## Calculating Fluid Forces on Surfaces in Comsol 5.1

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To calculate the fluid force on a surface,  $\underline{F}$ , from a solution to the microscopic momentum balance (the Navier-Stokes equation), we use the following expression (Morrison, 2013):

$$\underline{F} = \iint_{S} \left[ \widehat{n} \cdot \widetilde{\underline{\mathbf{I}}} \right] \Big|_{surface} dS \tag{1}$$

where S is the area of the macroscopic surface,  $\widetilde{\underline{\mathbb{I}}}$  is the total stress tensor, dS is a differential surface element on the surface, and  $\widehat{n}$  is the unit normal to dS. The tensor  $\underline{\widetilde{t}}$  is the extra stress tensor, also called the viscous stress tensor, which for a Newtonian fluid it is related to the velocity field  $\underline{v}(x,y,z)$  as follows:

$$\underline{\tilde{\tau}} = \mu(\nabla \underline{v} + (\nabla \underline{v})^T) \tag{2}$$

$$\widetilde{\underline{\Pi}} = \widetilde{\underline{\tau}} - p\underline{\underline{I}} \tag{3}$$

$$\underline{v} = \begin{pmatrix} v_x \\ v_y \\ v_z \end{pmatrix}_{xyz} \tag{4}$$

$$\underline{\tilde{z}} = \begin{pmatrix}
2\mu \frac{dv_x}{dx} & \mu \left( \frac{dv_x}{dy} + \frac{dv_y}{dx} \right) & \mu \left( \frac{dv_x}{dz} + \frac{dv_z}{dx} \right) \\
\mu \left( \frac{dv_x}{dy} + \frac{dv_y}{dx} \right) & 2\mu \frac{dv_y}{dy} & \mu \left( \frac{dy}{dz} + \frac{dv_z}{dy} \right) \\
\mu \left( \frac{dv_x}{dz} + \frac{dv_z}{dx} \right) & \mu \left( \frac{dy}{dz} + \frac{dv_z}{dy} \right) & 2\mu \frac{dv_z}{dz}
\end{pmatrix}_{xyz}$$
(5)

In Comsol, the software calculates the velocity field at every point on a mesh that the user chooses. To calculate the total force on a surface  $\underline{F}$  it must calculate the integral in Equation 1 from the numerical solution for the velocity  $\underline{v}(x,y,z)$  (stored in matricies for every location) and the relationships in Equations 2-5.

The kernel of the integral in equation 1 is a vector with units of stress (Pa). In Comsol, the coefficients of this stress vector are given the following names:

Total stress vector on a surface at a location with unit normal 
$$\hat{n}$$
 
$$\underline{T} \equiv \left[\hat{n} \cdot \underline{\tilde{\mathbb{I}}}\right]_{surface} = \begin{pmatrix} \text{spf.T\_stressx} \\ \text{spf.T\_stressy} \\ \text{spf.T\_stressz} \end{pmatrix}_{xyz} \tag{6}$$

A related stress vector is the analogous expression involving the tensor  $\underline{\tilde{t}}$ . In Comsol, this is given by

Viscous stress vector on a surface at a location with unit normal  $\hat{n}$ 

$$\underline{K} \equiv \left[ \hat{n} \cdot \underline{\tilde{1}} \right]_{surface} = \begin{pmatrix} \text{spf.K\_stressx} \\ \text{spf.K\_stressy} \\ \text{spf.K\_stressz} \end{pmatrix}_{xyz}$$
(7)

From Equation 1, we see that to calculate the fluid force on a surface Comsol needs to integrate the stress vector  $\underline{T}$  over the surface. We can write this as

$$\underline{F} = \iint_{S} \left[ \hat{n} \cdot \underline{\underline{\tilde{\Pi}}} \right] \Big|_{surface} dS = \iint_{S} \underline{T} \, dS \tag{8}$$

$$\underline{F} = \iint_{S} \begin{pmatrix} \text{spf.T\_stressx} \\ \text{spf.T\_stressy} \\ \text{spf.T\_stressz} \end{pmatrix}_{xyz} dS$$
 (9)

Note that this is the integration of stress=force/area over an area and thus yields a force (N).

In a 2D calculation, we consider only a slice of the flow. For a 2D rectangular geometry, for example, we may only be considering flow in the y direction as a function of the x-direction, with no variations taking place in the z-direction. For such a flow, the calculation for  $\underline{F}$  on a side wall (in a yz-plane, length L, width W) becomes

$$\underline{F} = \int_{0}^{W} \int_{0}^{L} \left[ \hat{n} \cdot \underline{\underline{\tilde{\Pi}}} \right] \Big|_{surface} dy dz \tag{10}$$

$$\frac{F}{L} = \int_{0}^{W} \int_{0}^{L} \left( \frac{\text{spf.T\_stressx}}{\text{spf.T\_stressz}} \right)_{xyz} dydz$$
(11)

Since there is no variation of velocity in the z-direction, we may carry out the z integration, obtaining

$$\underline{F} = W \int_{0}^{L} \left( \begin{array}{c} \text{spf.T\_stressx} \\ \text{spf.T\_stressy} \\ \text{spf.T\_stressz} \end{array} \right)_{xyz} dy \tag{12}$$

$$\frac{F}{W} = \int_{0}^{L} \begin{pmatrix} \text{spf.T\_stressx} \\ \text{spf.T\_stressy} \\ \text{spf.T\_stressz} \end{pmatrix}_{xyz} dy$$
 (13)

Note that Equation 13 is the integration of stress=force/area over a single direction (y) and thus yields a force/length (N/m). In Comsol 5.1 the calculation in Equation 13 is accomplished through steps related

to these choices: Derived Values-Line Integration-select the surface, select the appropriate stress vector component, spf.T\_stressx, spf.T\_stressy, or spf.T\_stressz (one at a time.)

## Reference:

Morrison, Faith A, An Introduction to Fluid Mechanics (Cambridge University Press, New York, 2013).