

Measurements are affected by errors

(uncertainty)

There are two general categories of errors
(uncertainties) in experimental measurements:

Systematic errors
Random errors

Paith A. Morrison, Michigan Tech U.

From Lecture 1: Quick Start, Replicate Errors:

Measurements are affected by errors

Random errors

(uncertainty)

- 1. Varies in sign and magnitude for identical conditions
- 2. May be due to the instrument or the process being measured
- 3. Must be understood and communicated with results

Sources:

Always present (need to minimize)

- Random process, instrument fluctuations
- Randomized systematic trends (e.g. operator identity, thermal drift)
- Rare events

Solutions:

Do:

- Replicate and average
- Always an option
- Improve measurement methods, practices
- Isolate from rare events

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From Lecture 1: Quick Start, Replicate Errors:

Measurements are affected by errors (uncertainty)

We have identified three sources of standard error:

- Random errors (replicate error)
- Reading errors
- Calibration errors

Averaging replicates allows us to calculate a standard error due to random error

$$e_{\scriptscriptstyle S} = \frac{{\scriptscriptstyle S}}{\sqrt{n}}$$

Standard error of replicates

 $e_s = \frac{e_R}{\sqrt{3}}$

Standard <u>reading</u> error

 $e_s = ?$

Standard calibration error

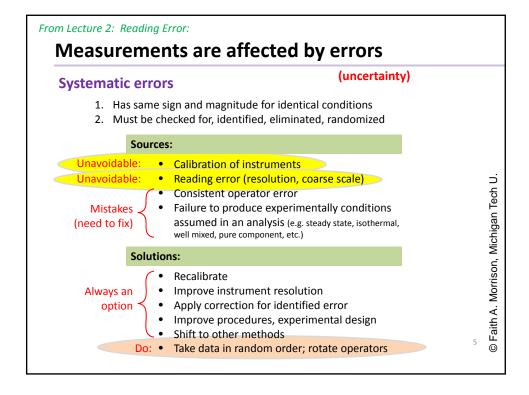
For all three types of errors, we write a **variance** of the sampling distribution.

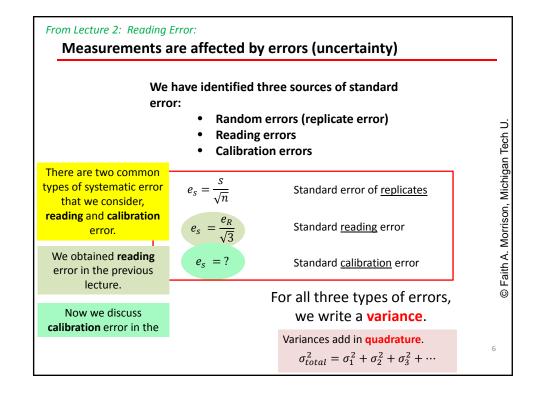
Why? Because we know how to combine variances (see literature):

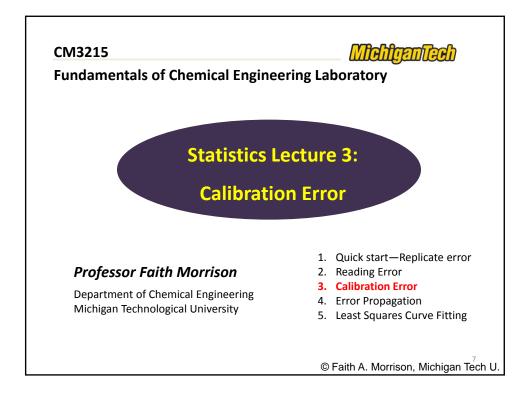
$$\sigma_{total}^2 = \sigma_1^2 + \sigma_2^2 + \sigma_3^2 + \cdots$$

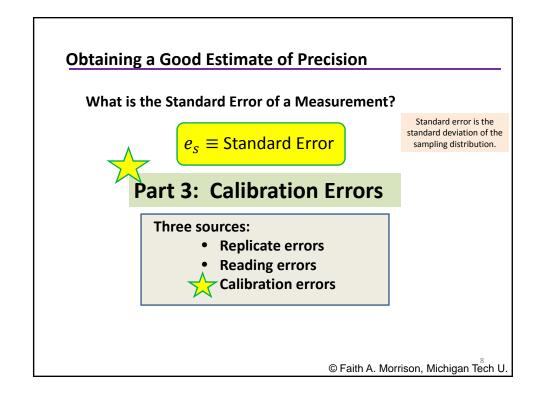
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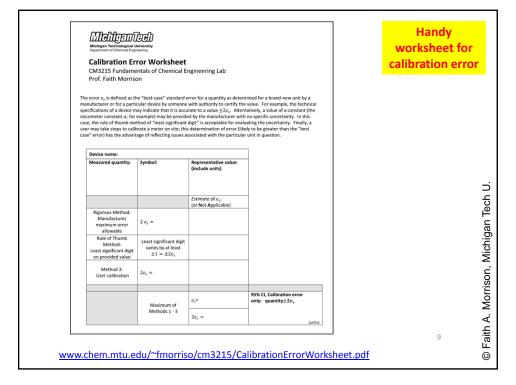
They add in quadrature.











Measurements are affected by errors

Systematic errors

- 1. Has same sign and magnitude for identical conditions
- 2. Must be checked for, identified, eliminated, randomized

Sources:

- Miscalibration of instruments
- Consistent operator error (e.g. parallax)
- Failure to produce experimentally conditions assumed in an analysis (e.g. steady state, isothermal, well mixed, pure component, etc.)

Solutions:

- Recalibrate
- Apply correction for identified error
- Improve procedures, experimental design
- Shift to other methods
- Take data in random order; rotate operators

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1

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Calibration

What is calibration?

Calibration is a step made to establish the correctness and utility of a device.

- A <u>standard</u> is used (a device or material whose correctness or properties are known.
- 2. The *unit under test* and the standard are both made to make a measurement.
- 3. The performance of the unit under test is assigned based on the comparison to the standard we say that the unit under test is *calibrated* against the standard.

12

Factory Calibration

- Many devices come to us calibrated by the manufacturers
- How do we know the accuracy of these devices?

 $T = 39.8 \pm ?$



13

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Factory Calibration

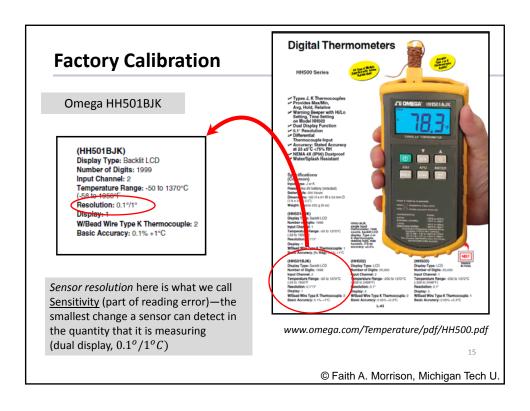
- Many devices come to us calibrated by the manufacturers
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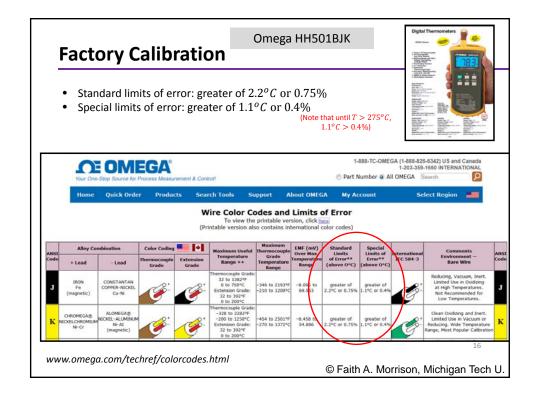
$$T = 39.8 \pm ?$$

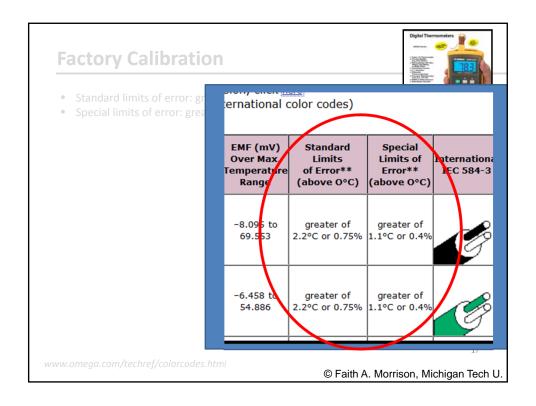


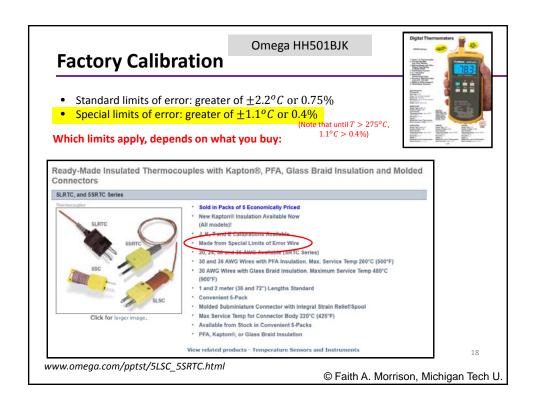
We check with the manufacturer.

14









Factory Calibration

- Many devices come to us calibrated by the manufacturers
- How do we know the accuracy of these devices?

According to the manufacturer (at best):

$$T = 39.8 \pm 1.1^{\circ}C$$

 $38.7 \le T \le 40.9^{\circ}C$

(note that $T > 275^{o}C$ the uncertainty is even higher, 0.4%)



19

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Let's check.



20

EXAMPLE 3: For the temperature indicators in the lab, what is the standard error and 95% confidence interval for the measurement? Consider replicate error, reading error, and calibration error.



Let's try.

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Replicate Error

- Test 11 meters
- Calculate standard error $e_{s}=\frac{s}{\sqrt{n}}$



Replicate Error

- 11 thermocouples, 11 temperature indicators
- Indicators in service for various amounts of time
- · Factory calibrated
- All measuring the temperature of a bath thermostated to 40.0^{o} C
- Record temperatures

Y=			mean	variance	std dev	std error		95%	6 CI
	Т	N		s ²	_S	e _s	$2e_s$	lower	upper
	°C	11	39.2	1.1	1.1	0.3	0.6	38.6	39.9
Y ₁	39.3		°C	°C	°C	°C	°C	°C	°C
Y ₂	40.0								
Y ₃	36.7								
Y ₄	39.9								
Y ₅	39.8								
Y ₆	39				S	1.1			
Y ₇	38			ec =	= —	=	- = 0	$.3^{\circ}C$	
Y ₈	39.9			05	\sqrt{n}	$\sqrt{1}$	1	.3°C	
Y ₉	39				V	V 1	_		
Y ₁₀	40.1								
Y ₁₁	40.0								

2

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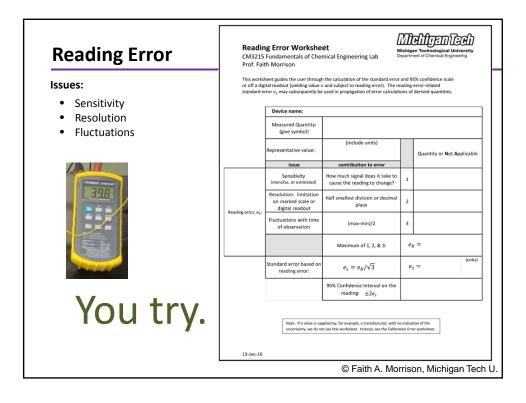
Reading Error

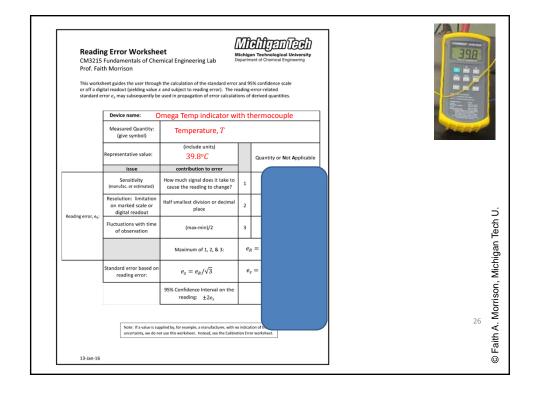
Issues:

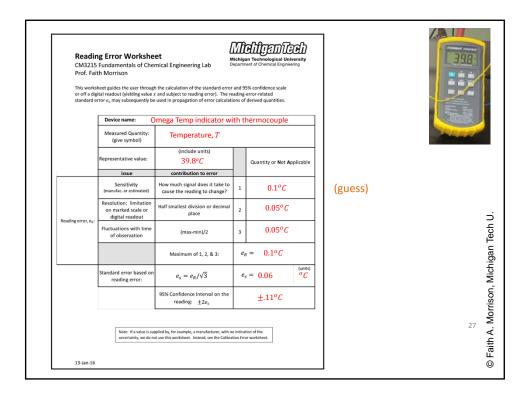
- Sensitivity
- Resolution
- Fluctuations



24







Summary of Errors

Standard Errors, e_x :

- Replicate standard error is $\frac{s}{\sqrt{n}} = 0.3^{o}C$
- Reading standard error is $\frac{e_R}{\sqrt{3}} = 0.06^o C$
- Calibration error?

28

Calibration Error

Issues:

- Manufacturer maximum error allowable
- Least significant digit on provided value
- User calibration



29

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Calibration Error

Issues:

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You try.

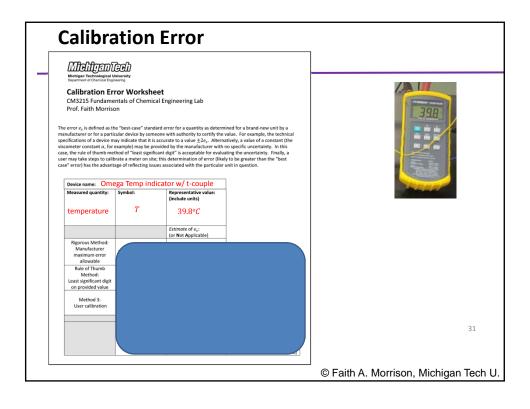
Michigan Technological University

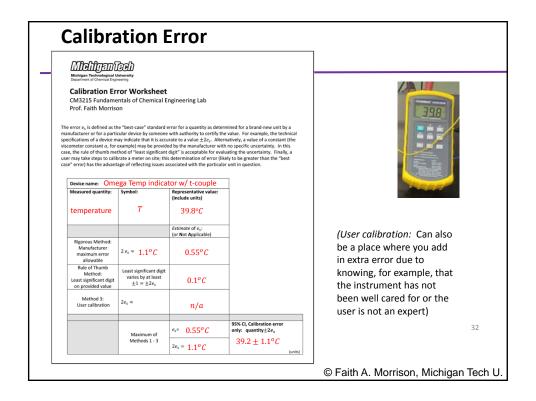
Calibration Error Worksheet

CM3215 Fundamentals of Chemical Engineering Lal

The error e, is defined as the "best-case" standard error for a quantity as determined for a brand-new unit by a mandacture or for a particular device by someone with authority to certify the value. For example, the technical sapedictiations of a device may indicate that it is accurate to a value ±2e., Alternatively, a value of a constant (the viscometer constant or, for example) may be provided by the manufacturer with no specific uncertainty, in this case, then rule of thom method of "mast application (and it is acceptable for embanding the uncertainty. Finally, acceptable to expendituding the uncertainty. Finally, acceptable to the embanding the uncertainty. Finally, acceptable to excluding the uncertainty. Finally, acceptable to excluding the uncertainty. Finally, acceptable to the embanding the uncertainty. Finally, and the second control of the control of the control of the second control of the contro

Measured quantity:	Symbol:	Representative value: (include units)	
		Estimate of e_S : (or Not Applicable)	
Rigorous Method: Manufacturer maximum error allowable	2 e _s ≈		
Rule of Thumb Method: Least significant digit on provided value	Least significant digit varies by at least $\pm 1 = \pm 2e_S$		
Method 3: User calibration	$2e_s \approx$		
	Maximum of	e _s =	95% CI, Calibra only: quantit
	Methods 1 - 3	$2e_s =$]





Summary of Errors of Temperature Indicator

Standard Errors, e_x :

- Replicate standard error is $\frac{s}{\sqrt{n}} = 0.3^{o}C$
- Reading standard error is $\frac{e_R}{\sqrt{3}} = 0.06^o C$
- Calibration error is $e_s = 0.55^{o}C$

33

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$$e_s = 0.55^{\circ}C$$

Calibration error is the largest, followed by replicate error

How do we combine?

34

Summary of Errors of Temperature Indicator

Standard Errors for temperature indicator, e_s :

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- Reading standard error is $\frac{e_R}{\sqrt{3}} = 0.06^{\circ} C$
- Calibration error is

$$e_s = 0.55^{o}C$$

For all three types of errors, we write a variance of the sampling distribution.

$$e_{s,total}^2 = (0.3)^2 + (0.06)^2 + (0.55)^2$$

 $e_{s,total} = 0.63^{\circ}C$

Why? Because we know how to combine variances (see literature):

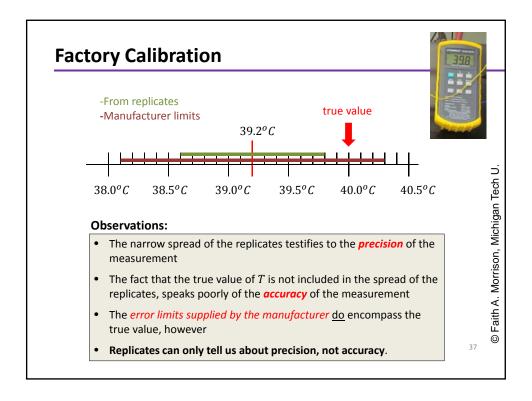
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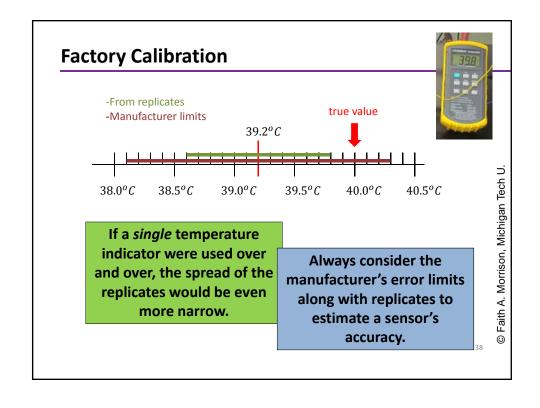
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33

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Factory Calibration Many devices come to us calibrated by the manufacturers How do we know the accuracy of these devices? According to the manufacturer: Performance in our laboratory: Faith A. Morrison, Michigan Tech U. (ignoring calibration error) $T = 39.2 \pm 1.1^{\circ}C$ $T = 39.2 \pm 0.6^{\circ}C$ $38.1 \le T \le 40.3^{\circ}C$ $38.6 \le T \le 39.8^{\circ}C$ 39.2°C $38.0^{o}C$ 38.5°C 39.0°C 39.5°C 40.0°C $40.5^{\circ}C$





Obtaining a Good Estimate of a Quantity

Summary:

Replicate error:

- Measure the quantity several times replicates
- The average value is a good estimate of the quantity we are measuring if only random errors are present
- The 95% confidence interval comes from $\pm (**)e_s$
- (**) = 2 if the number of replicates is 7 or higher
- (**) comes from the Student's t distribution if N < 7
- Report one sig fig on error (unless that digit is 1 or 2)

Reading error:

- Determine signal needed to change reading
- Determine half smallest division or decimal place
- Determine average of fluctuations
- Max of those $\sqrt{3}$ =reading error
- use $\pm 2e_s$ for 95% confidence interval

Calibration error:

- Determine manufacturer maximum error allowable
- Assume least significant digit varies by ± 1
- Calibrate in-house
- Use largest uncertainty as determined above
- Replication cannot reduce calibration error

Combining Errors:

$$e_{s,combined}^2 = e_{s,replicate}^2 + e_{s,reading}^2 + e_{s,calibration}^2$$

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