

Macroscopic Momentum Balance

$$\beta_{\text{laminar}} = 0.75$$

$$\beta_{\text{turbulent}} \sim 1$$

\underline{P} = *fluid* momentum

$$\frac{d\underline{P}}{dt} + \sum_{i=1}^{\text{\#streams}} \left[\frac{\rho A \cos\theta \langle v \rangle^2}{\beta} \hat{v} \right]_{A_i} = \sum_{i=1}^{\text{\#streams}} [-pA\hat{n}]_{A_i} + \underline{R} + M_{CV} \underline{g}$$

$$\begin{pmatrix} \frac{dP_x}{dt} \\ \frac{dP_y}{dt} \\ \frac{dP_z}{dt} \end{pmatrix}_{xyz} + \sum_{i=1}^{\text{\#streams}} \left[\frac{\rho A \cos\theta \langle v \rangle^2}{\beta} \begin{pmatrix} \hat{v}_x \\ \hat{v}_y \\ \hat{v}_z \end{pmatrix}_{xyz} \right]_{A_i} = \sum_{i=1}^{\text{\#streams}} \left[-pA \begin{pmatrix} \hat{n}_x \\ \hat{n}_y \\ \hat{n}_z \end{pmatrix}_{xyz} \right]_{A_i} + \begin{pmatrix} R_x \\ R_y \\ R_z \end{pmatrix}_{xyz} + M_{CV} \begin{pmatrix} g_x \\ g_y \\ g_z \end{pmatrix}_{xyz}$$

\underline{R} = net force *on fluid* due to walls

M_{CV} = mass of control volume

\hat{n} = outwardly pointing unit normal

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See inside front cover of Morrison, 2013

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