

## Reminder

- We have class on Friday, 9/11.
- K-Day starts at noon.

CS5811  
Sep. 9, 2020  
Wednesday

①

## Previous classes

- We defined a unified algorithm for uninformed search strategies: BFS, DFS, DLS, IDS
- We evaluated them along four dimensions:
  - completeness
  - time complexity
  - space complexity
  - optimality
- We used the following parameters:
  - $b$ : branching factor (finite)
  - $d$ : depth of the goal
  - $m$ : maximum depth of the tree
  - $l$ : depth limit
- Time complexity is exponential for all, these are hard problems
- IDS brings together the good parts of BFS and DFS by adding the cost of repetitions.  
The asymptotic cost remains the same.  
IDS is • complete and • optimal and has  
• linear space complexity.

## Main takeaway:

Always know the properties of an algorithm very well and be able to clearly identify the changes to the properties when variations are made to the algorithm.

## This lecture

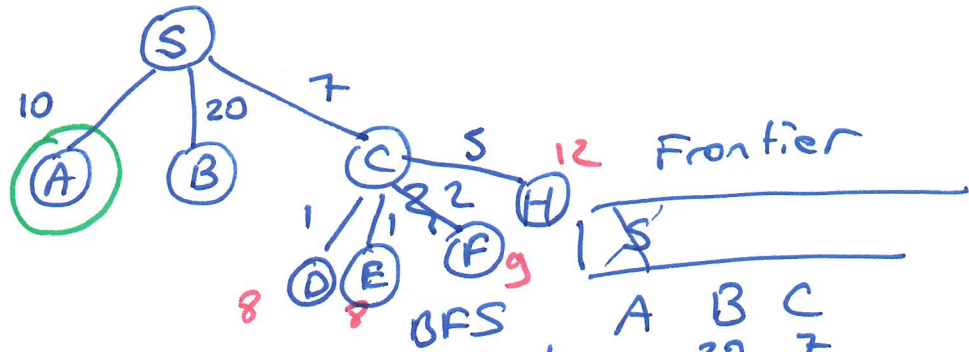
- Uniform cost search
- Tree search and graph search algorithms
- Heuristic "informed" search

# Uniform Cost Search

action costs are variable

(special case of BFS)

↳ cost of actions are 1



(order does not matter all are cost 1)

## UCS

sorted to facilitate picking up the lowest cost one first.

<del>A</del>	B
7	10 20

D	E	F	A	H	B
8	8	9	10	12	20

Keep bookkeeping information in a node ○  
In a node : state, depth, (cost),

path  
"pointer" to the parent

A: S A      F: S C F

"It will work just like BFS"

"If all the costs are 1 it is exactly BFS"

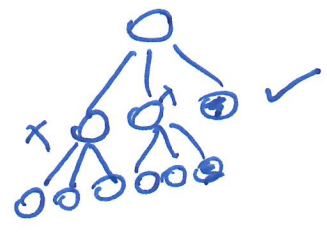
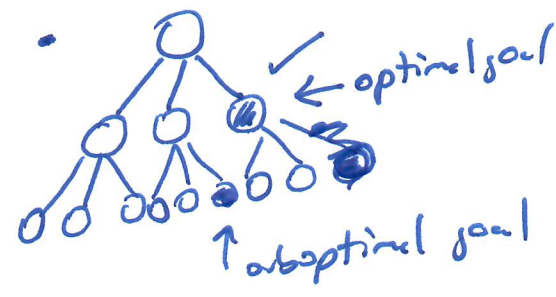
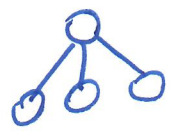
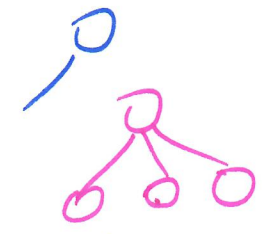
It should be optimal  
completeness, time complexity, space complexity, optimality  
still exponential, similar to BFS ✓

when to do the goal test?

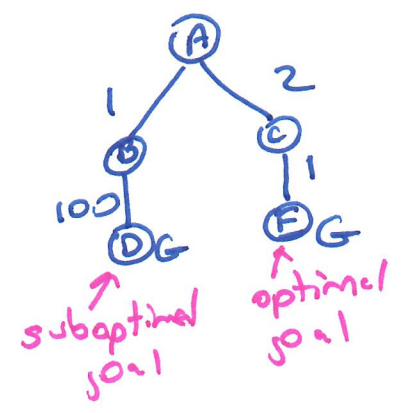
when a node is generated

when a node is expanded

if we do the goal test when a node is generated do we find the optimal goal?  
yes



what about uniform cost search?

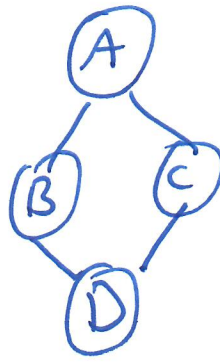
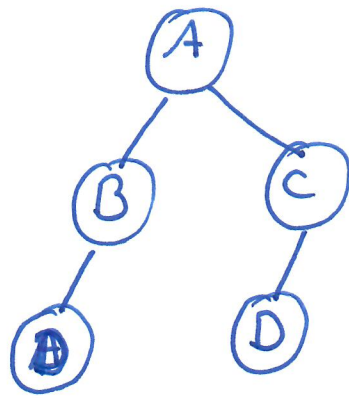


A  
0  
B  
1

C  
2  
C  
2

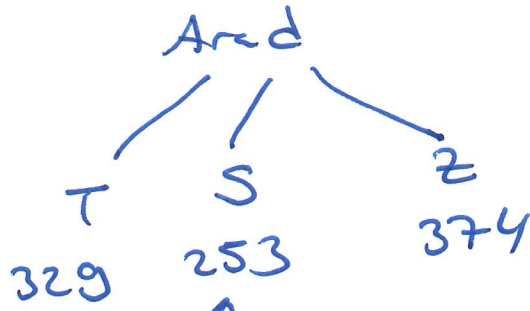
D  
100  
checked when expanded will be returned as the goal.

F  
3  
D  
100



### Heuristic search

informed search  
 → guess (hunch) of where the solution lies



↑  
 "best" option

? heuristic

best-first search  
 greedy → A\*