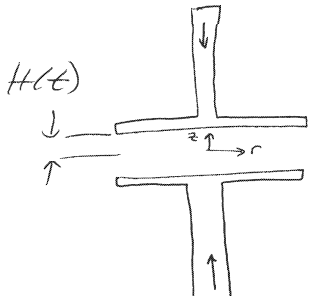


**PROBLEM: 7.44 Flow Problem: Squeeze flow** An incompressible Newtonian fluid fills the gap between two parallel disks of radius  $R$  (Figure 7.63). The disks are subjected to axial forces that cause them to squeeze together. The fluid in the gap responds by producing a combined axial and radial flow that pushes fluid out of the gap. The flow may be assumed to be symmetrical and the azimuthal direction (i.e., no  $\theta$  variation). A pressure gradient develops in the radial direction; the pressure at the center is  $p_0$  and the pressure at the rim is  $p_R$ . Calculate the steady state velocity profile and the radial pressure distribution. If the plates are moving with speed  $V$ , calculate the force needed to maintain the motion.

### SOLUTION



$H(t)$   
↓  
↑  
z ↑  
r →

Assume quasi steady state

(See also Dynamics of Polymeric Liquids, Bird et al Example 1.3-5)

$$\underline{V} = \begin{pmatrix} V_r \\ V_\theta \\ V_z \end{pmatrix}_{r\theta z} = \begin{pmatrix} V_r \\ 0 \\ V_z \end{pmatrix}_{r\theta z}$$

$\theta$  symmetry  $\Rightarrow \frac{\partial}{\partial \theta} = 0$

Continuity:  $\nabla \cdot \underline{V} = 0$   
(Table B.5)

$$0 = \frac{1}{r} \frac{\partial}{\partial r} (r V_r) + \frac{\partial V_z}{\partial z}$$

Momentum: (neglect gravity)  
(Table B.6)

r-component:

$$\rho V_r \frac{\partial V_r}{\partial r} + \rho V_z \frac{\partial V_r}{\partial z} = -\frac{\partial p}{\partial r} + \mu \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial (r V_r)}{\partial r} \right) + \mu \frac{\partial^2 V_r}{\partial z^2}$$

$\theta$ -component:

$$0 = -\frac{1}{r} \frac{\partial p}{\partial \theta}$$

z-component:

$$\rho V_r \frac{\partial V_z}{\partial r} + \rho V_z \frac{\partial V_z}{\partial z} = -\frac{\partial p}{\partial z} + \mu \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial V_z}{\partial r} \right) + \mu \frac{\partial^2 V_z}{\partial z^2}$$

$$\boxed{\frac{\partial P}{\partial \theta} = 0} \quad p = P(r, z)$$

The other two components are too complex to solve.

Assumptions:

- neglect inertia, i.e. assume slow, viscous-dominated flow

EOM:

$$0 = -\frac{\partial P}{\partial r} + \mu \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial r} (r v_r) \right) + \mu \frac{\partial^2 v_r}{\partial z^2}$$

$$0 = -\frac{\partial P}{\partial z} + \mu \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial v_z}{\partial r} \right) + \mu \frac{\partial^2 v_z}{\partial z^2}$$

$v_r$  is substantial; it is a function of  $r, z$

$v_z$  is nontrivial; it is a function of  $z$ ,  
but perhaps a weak function of  $r$ .

Assume:  $U_z = U_z(z)$

$z$ -component EOM:

$$\frac{\partial P}{\partial z} = \mu \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial U_z}{\partial r} \right) + \mu \frac{\partial^2 U_z}{\partial z^2}$$

only a function of  $z$ 
↓
0

$$\Rightarrow \frac{\partial^2 U_z}{\partial z^2} = \frac{1}{\mu} \frac{\partial P}{\partial z} = \text{function of } z \text{ only}$$

$$\frac{dU_z}{dz} = \phi(z)$$

Continuity:  $0 = \frac{1}{r} \frac{\partial}{\partial r} (r U_r) + \frac{\partial U_z}{\partial z}$

$$\frac{\partial}{\partial r} (r U_r) = -\phi r$$

$$r U_r = -\phi \frac{r^2}{2} + f(z)$$

$$U_r = -\frac{\phi(z)}{2} r + \frac{f(z)}{r}$$

Back to EOM: ( $r$ -component)

BC: at  $r=0$   $U_r = \text{finite}$   
 $\Rightarrow f(z) = 0$

$$\frac{\partial P}{\partial r} = \mu \frac{\partial}{\partial r} \left( \frac{1}{\kappa} \frac{\partial}{\partial r} (r \sqrt{r}) \right) + \mu \frac{\partial^2 V_r}{\partial z^2}$$

$\circ$                        $-\phi(z)\kappa$

$$= \mu \frac{\partial^2}{\partial z^2} \left( -\phi(z) \frac{r}{2} \right)$$

$$\frac{\partial P}{\partial r} = -\frac{r\mu}{2} \frac{d^2\phi}{dz^2}$$

$$P(r, z) = -\frac{\mu}{2} \frac{d^2\phi}{dz^2} \frac{r^2}{2} + \xi(z)$$

We previously saw that  $\frac{\partial P}{\partial z}$  is only a function of  $z$ ;  $\therefore$

$$\frac{\partial P}{\partial z} = -\frac{\mu r^2}{4} \frac{d^3\phi}{dz^3} + \frac{d\xi}{dz}$$

This is only a function of  $z$  if

$$\frac{d^3\phi}{dz^3} = 0$$

$$\frac{d^2\phi}{dz^2} = C_1$$

$$\frac{d\phi}{dz} = C_1 z + C_2 = \frac{\partial V_r}{\partial z}$$

NOTE :

$$\phi = C_1 \frac{z^2}{2} + C_2 z + C_3$$

Recall  $V_r = -\frac{\phi}{z} r$

$$V_r = -\frac{r}{z} \left( C_1 \frac{z^2}{2} + C_2 z + C_3 \right)$$

Boundary conditions:

$$z=0 \quad \frac{\partial V_r}{\partial z} = 0$$

(symmetric)

$$\frac{\partial V_r}{\partial z} = -\frac{r}{z} \left( C_1 z + C_2 \right) = 0$$

$$\Rightarrow C_2 = 0$$

$$z = \pm h \quad V_r = 0$$

(no slip)

$$0 = -\frac{r}{z} \left( c_1 \frac{h^2}{z} + c_3 \right)$$

$$c_3 = -\frac{c_1 h^2}{z}$$

$$U_r = -\frac{r}{4} c_1 (z^2 - h^2)$$

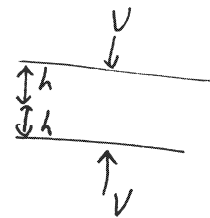
Back to  $U_z$ :

$$\frac{dV_z}{dz} = \phi(z) = c_1 \frac{z^2}{z} - \frac{c_1 h^2}{z}$$

$$V_z = \frac{c_1}{z} \left( \frac{z^3}{3} - h^2 z \right) + c_4$$

Boundary Conditions:

$$z = \pm h \quad V_z = \mp V$$



$$-h \quad V = \frac{c_1}{z} \left( -\frac{h^3}{3} + h^3 \right) + c_4$$

$$h \quad -V = \frac{c_1}{z} \left( \frac{h^3}{3} - h^3 \right) + c_4$$

ADP

$$0 = 2c_4 \Rightarrow \boxed{c_4 = 0}$$

SUBTRACT

$$2V = \frac{c_1}{2} \left( -\frac{2}{3}h^3 + 2h^3 \right)$$

$$2V = \frac{c_1}{2} \cancel{\frac{2}{3}} h^3$$

$$\boxed{c_1 = \frac{3V}{h^3}}$$

$$V_z = \frac{3V}{h^3} \left( \frac{z^3}{3} - h^2 z \right)$$

$$\boxed{\frac{V_z}{V} = \frac{3}{2} \left( \frac{z^3}{h^3} \frac{1}{3} - \frac{z}{h} \right)}$$

$$\begin{aligned} V_r &= -\frac{r}{4} c_1 (z^2 - h^2) \\ &= -\frac{r}{4} \frac{3V}{h^3} (z^2 - h^2) \end{aligned}$$

$$\boxed{\frac{V_r}{V} = -\frac{3}{4} \frac{r}{h} \left( \frac{z^2}{h^2} - 1 \right)}$$

For the pressure:

$$P = -\frac{\mu}{2} \frac{d^2\phi}{dz^2} \frac{r^2}{2} + \xi(z)$$

from z-component  
EOM

$$\frac{\partial P}{\partial z} = \frac{d\xi}{dz} = \mu \frac{\partial^2 V_z}{\partial z^2}$$

$$\frac{\partial V_z}{\partial z} = \frac{3}{2} V \left( \frac{1}{3h^3} 3z^2 - \frac{1}{h} \right)$$

$$\frac{\partial^2 V_z}{\partial z^2} = \frac{3}{2} V \left( \frac{1}{h^3} 2z \right)$$

$$= 3 \frac{V z}{h^3}$$

$$\frac{d\xi}{dz} = \mu \frac{3V}{h^3} z$$

$$\xi = \frac{3\mu V}{h^3} \frac{z^2}{2} + C_5$$

$$\frac{d\phi}{dz} = \frac{2C_1}{z}$$

$$\frac{d^2\phi}{dz^2} = C_1 = \frac{3V}{h^3}$$



$$P = -\frac{\mu}{2} \frac{r^2}{z} \frac{3V}{h^3} + \frac{3\mu V}{2h^3} z^2 + C_5$$

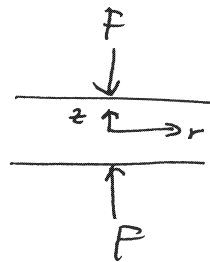
$$P = \frac{3\mu V}{h^3} \left( -\frac{r^2}{4} + \frac{1}{2} z^2 \right) + C_5$$

B.C.  $r=R$   $z=0$   $P=P_R$

$$\Rightarrow \frac{3\mu V}{h^3} \left( -\frac{R^2}{4} \right) + C_5 = P_R$$

$$P - P_R = \frac{3\mu V}{h^3} \left( \frac{R^2 - r^2}{4} + \frac{z^2}{2} \right)$$

Force to maintain the motion:



$$F = \iint_S (\hat{n} \cdot \underline{\underline{\pi}})_{\text{surface}} dS$$

Top surface:  $z = h$   
 $\hat{n} = -\hat{e}_z$   
 $\underline{\underline{\Pi}} = -p \underline{\underline{I}} + \underline{\underline{\sigma}}$   
 $= -p \underline{\underline{I}} + (\nabla \underline{v} + (\nabla \underline{v})^T) \mu$   
 (Table B.8)

$$\hat{n} \cdot \underline{\underline{\Pi}} = (0 \ 0 \ -1)_{r\theta z} \begin{pmatrix} 2 \frac{\partial v_r}{\partial r} - p & 0 & \frac{\partial v_r}{\partial z} + \frac{\partial v_z}{\partial r} \\ 0 & 2 \frac{v_r}{r} - p & 0 \\ \frac{\partial v_r}{\partial z} + \frac{\partial v_z}{\partial r} & 0 & 2 \frac{\partial v_z}{\partial z} - p \end{pmatrix}_{r\theta z}$$

$$\hat{n} \cdot \underline{\underline{\Pi}} = \begin{pmatrix} -\left( \frac{\partial v_r}{\partial z} + \frac{\partial v_z}{\partial r} \right) \\ 0 \\ -2 \frac{\partial v_z}{\partial z} + p \end{pmatrix}_{r\theta z}$$

← radial component  
 $\hat{e}_r = \cos\theta \hat{e}_x + \sin\theta \hat{e}_y$   
 (integrates to  $340$ )

←  $z$ -direction force

$$F_z = \int_0^{2\pi} \int_0^R \left( P - 2 \frac{\partial V_z}{\partial z} \right) \Big|_{z=h} r dr d\theta$$

$$\frac{\partial V_z}{\partial z} = \frac{3}{2} V \left( \frac{z^2}{h^3} - \frac{1}{h} \right)$$

$$\frac{\partial V_z}{\partial z} \Big|_{z=h} = \left( \frac{1}{h} - \frac{1}{h} \right) \frac{3V}{2} = 0$$

$$F_z = 2\pi \int_0^R r P_R + \frac{3\mu V}{4h^3} (R^2 - r^2)r + \frac{3}{2} \frac{\mu V}{h^3} h^2 r dr$$

$$\frac{F_z}{2\pi} = \left. \frac{P}{R} \frac{r^2}{2} \right|_0^R + \frac{3\mu V}{4h^3} \left( \frac{R^2 r^2}{2} - \frac{r^4}{4} \right) \Big|_0^R + \frac{3}{2} \frac{\mu V}{h} \frac{r^2}{2} \Big|_0^R$$

$$F_z = P_R \frac{R^2}{2} \cdot 2\pi + \frac{3}{2} \frac{\mu V \cdot 2\pi}{h^3} \left( \frac{R^4}{2} - \frac{R^4}{4} \right) + \frac{3}{2} \frac{\mu V R^2}{h} \cdot 2\pi$$

$$F_z = P_R \pi R^2 + \frac{3}{8} \frac{\mu V \pi R^4}{h^3} + \frac{3\mu V R^2 \pi}{2h}$$

Check soln:

$$\frac{\partial P}{\partial r} = \frac{3\mu V}{h^3} \frac{1}{4z} (-1) (2r)$$

$$\frac{\partial V_r}{\partial z} = -\frac{3}{4z} V \frac{r}{h} \frac{1}{h^2} 2z$$

$$\frac{\partial^2 V_r}{\partial z^2} = -\frac{3}{2} \frac{Vr}{h^3}$$

$$rV_r = -\frac{3V}{4h} r^2 \left( \frac{z^2}{h^2} - 1 \right)$$

$$\frac{1}{r} \frac{\partial}{\partial r} (rV_r) = -\frac{3V}{4h} \left( \frac{z^2}{h^2} - 1 \right) 2r \frac{1}{r}$$

$$\frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial r} (rV_r) \right) = 0$$

r-component EDM:

$$0 = -\frac{\partial P}{\partial r} + \mu \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial r} (rV_r) \right) + \mu \frac{\partial^2 V_r}{\partial z^2}$$

$$0 = +\frac{3\mu V}{2h^3} r + \mu \left( -\frac{3}{2} V \frac{r}{h^3} \right) \checkmark$$

$$\frac{\partial P}{\partial z} = \frac{3\mu V}{h^3} z$$

$$\frac{dU_z}{dz} = \frac{3}{2} \left( \frac{1}{h^3} z^2 - \frac{1}{h} \right) V$$

$$\frac{\partial^2 U_z}{\partial z^2} = \frac{3V}{2} \frac{1}{h^3} z = \frac{3zV}{h^3}$$

$$\frac{\partial U_z}{\partial r} = 0$$

z-component EOM:

$$0 = -\frac{\partial P}{\partial z} + \mu \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial U_z}{\partial r} \right) + \mu \frac{\partial^2 U_z}{\partial z^2}$$

$$0 = -\frac{3\mu V}{h^3} z + \mu \frac{3zV}{h^3} \checkmark$$

Continuity:  $\frac{1}{r} \frac{\partial}{\partial r} (rv_r) + \frac{\partial U_z}{\partial z} = 0$

$$-\frac{3}{2} \frac{V}{h} \left( \frac{z^2}{h^2} - 1 \right) + \frac{3}{2} V \left( \frac{z^2}{h^3} - \frac{1}{h} \right) = 0 \checkmark$$