

## CS4811 Neural Network Learning Algorithms

From: Stuart Russell and Peter Norvig

*Artificial Intelligence a Modern Approach*

Prentice Hall Series in Artificial Intelligence, 2003.

The following is a gradient descent learning algorithm for perceptrons, assuming a differentiable activation function  $g$ . For threshold perceptrons, the factor  $g'(in)$  is omitted from the weight update. NEURAL-NET-HYPOTHESIS returns a hypothesis that computes the network output for any given example.

**function** PERCEPTRON-LEARNING(*examples, network*)  
**returns** a perceptron hypothesis

**inputs:**

*examples*, a set of examples, each with input  $\mathbf{x} = x_1 \dots, x_n$  and output  $y$

*network*, a perceptron with weights  $W_j, j = 0, \dots, n$  and activation function  $g$

**repeat**

**for each**  $e$  **in** *examples* **do**

$in \leftarrow \sum_{j=0}^n W_j x_j[e]$

$err \leftarrow y[e] - g(in)$

$W_j \leftarrow W_j + c \times Err \times g'(in) \times x_j[e]$

**until** some stopping criterion is satisfied

**return** NEURAL-NET-HYPOTHESIS(*Network*)

The following is the back propagation algorithm for learning in multilayer networks.

**function** BACK-PROP-LEARNING(*examples, network*)  
**returns** a neural network

**inputs:**

*examples*, a set of examples, each with input vector  $\mathbf{x}$  and output vector  $\mathbf{y}$ .

*network*, a multilayer network with  $L$  layers, weights  $W_{j,i}$ , activation function  $g$

**repeat**

**for each**  $e$  **in** *examples* **do**

**for each** node  $j$  in the input layer **do**  $a_j \leftarrow x_j[e]$

**for**  $l = 2$  to  $L$  **do**

$in_i \leftarrow \sum_j W_{j,i} a_j$

$a_i \leftarrow g(in_i)$

**for each** node  $i$  in the output layer **do**

$\Delta_i \leftarrow g'(in_i) \times (y_i[e] - a_i)$

**for**  $l = L - 1$  to 1 **do**

**for each** node  $j$  in layer  $l$  **do**

$\Delta_j \leftarrow g'(in_j) \sum_i W_{j,i} \Delta_i$

**for each** node  $i$  in layer  $l + 1$  **do**

$W_{j,i} \leftarrow W_{j,i} + c \times a_j \times \Delta_i$

**until** some stopping criterion is satisfied

**return** NEURAL-NET-HYPOTHESIS(*network*)

For  $g$ , use the hyperbolic tangent:  $\tanh(x)$ . The derivative of  $\tanh$  is  $\text{sech}^2$ .

$$\tanh(x) = \frac{\sinh(x)}{\cosh(x)}$$

$$\text{sech}(x) = \frac{1}{\cosh(x)}$$