

LESSON 24 INTRO. TO DIRECT STIFFNESS METHOD

READING: TEXT Ch. 16.1 - 16.2

- INTRODUCE DIRECT STIFFNESS METHOD
- QUICK COMPARISON TO FLEXIBILITY METHOD
- SPRING ANALOGY

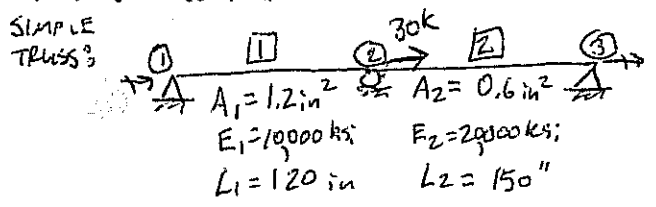
A.) INTRODUCTION TO DIRECT STIFFNESS METHOD:
STEPS:

- FIND EQUILIBRIUM AT JOINTS IN TERMS OF UNKNOWN JOINT DEFLECTIONS
- SOLVE FOR DEFLECTIONS
- SOLVE FOR MEMBER FORCES

- ADVANTAGES:
 - ALGORITHMIC: CAN AUTOMATE
 - BASIS FOR COMPUTER-BASED ANALYSIS SOFTWARE PACKAGES
 - CAN EASILY HANDLE ANY GEOMETRY
 - MANY DEGREE OF DETERMINACY OK

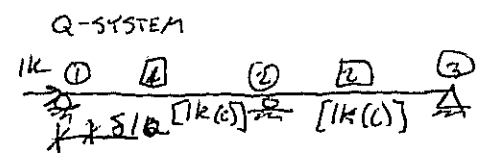
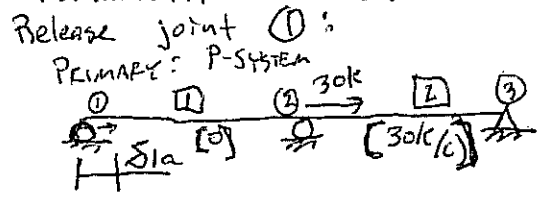
- DISADVANTAGES: MANY COMPUTATIONS / TEDIUS

B.) QUICK COMPARISON TO FLEXIBILITY METHOD:

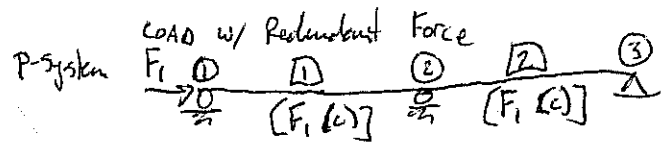


2 REACTIONS
- 1 EQN. OF EQUILIBRIUM
1 DEGREE INDETERMINATE

BY FLEXIBILITY METHOD:



$$\delta_{1a} = \frac{F_2 F_{Q2} L_2}{A_2 E_2} = \frac{-30(-1)(150)}{(0.6)(20,000)} = 3/8 \text{ in}$$



Q-SYSTEM (see above)

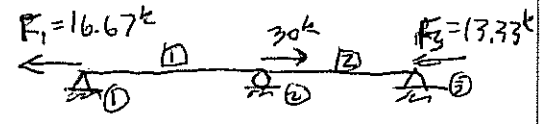
$$\delta_{1b} = \frac{F_1 F_{Q1} L_1}{A_1 E_1} + \frac{F_2 F_{Q2} L_2}{A_2 E_2} = \frac{(F_1)(-1)(120)}{1.2(10,000)} + \frac{(F_1)(-1)(150)}{0.6(20,000)} = 0.0225 F_1 \text{ (in)}$$

SIMPLE TRUSS EXAMPLE (FLEXIBILITY METHOD) CONT...

EQN. OF COMPATIBILITY:

$$0 = 3/8 + (0.0225) F_1$$

$$F_1 = -16.67 \text{ k} \leftarrow$$

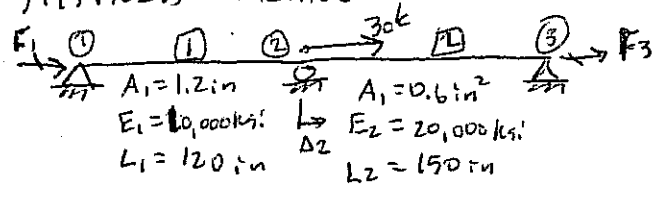


Now:

$$\sum F_x = 0 \Rightarrow F_1 + F_3 + 30 = 0$$

$$F_3 = -13.33 \text{ k} \leftarrow$$

BY STIFFNESS METHOD



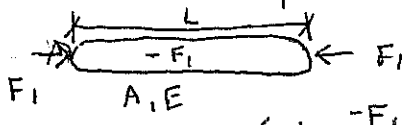
IMAGINE WHAT HAPPENS WHEN JOINT 2 DEFORMS

$$\Delta L_1 = \Delta L_2 = \Delta L_2 \quad (\text{COMPATIBILITY})$$

FOR 1 BAR, WE CAN EXPRESS A RELATIONSHIP

BETWEEN ΔL & END FORCE

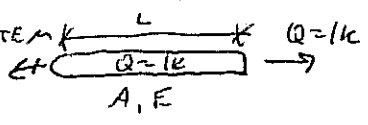
P-SYSTEM



$$\Delta L = \frac{-F_1 (1) L}{AE}$$

$$\text{OR: } F_1 = \left(\frac{AE}{L} \right) \Delta L$$

Q-SYSTEM



FOR OUR EXAMPLE THEN, $F_1 = \Delta L_1 \frac{A_1 E_1}{L_1}$ & $F_2 = \Delta L_2 \frac{A_2 E_2}{L_2}$

SINCE $\Delta L_1 = \Delta L_2 = \Delta L_2$

$$F_1 = \frac{-1.2 (10,000)}{120} \Delta L_2 = -100 \Delta L_2$$

$$F_2 = \frac{-0.6 (20,000)}{150} \Delta L_2 = -80 \Delta L_2$$

USING STATIC EQUILIBRIUM:

$$\sum F_x = 0 \Rightarrow 30 + F_1 + F_3 = 0$$

$$30 - 100 \Delta L_2 - 80 \Delta L_2 = 0$$

$$\Delta L_2 = 1/6 \text{ in}$$

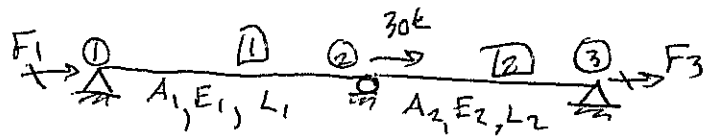
Plug in ΔL_2 :

$$F_1 = 100 \Delta L_2 = -100 (1/6) = -16.67 \text{ k}$$

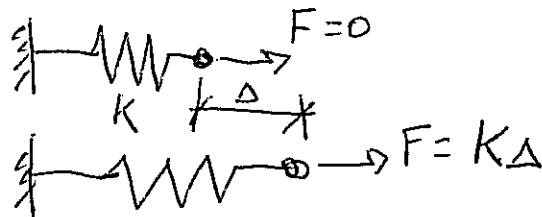
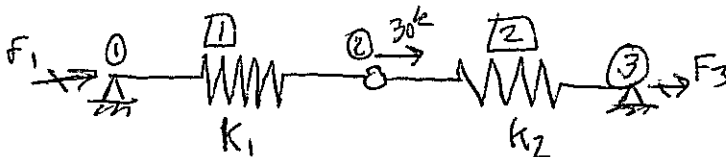
$$F_2 = 80 \Delta L_2 = -80 (1/6) = -13.33 \text{ k}$$

C.) SPRING ANALOGY

TRUSS



SPRING SYSTEM



FOR TRUSS ELEMENTS, $K = \frac{AE}{L}$

(FROM EXAMPLE, $F_1 = \frac{A_1 E_1}{L_1} \Delta L_1$ & $F_2 = \frac{A_2 E_2}{L_2} \Delta L_2$)

- TRUSS BARS ARE LIKE SPRINGS! (Related to axial deflection).
- WE WILL ALSO SEE, BEAMS WILL HAVE THEIR OWN SPRING CONSTANTS RELATED TO DISP. & ROTATION.