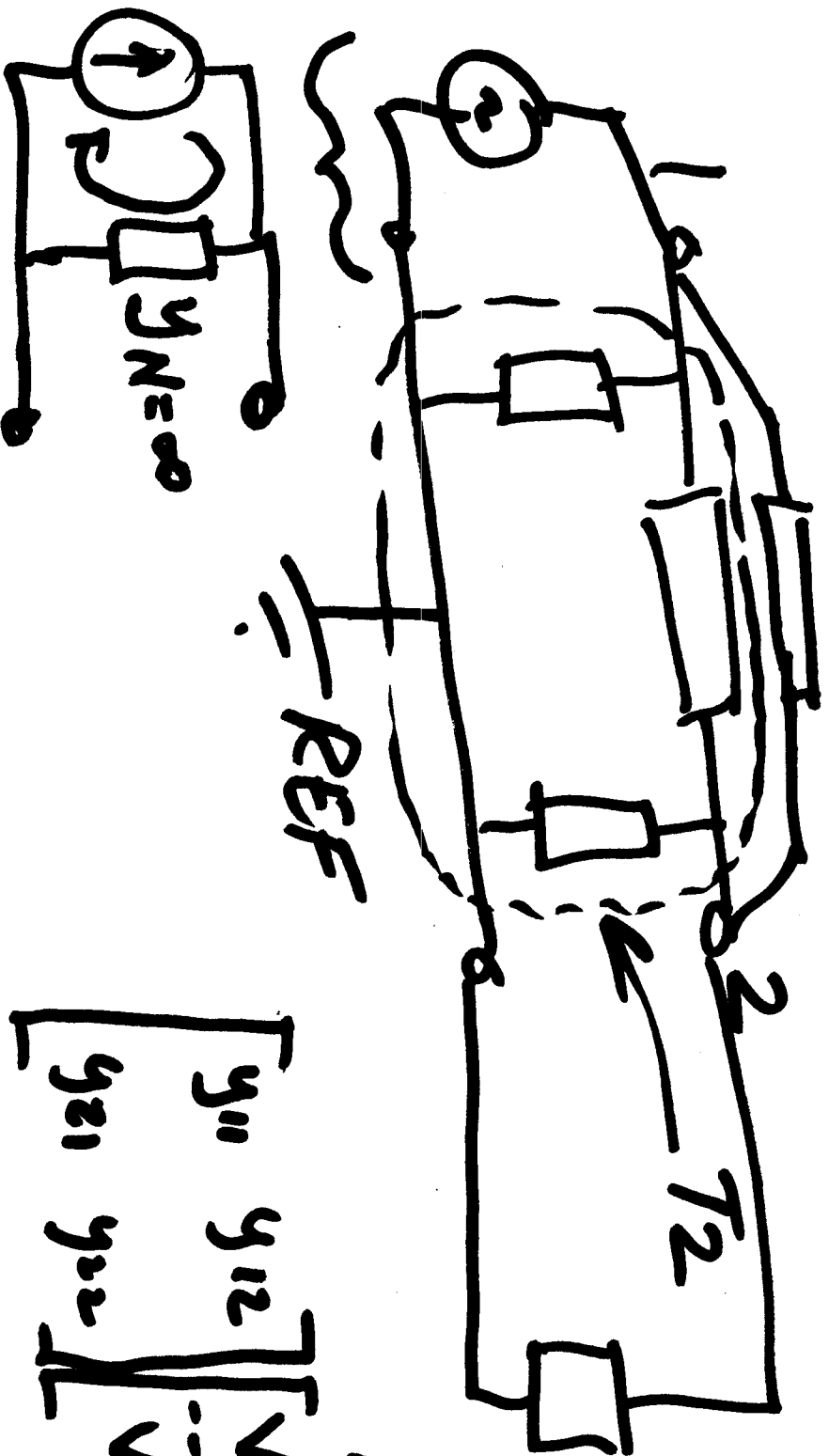
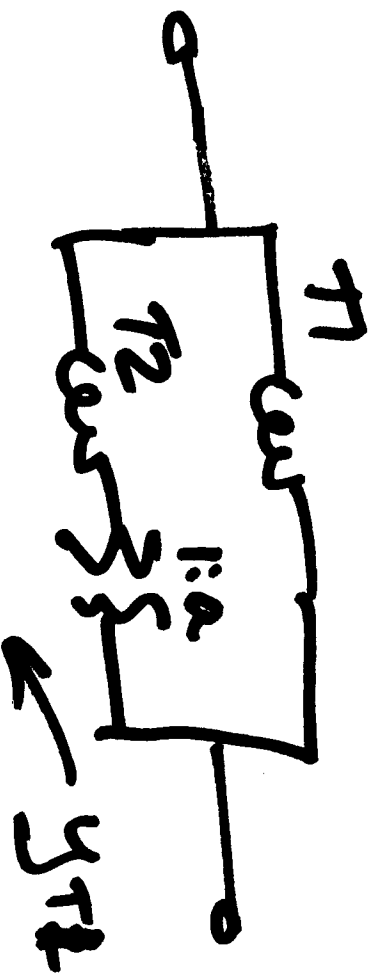
$$I_1 = (V_1 - \frac{V_2}{a}) Y = Y V_1 - \frac{Y}{a} V_2 = -a^* I_2$$

$$\therefore I_2 = \frac{-I_1}{a^*} = \frac{-Y V_1}{a^*} + \frac{Y}{a a^*} V_2$$

$$Y_{11} = Y \quad Y_{12} = -\frac{Y}{a}$$

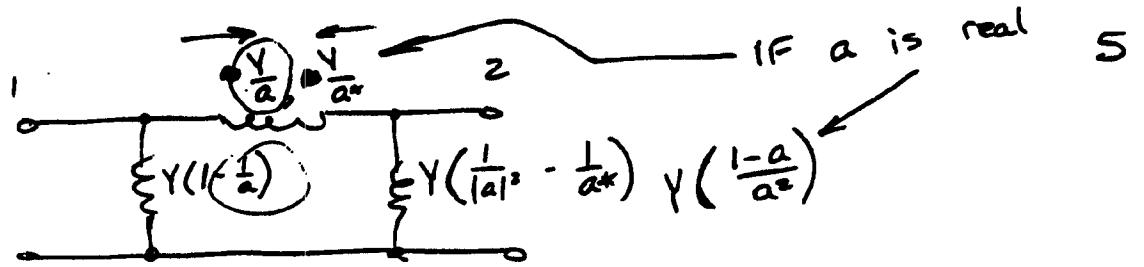
$$Y_{21} = -\frac{Y}{a^*} \quad Y_{22} = \frac{Y}{a a^*} = \frac{Y}{|a|^2}$$



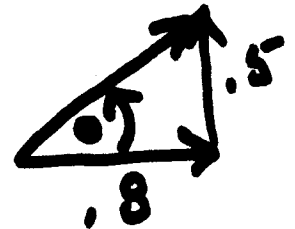
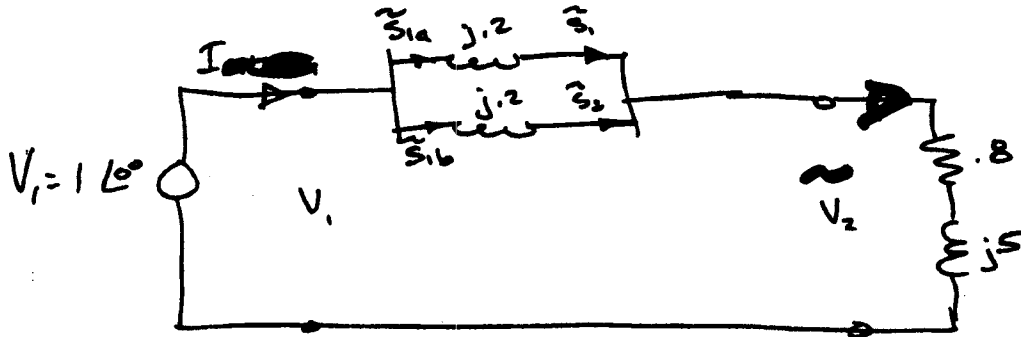


$$\begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} I_1 \\ I_2 \end{bmatrix}$$

known



## 2) CIRCUIT THEORY APPROACH



$$V_2 = \frac{(.8 + j.5)(1 \angle 0^\circ)}{.8 + j.6} = .94 - j.08 = .9434 \angle -4.86^\circ$$

$$I_2 = \frac{.94 - j.08}{.8 + j.5} = 1 \angle -36.87^\circ$$

$$\vec{S} = VI^* = .9434 \angle -4.86^\circ (1 \angle 36.87^\circ) = .9434 \angle 32^\circ = .8 + j.5$$

$$\left. \begin{aligned} S_1 &= .4 + j.25 \\ S_2 &= .4 + j.25 \end{aligned} \right\} = \frac{S_{TOTAL}}{2}$$

$$I_1 = \frac{1}{.8 + j.6} = 1(.8 - j.6) = .8 - j.6$$

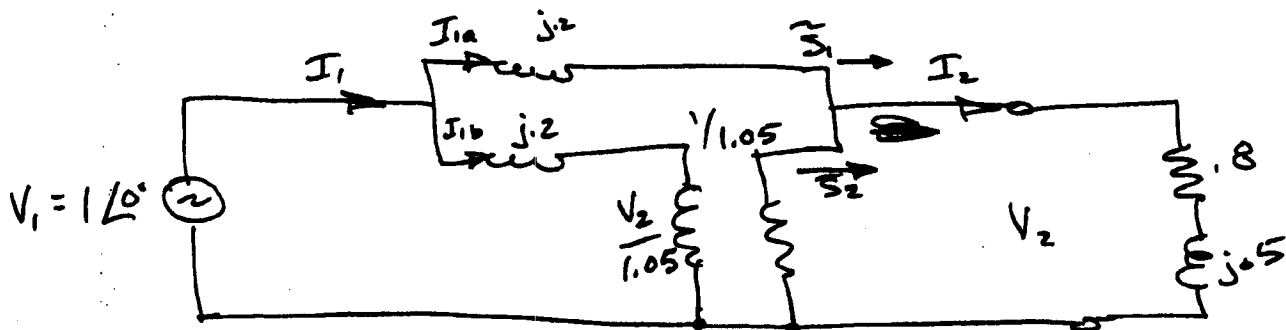
$$S_{1a} = \frac{V_1 I_1^*}{2} = 4 + j.3$$

$$S_{1b} = \frac{V_1 I_1^*}{2} = 4 + j.3$$

Difference due to XFMR Inductance

Now add tap changer  $a = 1.05$

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$$\begin{cases} I_1 = I_{1a} + I_{1b} \\ I_1 = \frac{1 - V_2}{j \cdot 2} + \frac{1 - \frac{V_2}{1.05}}{j \cdot 2} \\ I_2 = \frac{1 - V_2}{j \cdot 2} + \frac{1 - \frac{V_2}{1.05}}{j \cdot 2} \left( \frac{1}{1.05} \right) \\ V_2 = I_2 (0.8 + j \cdot 5) = \left[ \frac{1 - V_2}{j \cdot 2} + \frac{1 - \frac{V_2}{1.05}}{j \cdot 2} \left( \frac{1}{1.05} \right) \right] (0.8 + j \cdot 5) \end{cases}$$

$$V_2 = \left( 1 - V_2 + \frac{1 - \frac{V_2}{1.05}}{1.05} \right) (0.8 + j \cdot 5) = (1.952 - 1.907 V_2) (4.717 \angle -58^\circ)$$

$$V_2 = -1.907 V_2 (4.717 \angle -58^\circ) + (1.952) (4.717 \angle -58^\circ)$$

$$= -8.995 \angle -58^\circ V_2 + 9.207 \angle -58^\circ$$

$$V_2 = \frac{9.207 \angle -58^\circ}{1 + 8.995 \angle -58^\circ} = \frac{9.207 \angle -58^\circ}{9.563 \angle -52.9^\circ} = 0.963 \angle -5.1^\circ$$

$$I_{1a} = \frac{1 - V_2}{j \cdot 2} = 0.473 \angle -25.54^\circ$$

$$I_{1b} = \frac{1 - \frac{V_2}{1.05}}{j \cdot 2} = 0.59 \angle -46.75^\circ$$

$$S_{1a} = V_1 I_{1a}^* = 0.427 + j \cdot 204$$

$$S_{1b} = V_1 I_{1b}^* = 0.4067 + j \cdot 4324$$

$$\tilde{S}_{1a} = V_2 I_{1a}^* = (.963 \angle -5.0^\circ) (.4732 \angle 25.53^\circ)$$

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$$= .427 + j.116 = S_1$$

~~Complex~~

$$\tilde{S}_2 = V_2 \frac{I_{1b}^*}{a} = .963 \angle -5.1^\circ \left( \frac{.59 \angle -46.75^\circ}{1.05} \right)^* = .406 + j.3616$$

$S_2$

$$\tilde{S} = V_2 I_2^* = (.963 \angle 5.1^\circ) \left( \frac{V_2}{2} \right)^* = .983 \angle 32^\circ = \tilde{S}_1 + \tilde{S}_2$$

Before Tc

After T.C.

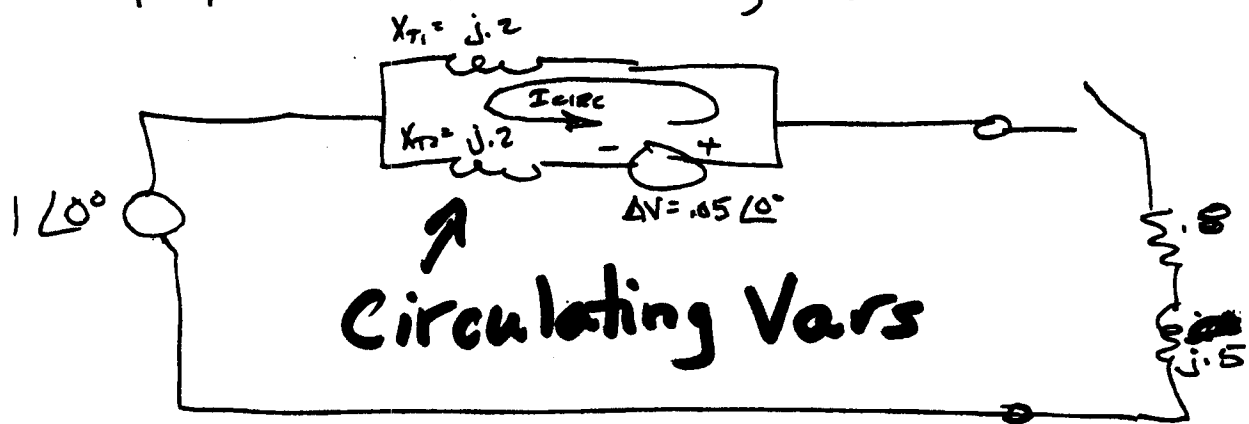
		<u>Circ. Approx.</u>	<u>Ckt. Analysis</u>
$V_1$	1	1	1
$V_2$	.943 $\angle -4.86^\circ$	.963 $\angle -4.87^\circ$	.963 $\angle -5.1$
at $V_2$ {	P.	.4	.398
	$r_2$	.4	.418
	$Q_1$	.25	.135
	$Q_2$	.25	.375

~~So Top changing XFMR shifted to Q to XFMR with top tap to higher than rated secondary voltage. higher top setting.~~

So:  
 Q is shifted to XFMR of higher tap setting.  
 P is still divided almost evenly.

Approximate solution:

Superposition of circulating current



First, look at XFMR before load applied.

$$I_{CIRC} = \frac{.05 \angle 0^\circ}{j.4} = .125 \angle -90^\circ = -j.125$$

From first example,

$$I_{1a} = .4 - j.3 + j.125 = .4 - j.175$$

$$I_{1b} = .4 - j.3 - j.125 = .4 - j.425$$

~~Handwritten scribbles and calculations, including  $(.125)(j.2) = .025$  and  $(j.08 + .025)$ .~~

By Superposition,

$$V_2 = V_2 \text{ BEFORE THE CHANGE} +$$

$$\frac{\Delta V (jX_{T1})}{jX_{T1} + jX_{T2}} \left[ \frac{Z_{LOAD}}{Z_{TOTAL}} \right]$$

Voltage at Load due to ΔV

$$\Delta V_{oc} = \frac{\Delta V (jX_{T1})}{(jX_{T1} + jX_{T2})}$$

$$Z_{th} = jX_{T1} \parallel jX_{T2}$$

$$= .943 \angle -4.86^\circ +$$

$$\frac{.05 (j.2)}{j.4} \left[ \frac{.8 + j.5}{.8 + j.6} \right]$$

$$V_2 = .963 \angle -4.87^\circ$$

$$j.5 + (jX_{T1} \parallel jX_{T2})$$

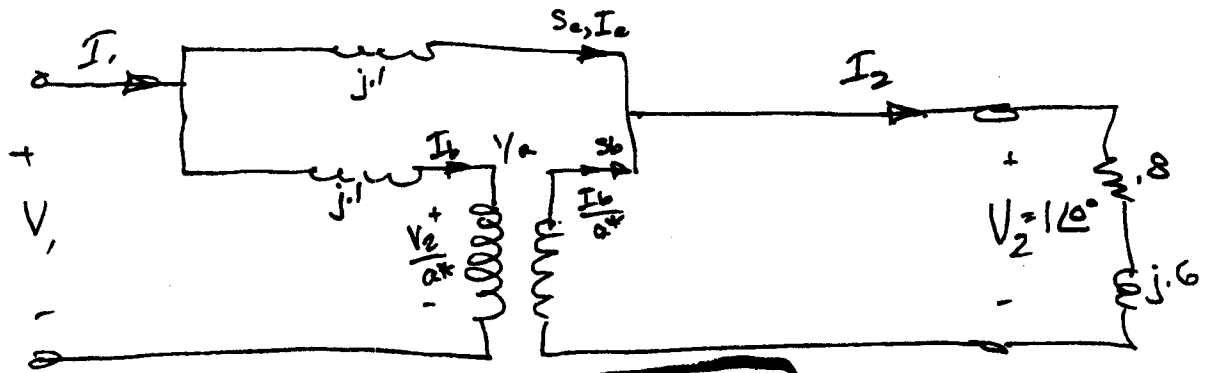
$$S_{1a} = V_2 I_{1a}^* = (.963 \angle -4.87^\circ) (.437 \angle 23.63^\circ)^* = .421 \angle 18.76^\circ$$

$$S_{2a} = V_2 I_{2a}^* = (.963 \angle -4.87^\circ) (.584 \angle 46.73^\circ) = .562 \angle 41.86^\circ$$

$$= .398 + j.135$$

$$= .418 + j.375$$

Phase Shifting XFMR



$$a = 1/3^\circ = e^{j46}$$

Without phase shifter,

$$P_{LOAD} = \frac{V_2^2}{Z^*} = 1(.8 + j.6) = .8 + j.6$$

$$S_a = .4 + j.3$$

$$S_b = .4 + j.3$$

$$I_a = .4 - j.3$$

$$I_b = .4 - j.3$$

$$V_1 = 1 \angle 0^\circ + (.4 + j.3)(j.1)$$

$$= 1.0307 \angle 2.2^\circ$$

With Phase Shifter,

$$\frac{V_1 - 1}{j.1} + \frac{V_1 - 1 \angle 3^\circ}{j.1} \left( \frac{1}{1 \angle 3^\circ} \right) = \frac{1}{.8 + j.6} = I_2$$

$$V_1 \left( 1 + \frac{1}{1 \angle 3^\circ} \right) - 1 - \left( \frac{1}{1 \angle 3^\circ} \right)^2 = j.1(.8 + j.6)$$

$$V_1 (1.999 \angle -1.5^\circ) - 1 - 1 \angle -6^\circ = .1 \angle 53.7^\circ + 1.999 \angle -1.5^\circ$$

$$V_1 = 1.031 \angle 1.73^\circ = 1.031 + j.013$$

$$1.028 + j.016 = 1.922 \angle -6.03^\circ = .159 - j.28$$

$$I_a = \frac{1.031 + j.013 - 1}{j.1} = .131 - j.311$$

$$\frac{I_b}{a^*} = I_2 - I_a = .8 - j.6 - .131 + j.311 = .669 - j.289$$

$$S_a = .131 + j.311$$

$$S_b = .669 + j.289$$

NOTE SHIFT IN POWER FLOW THRU XFMR

BEFORE

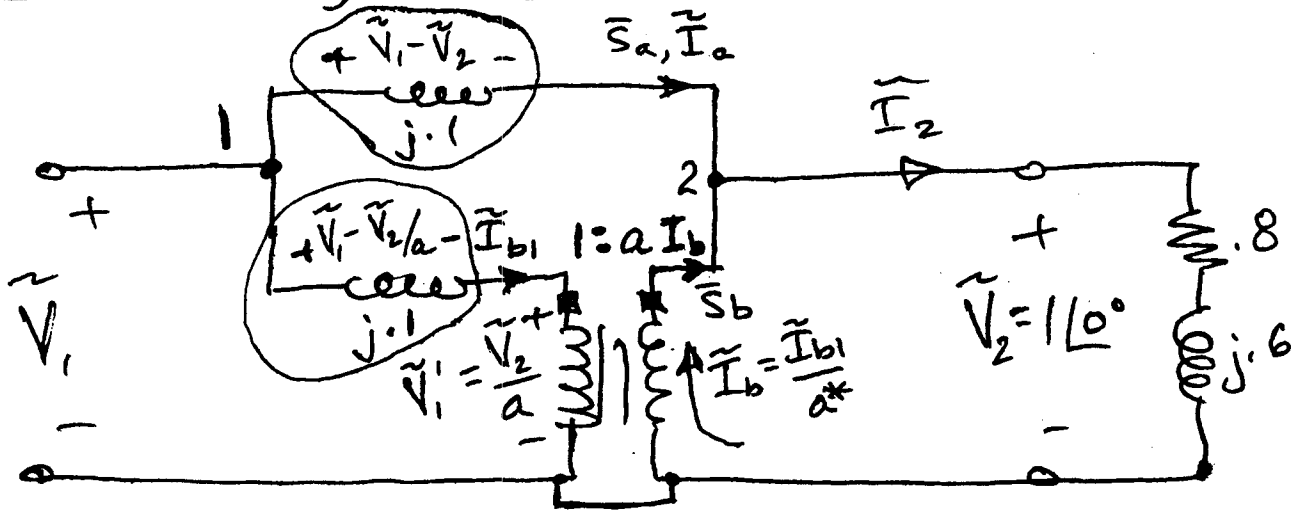
AFTER

$I_a$	$.4 + j.3$	$.131 - j.311$
$I_b/a^*$	$.4 - j.3$	$.669 - j.289$
$P_a$	.4	.131
$P_b$	.4	.669
$Q_a$	+1.3	.311
$Q_b$	+1.3	.289
$V_1$	1.031 $\angle 2.2^\circ$	1.031 $\angle 7.73^\circ$
$V_2$	1.0 $\angle 0^\circ$	1.0 $\angle 0^\circ$

if  $a$  is at positive angle, power flow through phase shifting XFMR increases

# Phase-Shifting XFMR:

PS-1



Solve:

$$\tilde{I}_2 = \frac{\tilde{V}_2}{8 + j.6} = \frac{\tilde{V}_1 - \tilde{V}_2}{j.1} + \frac{\tilde{V}_1 - \frac{\tilde{V}_2}{a}}{j.1} \left( \frac{1}{a^*} \right)$$

KCL at Node 2

$$\tilde{I}_b = \tilde{I}_2 \div a^*$$

Since  $\tilde{V}_2$  is known (it's typical to state desired load voltage and then solve for required load voltage  $\tilde{V}_1$ ) we can solve for  $\tilde{V}_1$ .  
Since  $\tilde{V}_2 = 1 \angle 0^\circ$ ,

$$\frac{1}{8 + j.6} = \frac{\tilde{V}_1 - 1}{j.1} + \left( \frac{\tilde{V}_1 - \frac{1}{a}}{j.1} \right) \frac{1}{a^*}$$

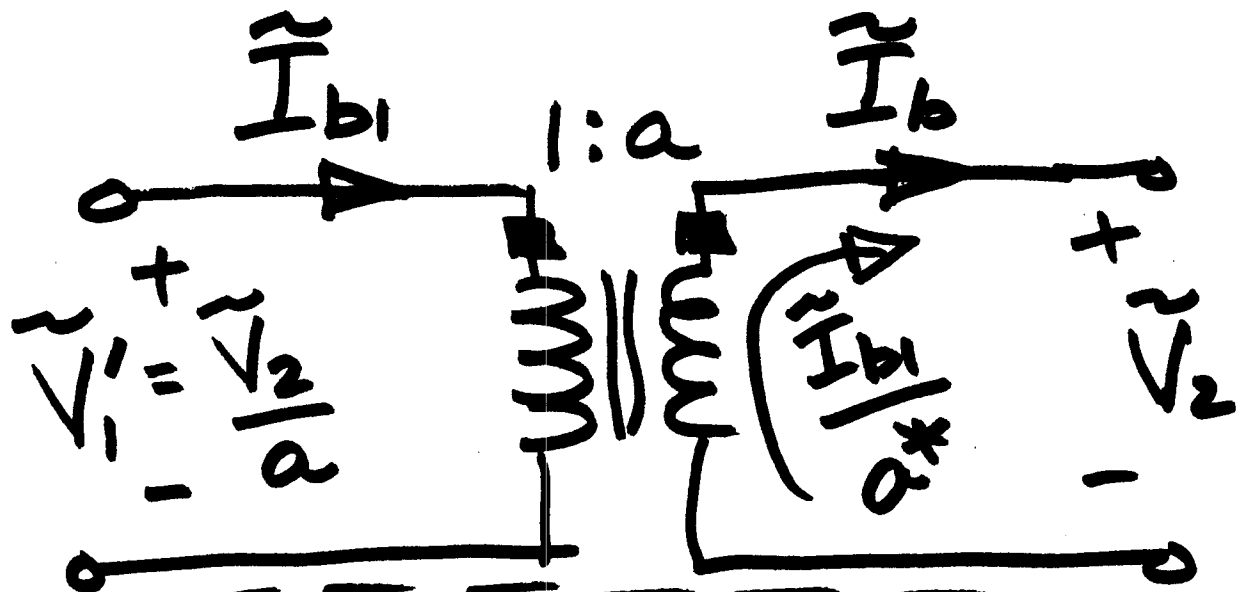
Multiplying through by  $j.1$ ,

$$\frac{j.1}{8 + j.6} = \tilde{V}_1 - 1 + \left( \tilde{V}_1 - \frac{1}{a} \right) \frac{1}{a^*}$$

Grouping, 
$$\tilde{V}_1 \left( 1 + \frac{1}{|a|^2} \right) - 1 - \frac{1}{|a|^2} = \frac{j.1}{8 + j.6}$$



Take a close look at the PS transformer:



$$\tilde{V}_1 \tilde{I}_{b1}^* = \tilde{V}_2 \tilde{I}_b^*$$

$$\tilde{S}_1 = \tilde{S}_2$$

"a" is defined as the voltage ratio:

$$a = \frac{\tilde{V}_2}{\tilde{V}_1} \Rightarrow \tilde{V}_1 = \frac{\tilde{V}_2}{a}$$

$$a = \frac{\tilde{I}_{b1}^*}{\tilde{I}_b^*}$$

$$a^* = \frac{\tilde{I}_{b1}}{\tilde{I}_b}$$

$$\tilde{I}_{b1} = a^* \tilde{I}_b$$

Or, 
$$\tilde{V}_1 = \frac{j0.1}{(1.8+j1.6)} + 1 + \frac{1}{|a|^2}$$

$$\left(1 + \frac{1}{a^*}\right)$$

PS-2

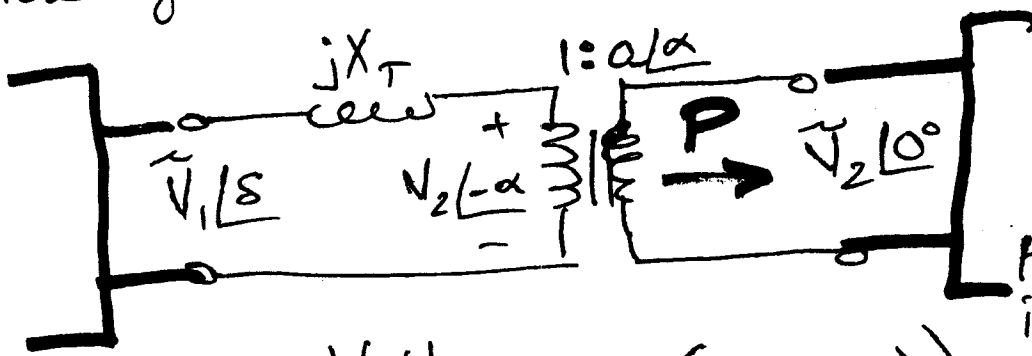
If Load Impedance & transformer reactance are expressed as variables,

$$\tilde{V}_1 = \frac{\frac{jX_T}{Z_{LOAD}} + 1 + \frac{1}{|a|^2}}{1 + \frac{1}{a^*}} \quad \left| \quad \tilde{V}_2 = 1 \angle 0^\circ \right.$$

After  $\tilde{V}_1$  is known, all currents,  $P_s, Q_s$  can be solved for. (See next page).

We note that <sup>as</sup> the angle of  $a$  increases, so does the power flow thru XFMR #2.

This is easy to explain using the power flow equation for a short lossless line:



$$P = \frac{V_1 V_2}{X} \sin(\delta - (-\alpha))$$

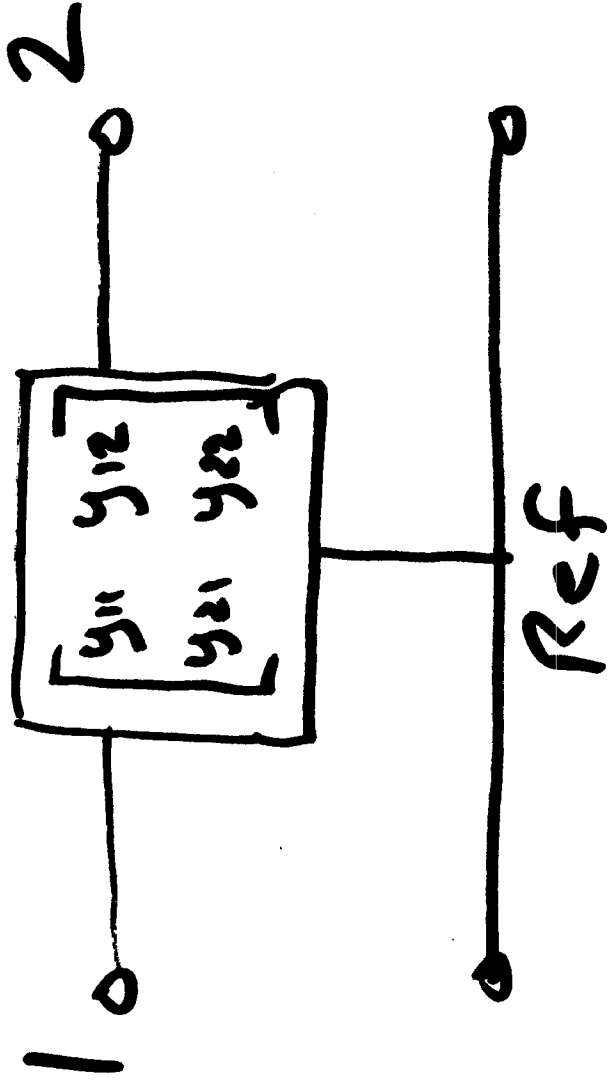
Hence, as  $\alpha$  increases, so does  $P$ .

Summary of Effect of Phase Shift in Paralleled Transformers:

Quantity	Case #1	Case #2	Case #3
Turns Ratio "a"	1/-3°	1/0°	1/+3°
V <sub>1</sub>	1.031 /3.72°	1.031/2.22°	1.031/0.72°
V <sub>2</sub>	1/0°	1/0°	1/0°
I <sub>1</sub>	1.009/-35.99°	1.0/-36.87° = I <sub>2</sub>	1.009/-38.99°
I <sub>2</sub>	1.0/-36.87°	1.0/-36.87°	1.0/-36.87°
I <sub>b1</sub>	0.337 /-64.23°	0.5/-36.87°	0.730/-26.38°
I <sub>b</sub>	0.337 /-67.24°	0.5/-36.87°	0.730/-23.38°
I <sub>a1</sub> = I <sub>a</sub>	0.730 /-23.38°	0.5/-36.87°	0.337/-67.24°
P <sub>1</sub>	0.8000	0.8000	0.8000
P <sub>2</sub>	0.8000	0.8000	0.8000
P <sub>a1</sub>	0.6697	0.4000	0.1303
P <sub>a</sub>	0.6697	0.4000	0.1303
P <sub>b1</sub>	0.1303	0.4000	0.6697
P <sub>b</sub>	0.1303	0.4000	0.6697
Q <sub>1</sub>	0.6646	0.6500	0.6646
Q <sub>2</sub>	0.6000	0.6000	0.6000
Q <sub>a1</sub>	0.3428	0.3250	0.3218
Q <sub>a</sub>	0.2895	0.3000	0.3105
Q <sub>b1</sub>	0.3218	0.3250	0.3428
Q <sub>b</sub>	0.3105	0.3000	0.2895

$$Q_{T1} = |I_a|^2 \times T_1$$

$$0.5^2 (.1) = \underline{\underline{.025}}$$

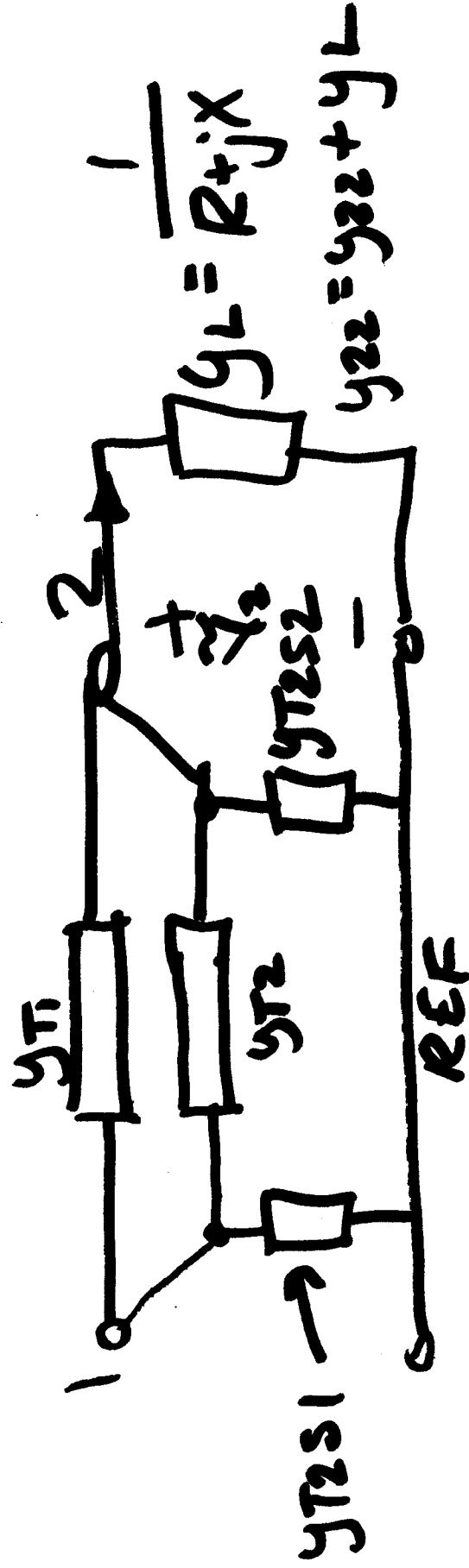


$$y_{11} = y_{11} + y_{T1}$$

$$y_{22} = y_{22} + y_{T1}$$

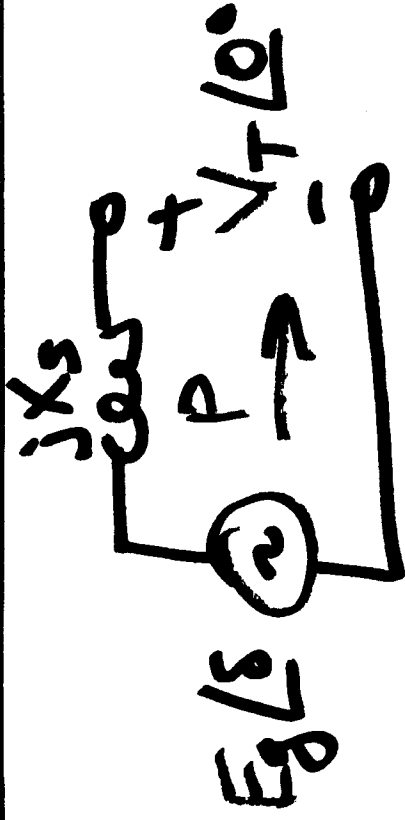
$$y_{12} = y_{12} - y_{T1}$$

$$y_{21} = y_{21} - y_{T1}$$

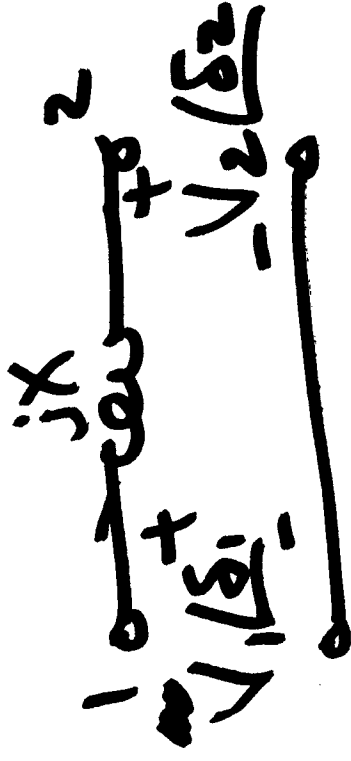


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$$\begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} = \begin{bmatrix} F_1 \\ F_2 \end{bmatrix}$$



$$P = \frac{E_g V_T}{X_s} \sin(\delta)$$



$$P_{1 \rightarrow 2} = \frac{V_1 V_2}{X_s} \sin(\delta_1 - \delta_2)$$